

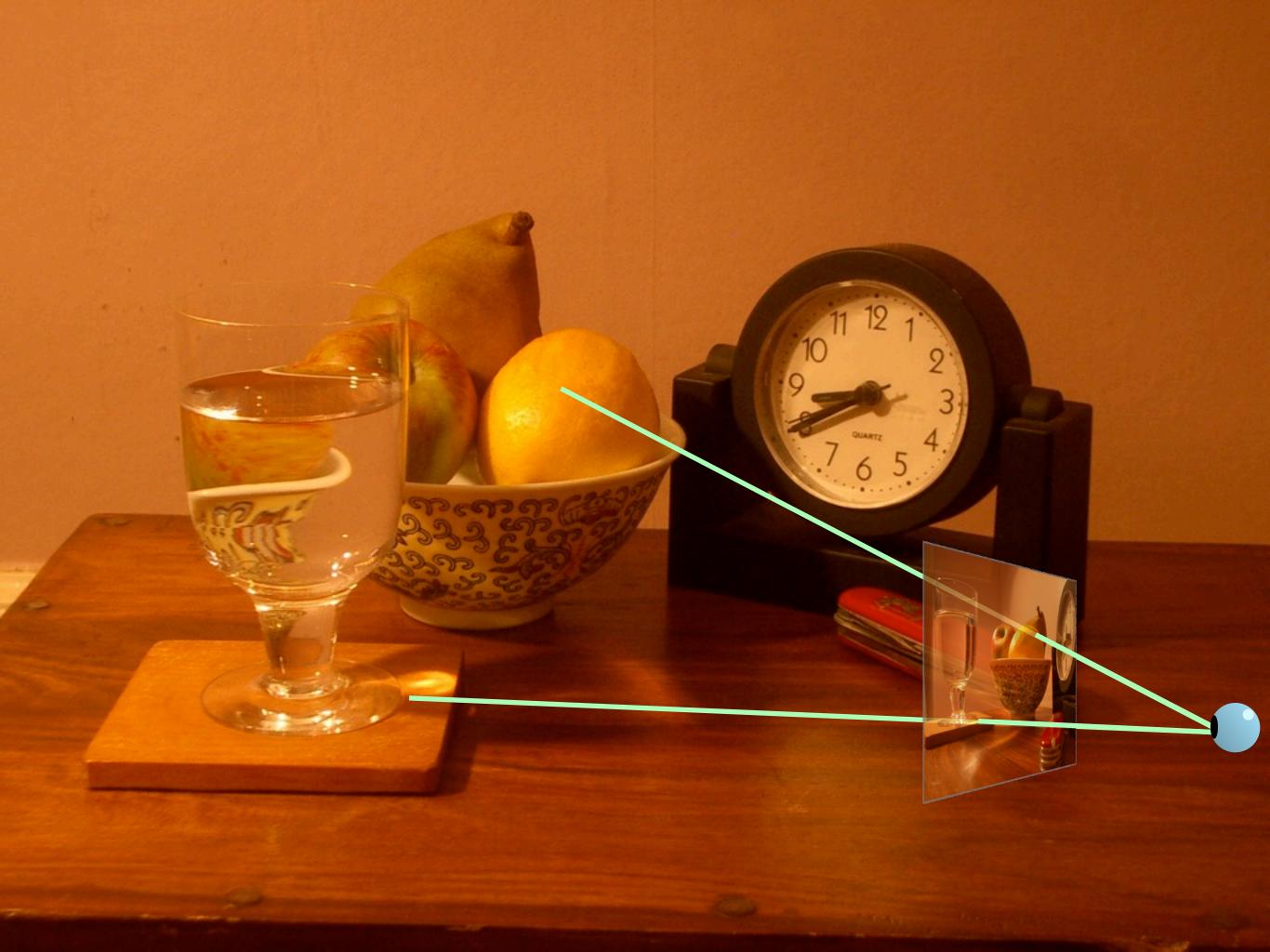


Create an image plane and viewpoint.
For each pixel trace a 'ray' from the eye through a corresponding point in the image plane.

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The hit point?

The Hit Point

- For each ray we have to find what we can see in that direction.
- So we need to know which object the ray hits first.
- Objects are represented mathematically.
- We must find where a ray intersects an object's surface.

Intersection of line and sphere

- Why sphere?
- How do we represent a line?
- How do we represent a sphere?
- How do we find the intersection point?

Sphere is the simplest

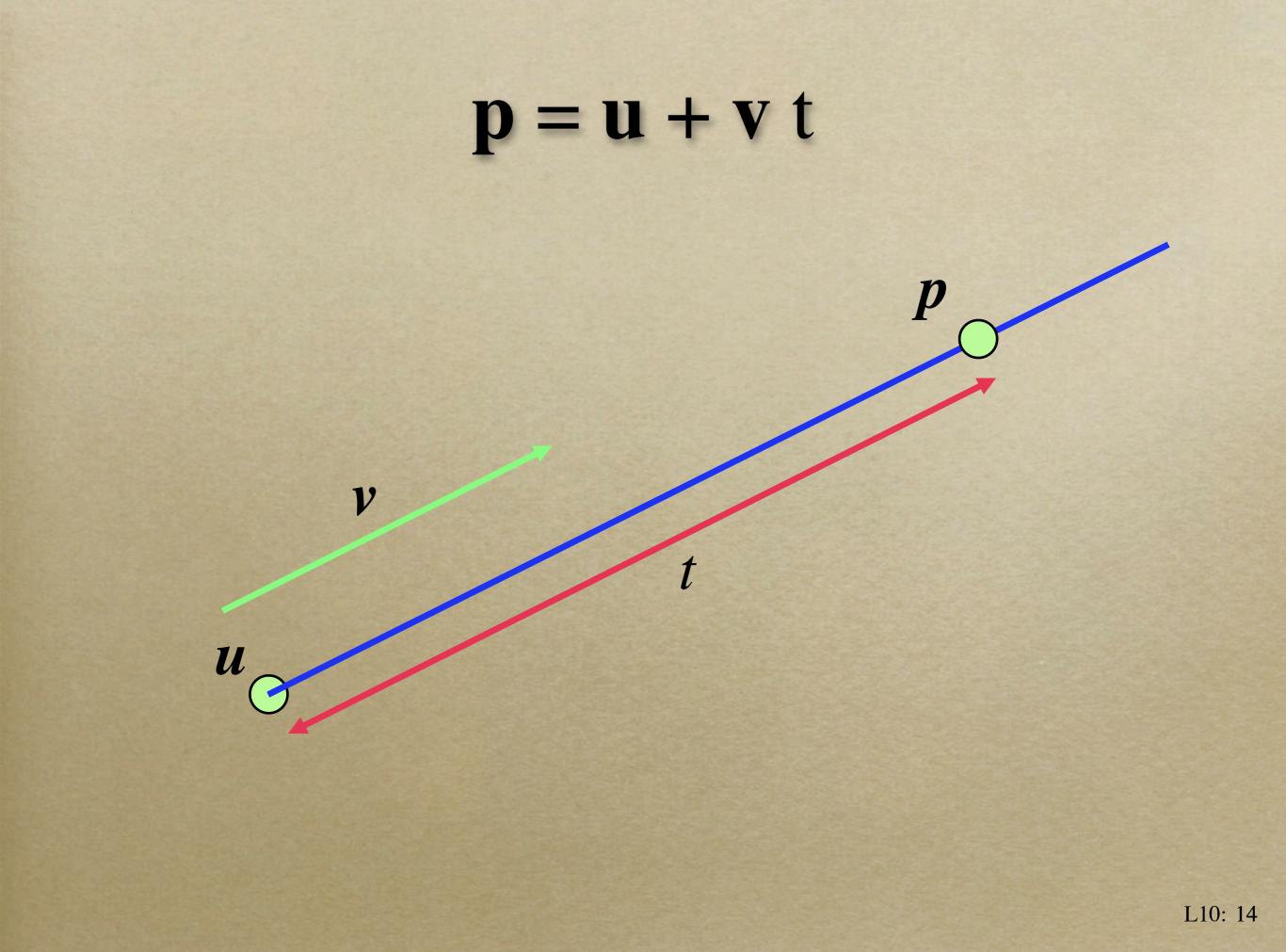
Given a point p = (x, y, z)Its distance from the origin is: $p^2 = p \cdot p = (x^2 + y^2 + z^2)$ $p^2 = p \cdot p = (x^2 + y^2 + z^2) = 1.0$ describes a sphere of radius 1.0 centred at the origin.

A line ...

We can describe a line using a starting point, **u** and direction **v**:

p = u + v t

If v is a unit vector, we can think of t as the distance along the line.



If **p** is on the line and the sphere?

 $p^{2} = p \cdot p = (u + v t)^{2} = 1.0$ (u + v t) \cdot (u + v t) = v^{2} t^{2} + 2 u \cdot v t + u^{2} So:

 $v^2 t^2 + 2 u \cdot v t + u^2 = 1.0$

This is just an ordinary quadratic equation in t.

Quadratic Solution

 $v^{2} t^{2} + 2 u \cdot v t + u^{2} = 1.0$ $A = v^{2}$ $B = 2 u \cdot v$ $C = u^{2} - 1.0$ $t = (-B \pm \sqrt{(B^{2} - 4AC)}) / (2A)$

Avoid Rounding errors

if B > 0, $t_1 = (-B - \sqrt{(B^2 - 4AC)}) / (2A)$ else $t_1 = (-B + \sqrt{(B^2 - 4AC)}) / (2A)$ $t_2 = C/(A t_1)$

Explaining the 'odd' t₂ equation

 $(t - t_1)(t - t_2) = t^2 - (t_1 + t_2)t + t_1 t_2$ In $At^2 + Bt + C = 0$ $t^2 + (B/A)t + C/A = 0$ and: $t_1 t_2 = C/A$

Sphere not at origin?

Z

X

U

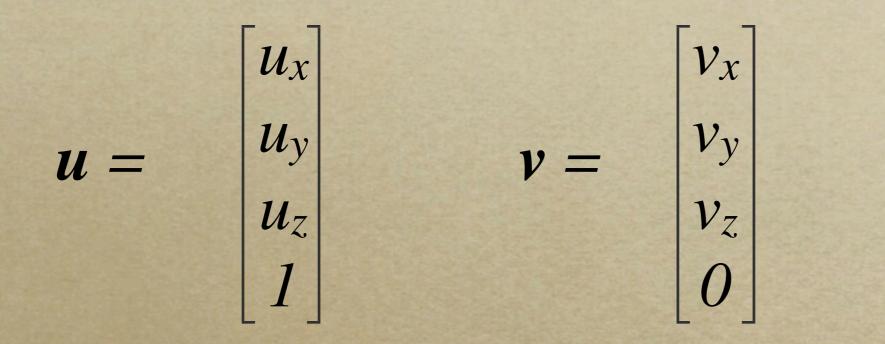
Move the ray not the sphere

Sphere at $c = (c_x, c_y, c_z)$ Use(u-c) + vtSo new $u' = u - c = (u_x, u_y, u_z) - (c_x, c_y, c_z)$ Key point: solving for t in the transformed ray case gives valid t solutions for the original ray equation

General transformed sphere

Suppose the sphere has been magnified, stretched, rotated and shifted. That's just one transformation matrix, M $u' = M^{-1} u$ $v' = M^{-1} v$

Here is real cunning...



M⁻¹ u includes shift but M⁻¹ v doesn't



Ray tracing triangles