COSC410 Logic for AI Introduction to SAT solvers

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Key Topics

- propositional formulas
- seeing formulas as trees
- clausal form
- the SAT problem and its complexity

- getting to clausal form (two ways)
- the DPLL procedure

Propositional Formulas

A propositional formula ϕ can be

- an atomic sentence π such as p
- or a compound formula ψ ↔ χ, ψ → χ, ψ ∨ χ, ψ ∧ χ, or ¬χ, where ψ and χ are smaller formulas.

Not a string but a tree

- When we look at a written formula, we see a string of symbols.
- We have to use precedence rules and parentheses to disambiguate it.
- But a compound formula has a principal connective and one or more parts.

▶ We're dealing with a *tree*.

Why do we care?

Recursive definition by cases.

$$V[\pi]\rho = \rho(\pi)$$

$$V[\psi \leftrightarrow \chi]\rho = V[\psi]\rho \leftrightarrow V[\chi]\rho$$

$$V[\psi \rightarrow \chi]\rho = V[\psi]\rho \rightarrow V[\chi]\rho$$

$$V[\psi \lor \chi]\rho = V[\psi]\rho \lor V[\chi]\rho$$

$$V[\psi \land \chi]\rho = V[\psi]\rho \land V[\chi]\rho$$

$$V[\neg \chi]\rho = \neg V[\chi]\rho$$

where the connectives on the left connect trees and the connectives on the right are applied to truth values, and ρ maps atomic sentences to truth values.

Why this is meaningful

Induction over trees works like induction over natural numbers.

$$\begin{array}{rcl} S[\pi] &=& 1\\ S[\psi \leftrightarrow \chi] &=& 1+S[\psi]+S[\chi]\\ S[\psi \rightarrow \chi] &=& 1+S[\psi]+S[\chi]\\ S[\psi \lor \chi] &=& 1+S[\psi]+S[\chi]\\ S[\psi \land \chi] &=& 1+S[\psi]+S[\chi]\\ S[\neg \chi] &=& 1+S[\chi] \end{array}$$

Recursion on formulas drive sizes (S) down.

Proofs by cases and induction

- Just as we can define functions on formulas recursively, so we can give inductive proofs about formulas.
- Having more ways to build a tree makes a language more convenient to use, but harder to reason about.
- A simpler *language* may mean more complex *formulas*

We're already missing handy connectives

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$$\psi \oplus \chi = \neg(\psi \leftrightarrow \chi)$$

- if au then ψ else χ
- $\langle \alpha \beta \gamma \rangle$, the median or majority function
- $n^{=}(\psi, \chi, ...) = \text{exactly } n \text{ of } \psi, \chi, ... \text{ are true.}$ $\psi \wedge \chi = 2^{=}(\psi, \chi).$
- $n^{\geq}(\psi, \chi, ...) = \text{at least } n \text{ of } \psi, \chi, ... \text{ are true.}$ $\psi \lor \chi = 1^{\geq}(\psi, \chi).$

Simplicity can go too far, or can it?

Anything you can express with the standard propositional connectives or the ones introduced on the previous slide can be expressed using just *one* connective.

• NAND:
$$\psi \tilde{\wedge} \chi = \neg (\psi \wedge \chi)$$

• NOR:
$$\psi \tilde{\lor} \chi = \neg (\psi \lor \chi)$$

▶ ITE: if π then ψ else χ (but needs \top and \bot at leaves)

NAND and NOR are handy for making electronic circuits. If-then-else is one effective approach to SAT solving. Not good for people, though!

Clausal form

- A sentence in clausal form is the conjunction
 (\lambda) of a set of *clauses*.
- ► A clause is the disjunction (∨) of a set of *literals*.
- A literal is either an atom (π) or the negation of an atom (¬π).

Example: $((\neg p \lor q) \land (\neg q \lor r) \land (\neg r)).$

Suppressing the connectives

- Since we know the mid level connectives are all
 v we don't need to write them, just write the clause as a set.

Example: $\{\{\neg p, q\}, \{\neg q, r\}, \{\neg r\}\}$.

Valuations

- A valuation is a function from atomic sentences to truth values.
- Because there are only two truth values, we can think of a valuation as a partition of the set of atomic sentences into *T* (the ones mapped to *T*) and *F* (the ones mapped to ⊥)
- The second approach is handy for *partial* valuations where some atomic sentences have been assigned values and others may not. We shall meet partial valuations later.
- A model of a formula is a valuation making the formula true.

SAT

Given a propositional formula in clausal form,

- **Decision** problem: does it have a model?
- Search problem: find a model or determine that there isn't one.
- Optimisation problem: given a price function on valuations, find a cheapest model (if there is one).

Strictly speaking, SAT is the decision problem.

SAT complexity

- If a formula has n variables, there are 2ⁿ valuations, which we can generate straightforwardly.
- If the formula has m operators, checking a valuation takes O(m) time, so we can try all possible valuations in O(m.2ⁿ) time.
- Can we do better than this?
- In theory, no. Cook proved that SAT is NP-complete. (Checking is easy, searching is hard. Lots of problems can be converted to SAT, which shows they're hard.)
- Yet SAT-solvers are quite practical these days.

k-SAT

 k-SAT is the problem where every clause has k literals.

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- ▶ 2-SAT can be solved in linear time.
- ▶ 3-SAT is as hard as SAT.

Getting to clausal form

- The basic idea is to rewrite a formula from one form to another.
- We use logical theorems $\alpha \equiv \beta$ (to preserve meaning)
- and *orient* them α ⇒ β to convert a "more complex" formula to strictly "less complex" one (so that rewriting terminates and "simplifies")

Four stages

- 1. Eliminate equivalence.
- 2. Eliminate implication.
- 3. Move negation down to the leaves.
- 4. Move conjunction above disjunction.

Each of these stages has its own notion of "complexity".

Eliminate equivalence

- ► Complexity of a formula: the number of ↔ connectives in it.
- Rewrite rule: $\psi \leftrightarrow \chi \Rightarrow (\psi \land \chi) \lor (\neg \psi \land \neg \chi).$
- Apply this rule bottom-up, so that we know ψ and χ do not contain \leftrightarrow .

Eliminate implication

- \blacktriangleright Complexity of a formula: the number of \rightarrow connectives in it.
- Rewrite rule: $\psi \to \chi \Rightarrow (\neg \psi) \lor \chi$
- This rule does not duplicate ψ or χ so the proof of termination works top-down or bottom-up.

Move negation down to the leaves

 Complexity: the number of nodes covered by negations

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Rules:

$$\neg (\psi \lor \chi) \Rightarrow (\neg \psi) \land (\neg \chi) \neg (\psi \land \chi) \Rightarrow (\neg \psi) \lor (\neg \chi) \neg (\neg \chi) \Rightarrow \chi$$

Move conjunction above disjunction

- Complexity: weighted sum of or-over-and violations.
- Rules:

$$\tau \lor (\psi \land \chi) \Rightarrow (\tau \lor \psi) \land (\tau \lor \chi) (\psi \land \chi) \lor \tau \Rightarrow (\tau \lor \psi) \land (\tau \lor \chi)$$

- What if both rules are applicable? E.g., (a ∧ b) ∨ (c ∧ d).
- You get the same end result either way. (Try it.)

Oops

- This process shows that we *can* get from any formula to clausal form by a simple mechanisable procedure.
- But "Eliminate equivalence" *duplicates* subformulas. Hello power of two! Eliminating ⊕ or ⟨...⟩ or if-then-else or n⁼ or n[≥] this way would also duplicate subformulas.
- Worse still, applying the distribution laws *also* duplicates a subformula. Hello exponential growth!

Fighting the monster

- Cook's theorem tells us that we can't do better than exponential time in the worst case.
- But we don't have to go out of our way to cause trouble for ourselves.
- Avoiding an exponential blowup in the size of the formula is a good idea.

The easiest way to do that introduces new atomic sentences.

The Tseitin Transformation

- Key idea: introduce a new atom for each node in the tree.
- Each node now relates at most 3 atoms, and its semantics can be represented by a small set of clauses.
- ► Glue those clause sets together with ∧ and you're done.
- But since the original formula and the transformed one have different sets of atoms, they have different sets of valuations.

We mostly don't care

- Decision: the transformed formula has a model if and only if the original formula has a mode.
- Search: any model for the transformed formula yields a model for the original, by dropping the new atoms.
- Optimisation: if the price of a valuation ignores the new atoms, the transformed and original formulas have the same cheapest models.
- See Tseytin_transformation in Wikipedia.

Tseitin: the rules

$C = \neg A \implies \{\{\neg A, \neg C\}, \{A, C\}\}\$ $C = A \land B \implies \{\{\neg A, \neg B, C\}, \{A, \neg C\}, \{B, \neg C\}\}\$ $C = A \lor B \implies \{\{A, B, \neg C\}, \{\neg A, C\}, \{\neg B, C\}\}\$ $C = A \rightarrow B \implies \{\{\neg A, B, \neg C\}, \{A, C\}, \{\neg B, C\}\}\$ $C = A \leftrightarrow B \implies \{\{A, B, C\}, \{A, \neg B, \neg C\}, \{\neg A, \neg B, C\}\}\$

Exhaustive search

- A simple way to solve any problem with a finite number of discrete variables:
 - Generate each combination and
 - check if it works.
- Simple, yes. Efficient, no. Adequate to show that the problem *can* be solved. Always seek something better.
- Called "generate-and-test". Rule of thumb: push tests back into generator.

Seeking a path through a state space

— Simple depth first search procedure DFS(state, solved?, report, children) if solved?(state) then report(state) else for successor ∈ children(state) do DFS(successor, solved?, report, children)

Backtrack programming

- Given a problem with *n* variables, where each variable x_i has a finite domain D_i, and there is a system of constraints,
- we seek a solution by calling solve({}, {1..n}, $\{j \mapsto D_j, \dots\}$), where
- solve(Known, Unknown, Domains) =
 - if Unknown is empty, report Known.
 - remove some j from Unknown.
 - $\langle \text{try values for } j \rangle$
 - undo remove j
- If no solution is reported, there is none.

 $\langle try values for j \rangle$

▶ for each v in Domains[j] in some order,

- add $j \mapsto v$ to Known.
- if the constraints are not yet violated
 - remove now impossible values from Domains

- solve(Known', Unknown', Domains')
- undo remove now impossible values
- undo add $j \mapsto v$

Room for heuristics

- Which variable j do you pick? (Try the one with the smallest domain, called the "fail-fast" heuristic.)
- ▶ What order do you try the values *v*?
- How much work do you put into ensuring that constraints are not obviously unsatisfiable?
- Do you learn anything from unsuccessful searches? (Modern SAT solvers do.)
- Key point: the undo steps may be unfamiliar. They let us explore large problems by making small, incremental changes and undoing them, instead of copying.

Backtracking is used for

- pretty much any constraint satisfaction or combinatorial optimisation problem, at least as a starting point.
- graph colouring, parsing mildly ambiguous grammars, Sudoku and similar puzzles, finding paths, planning, finding assignments of people to tasks or resources to people, course selection, ...

Incremental simplification (*alias* forward checking, *alias* constraint propagation) usually helps.

Davis-Putnam-Logemann-Loveland Procedure

- Variables: atomic sentences
- Their domains: $\{\bot, \top\}$
- Constraints: the clauses
- Known: a partial valuation
- Unknown: as-yet-unknown atomic sentences
- Seeking: a complete valuation consistent with the clauses

At each DPLL step

- unit propagation. Unit clauses have one literal. "Propagation" is substituting known information in clauses (or other constraints) and simplifying. For example, $\{x\}$ and $\{\{x, \neg y\}, \{\neg x, y\}\}$ simplifies to $\{\{y\}\}$. The first clause drops out. The second clause simplifies: if x is true, the only way to make $\neg x \lor y$ true is for y to be true. Now we can substitute y and simplify...
- pure literal elimination. If some clause has π but no clause has ¬π, make π true and delete all clauses containing π. (Similarly ¬π.)

and then

After unit propagation and pure literal elimination,

- search: pick some variable π
- make π true, simplify, and recur.
- undo those changes.
- make π false, simplify, and recur.
- undo those changes.

Finally *undo* changes made by unit propagation and pure literal elimination.

Improvements to DPLL

- Clever data structure design to make changing and undoing changes easy.
- Typical backtracking heuristics: choose the most constrained variable, try first the value that will let you eliminate most clauses.
- Learn from failure: non-chronological backtracking and conflict-driven clause learning.
- Human care in formulating a problem, e.g., exploit symmetry.