

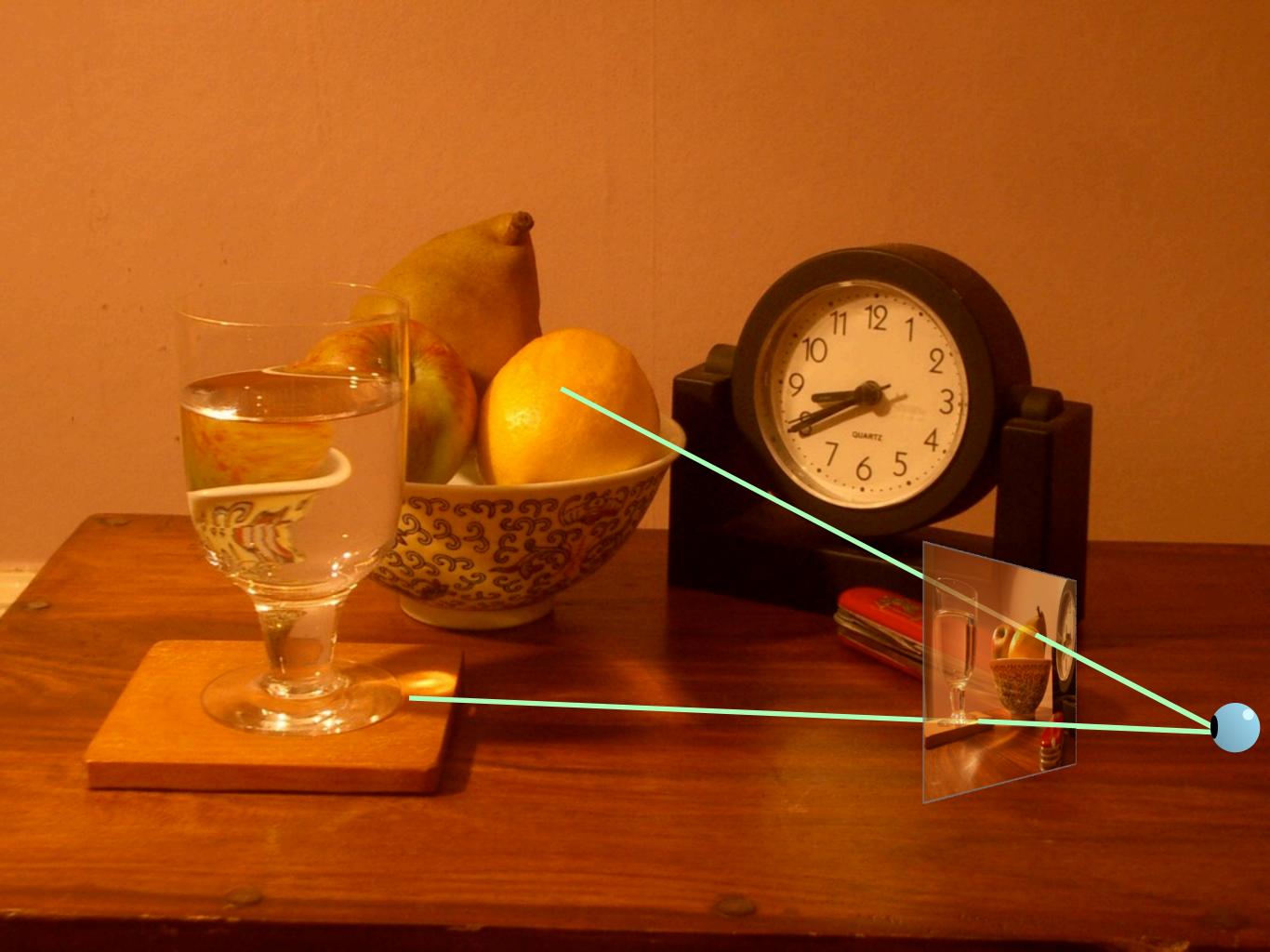


Create an image plane and viewpoint.
For each pixel trace a 'ray' from the eye through a corresponding point in the image plane.

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# The hit point?

# The Hit Point

- For each ray we have to find what we can see in that direction.
- So we need to know which object the ray hits first.
- Objects are represented mathematically.
- We must find where a ray intersects an object's surface.

# Intersection of line and sphere

- Why sphere?
- How do we represent a line?
- How do we represent a sphere?
- How do we find the intersection point?

# Sphere is the simplest

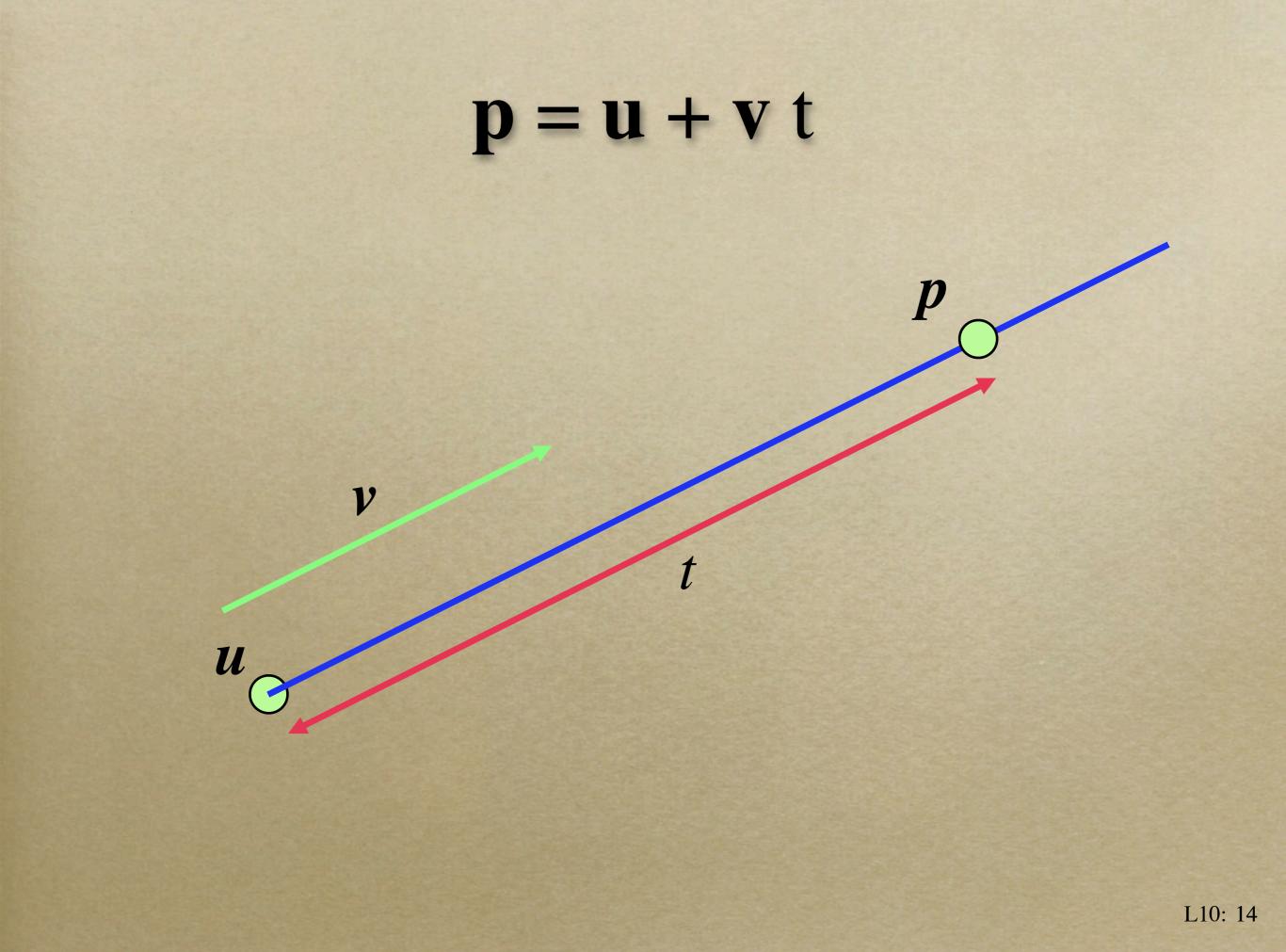
Given a point p = (x, y, z)Its distance from the origin is:  $p^2 = p \cdot p = (x^2 + y^2 + z^2)$  $p^2 = p \cdot p = (x^2 + y^2 + z^2) = 1.0$ describes a sphere of radius 1.0 centred at the origin.

### A line ...

We can describe a line using a starting point, **u** and direction **v**:

p = u + v t

If v is a unit vector, we can think of t as the distance along the line.



# If **p** is on the line and the sphere

 $p^{2} = p \cdot p = (u + v t)^{2} = 1.0$  $(u + v t) \cdot (u + v t) = v^{2} t^{2} + 2 u \cdot v t + u^{2}$ so:

 $v^2 t^2 + 2 u \cdot v t + u^2 = 1.0$ 

This is just an ordinary quadratic equation in t.

#### Quadratic Solution

 $v^{2} t^{2} + 2 u \cdot v t + u^{2} = 1.0$   $A = v^{2}$   $B = 2 u \cdot v$   $C = u^{2} - 1.0$  $t = (-B \pm \sqrt{(B^{2} - 4AC)}) / (2A)$ 

#### Avoid Rounding errors

if B > 0,  $t_1 = (-B - \sqrt{(B^2 - 4AC)}) / (2A)$ else  $t_1 = (-B + \sqrt{(B^2 - 4AC)}) / (2A)$  $t_2 = C/(A t_1)$ 

# Explaining the 'odd' t<sub>2</sub> equation

 $(t - t_1)(t - t_2) = t^2 - (t_1 + t_2)t + t_1 t_2$ In  $At^2 + Bt + C = 0$  $t^2 + (B/A)t + C/A = 0$ and:  $t_1 t_2 = C/A$ 

# Sphere not at origin?

Z

X

U

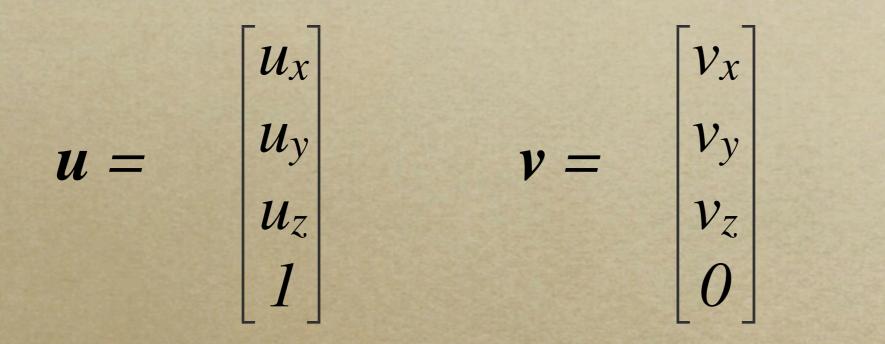
#### Move the ray not the sphere

Sphere at  $c = (c_x, c_y, c_z)$ Use (u - c) + v tSo new  $u' = u - c = (u_x, u_y, u_z) - (c_x, c_y, c_z)$ 

### General transformed sphere

Suppose the sphere has been magnified, stretched, rotated and shifted. That's just one transformation matrix, M $u' = M^{-1} u$  $v' = M^{-1} v$ 

#### Here is real cunning...



#### M<sup>-1</sup> u includes shift but M<sup>-1</sup> v doesn't



# Ray tracing triangles