
NEURON - tutorial D of Gillies & Sterratt (part 2)

<http://www.anc.ed.ac.uk/school/neuron/>

COSC422 – lecture 11

How to program ion channels with **NMODL**

NMODL: creating the .mod file

- A description of a membrane mechanism in **NMODL** in a text file is divided into a number of blocks.
- Each block begins with a keyword defining the type of block, then an open brace "{", followed by block specific definitions, and finally, the block is ended with a closing brace "}".
- We will construct a NMODL file, called **CaT.mod** to calculate the low threshold calcium channel kinetics. As with hoc files we can use any text editor to create this file.
- (Note: there are a number of NMODL examples provided with the NEURON package.)

The TITLE and UNITS blocks

- We start the NMODL file with some standard definitions, i.e.:

```
TITLE Calcium T channel for Subthalamic Nucleus
UNITS {
    (mV) = (millivolt)
    (mA) = (milliamp)
}
```

- The TITLE keyword identifies what this file is describing.
- The UNITS block defines conventions for the units that will be used in this file. It uses these units to check that equations are consistent.
- By default, NMODL understands units in the UNIX units database (see file /usr/share/units.dat or look at the units command).

The NEURON block

- The NEURON block is the public interface of the mechanism. It tells the **hoc** interpreter how to refer to the mechanism and what variables it can see or change. The structure of the block is as follows:

```
NEURON {  
    SUFFIX suffix  
    USEION ions... READ vars... WRITE vars...  
    RANGE var,var,...  
    GLOBAL var,var,...  
}
```

- Now we will explain each line in turn.

The NEURON block: **SUFFIX** **suffix**

- The first step is to identify this particular mechanism from all other membrane mechanisms when referencing it from the **hoc** file.
- This is done through the **SUFFIX** statement of the block.
- Access to all variables in this mechanism from the **hoc** file is then done using the **suffix**.
- For example, we will call this channel mechanism "**CaT**", so to access variables in the mechanism from hoc we use **var_CaT** (where **var** is a variable in this mechanism).

The NEURON block: **USEION**

- The **USEION** specifies what ions this channel mechanism uses.
- There are three implicitly defined ions NEURON knows about (**na**, **k**, **ca**) however, others may also be defined via this statement.
- NEURON can keep track of the intracellular and extracellular concentrations of each ion.
- Dealing with ions is difficult, because more than one mechanism may affect a particular ion. For example, we may have more than one calcium channel mechanism. Therefore, when dealing with ions use exactly the same name used in all other mechanisms.

```
USEION ions READ vars WRITE vars
```

- The READ modifier lists ion variables needed in calculating the ion channel current (usually the equilibrium potential, or concentration).
- The WRITE modifier lists what ion variables are calculated in this mechanism (usually the current). In our example we use Ca ion:
 - ```
USEION ca READ eca WRITE ica
```
- where **eca** is the equilibrium potential for ion ca (calcium),
- **ica** is the calcium current

## Note on how NEURON deals with ions

- Since we have just introduced `ica`, a calcium current, we may expect NEURON will automatically adjust the intra- and extracellular calcium concentrations. **It doesn't !!!**
- NEURON does not change the ionic concentrations automatically. To do this, we would need another mechanism defined in NMODL that would WRITE `cai` and/or `cao`, the intra- and extracellular calcium concentrations. However this mechanism would need to know the total calcium current `ica` originating from our CaT mechanism and any other mechanisms affecting calcium current. NEURON provides a means of doing this – see the NMODL webpage.
- Let's continue without modelling calcium accumulation adjacent to the membrane, either intracellularly or extracellularly.



# The NEURON block: Range and Global

- The RANGE statement makes the following variables visible to the NEURON interpreter and that they are to be functions of a position.
- The GLOBAL statement specifies variables that are always the same for the mechanism. CaT mechanism does not have any GLOBAL variables. Our final NEURON block now has the form:

```
NEURON {
 SUFFIX CaT
 USEION ca READ eca WRITE ica
 RANGE gmax
}
```

# The PARAMETER block

- The PARAMETER block in **CaT.mod** is this:

```
PARAMETER {
 gmax = 0.002 (mho/cm2)
}
```

- For each parameter, we specify the name of the parameter, its default value and its units (in parentheses).
- The PARAMETER block specifies variables that:
  - ❑ are not changed as a result of the calculations in the mechanism;
  - ❑ are (generally) constant throughout time; and
  - ❑ can be changed in the **hoc** file, e.g. **soma gmax\_CaT = 0.001**

---

# The ASSIGNED block

- The ASSIGNED block declares variables that are either:
  - calculated by the mechanism itself or
  - computed by NEURON.
- Variables that this mechanism will compute are the calcium current  $i_{ca}$ , and variables for the rate equations **ralpha**, **rbeta**, **salpha**, etc.
- The variables that the mechanism uses that are computed by NEURON are the membrane potential  $V$  and the calcium equilibrium potential **eca**.

# The ASSIGNED block

- For **CaT**, the ASSIGNED block looks like this:

```
ASSIGNED {
 v (mV)
 eca (mV)
 ica (mA/cm2)
 ralpha (/ms)
 rbeta (/ms)
 salpha (/ms)
 sbeta (/ms)
 dalpha (/ms)
 dbeta (/ms)
}
```

# The heart of CaT mechanism

- Recall we want to calculate:

$$I_T = g_{T(\max)} r^3 s (V - E_{Ca})$$

- We wish to calculate the values of the state variables  $r$ ,  $s$  and  $d$  in order to calculate the calcium current from the above equation.
- The state variables are given by the three kinetic differential equations:

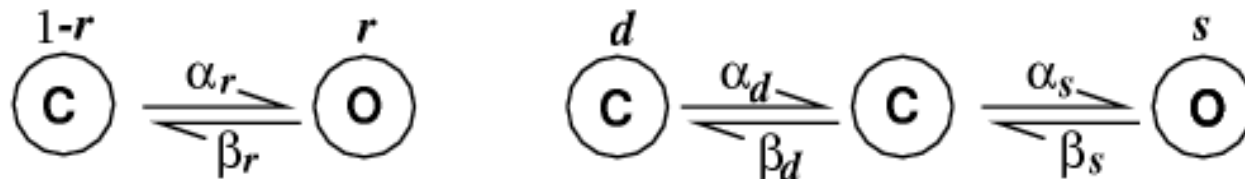
$$\dot{r} = \alpha_r (1 - r) - \beta r$$

$$\dot{s} = \alpha_s (1 - s - d) - \beta_s s$$

$$\dot{d} = \alpha_d (1 - s - d) - \beta_d d$$

# The STATE block

- The STATE block declares state variables.
- There are 3 state variables in our kinetic channel model,  $r$ ,  $s$  and  $d$ .



- For **CaT**, the STATE block looks like this:

```
STATE {
 r s d
}
```

---

# PROCEDURE

- However, we must first calculate each of the rate functions  $r_{\alpha}$ ,  $r_{\beta}$ ,  $s_{\alpha}$ ,  $s_{\beta}$ ,  $d_{\alpha}$  and  $d_{\beta}$ .
- We can create a PROCEDURE to do this.
- A procedure is defined using the following format:

```
PROCEDURE name(vars) {
 calculations...
}
```

```

PROCEDURE settables(v (mV)) {
 LOCAL bd

 ralpha = 1.0 / (1.7 + exp(-(v+28.2)/13.5))
 rbeta = exp(-(v+63.0)/7.8) / (exp(-(v+28.8)/13.1) + 1.7)

 salpha = exp(-(v+160.3)/17.8)
 sbeta = (sqrt(0.25 + exp((v+83.5)/6.3)) - 0.5) *
 (exp(-(v+160.3)/17.8))

 bd = sqrt(0.25 + exp((v+83.5)/6.3))
 dalpha = (1.0 + exp((v+37.4)/30.0)) / (240.0 * (0.5 + bd))
 dbeta = (bd - 0.5) * dalpha
}

```



---

# Why we call procedure **settables**

- The above procedure takes the current voltage  $v$  as an argument (**vars**) and calculates values of the rate functions  $r_{\alpha}$ ,  $r_{\beta}$ , etc.
- The rate functions will need to be reevaluated at each time step.
- However, as the voltage is changing, it is more computationally efficient to create a table of values calculated at closely spaced voltages at the start of a simulation, and use the table lookup with linear interpolation based on the current voltage (memory is cheaper than computation).
- This can be done by adding a TABLE line to the procedure.

---

# Procedure **settables**

- The TABLE command has the form:

**TABLE funcs DEPEND vars FROM lowest TO highest WITH steps**

- Where **funcs**, are the variables representing the functions to create tables for (e.g. the alpha and beta function variables)
- **vars** are those variables, which if they change value then all tables must be recalculated.
- **lowest** and **highest** are the lowest and highest values of the voltage we make the tables over, with steps **steps** between them.

```

PROCEDURE settables(v (mV)) {
 LOCAL bd

 TABLE ralpha, rbeta, salpha, sbeta, dalpha, dbeta
 FROM -100 TO 100 WITH 200

 ralpha = 1.0 / (1.7 + exp(-(v+28.2)/13.5))
 rbeta = exp(-(v+63.0)/7.8) / (exp(-(v+28.8)/13.1) + 1.7)
 salpha = exp(-(v+160.3)/17.8)
 sbeta = (sqrt(0.25 + exp((v+83.5)/6.3)) - 0.5) *
 (exp(-(v+160.3)/17.8))

 bd = sqrt(0.25 + exp((v+83.5)/6.3))
 dalpha = (1.0 + exp((v+37.4)/30.0)) / (240.0 * (0.5 + bd))
 dbeta = (bd - 0.5) * dalpha
}

```

## The DERIVATIVE block

$$\dot{r} = \alpha_r(1-r) - \beta_r r$$

$$\dot{s} = \alpha_s(1-s-d) - \beta_s s$$

- The  $\alpha$  and  $\beta$  rate functions are used in equations:  
$$\dot{d} = \alpha_d(1-s-d) - \beta_d d$$
- These are specified in the DERIVATIVE block, which we will call **states**.

```
DERIVATIVE states {
 settables(v)
 r' = ((ralpha*(1-r)) - (rbeta*r))
 d' = ((dbeta*(1-s-d)) - (dalpha*d))
 s' = ((salpha*(1-s-d)) - (sbeta*s))
}
```

- Each time NEURON calculates the differential equations, the a and b must be updated, so the first line calls the procedure **settables** with the current voltage v.

# The BREAKPOINT block

- The BREAKPOINT is the top level mechanism calculation block that calculates the calcium current:

```
BREAKPOINT {
 SOLVE states METHOD cnexp
 ica = gmax*r*r*r*s*(v-eca)
}
```

- The Ca current is calculated according to the equation:

$$I_T = g_{T(\max)} r^3 s (V - E_{Ca})$$

- The SOLVE statement refers to the states defined in the DERIVATIVE block. The METHOD cnexp part of the line tells NEURON to use the "**cnexp**" method of integration, which is suitable for mechanisms of the form:  $dx/dt = f(V, x)$ , where  $f$  is linear in  $x$  and involves no other states.

# The INITIAL block

- This block is the last one. It is used to set the state variables  $r$ ,  $d$  and  $s$  to their initial values. The INITIAL block first calls the procedure **settables** with the present voltage to calculate the values of the  $\alpha$ 's and  $\beta$ 's, which are used to calculate the initial values of  $r$ ,  $d$  and  $s$ .

```
INITIAL {
 settables(v)
 r = ralpha/(ralpha+rbeta)
 s = (salpha*(dbeta+dalpha) - (salpha*dbeta)) /
 ((salpha+sbeta) * (dalpha+dbeta) - (salpha*dbeta))
 d = (dbeta*(salpha+sbeta) - (salpha*dbeta)) /
 ((salpha+sbeta) * (dalpha+dbeta) - (salpha*dbeta))
}
```

# Putting it all together

```
TITLE Calcium T channel for Subthalamic Nucleus
UNITS {...}
NEURON {...}
PARAMETER {...}
ASSIGNED {...}
STATE {...}
BREAKPOINT {...}
INITIAL {...}
DERIVATIVE states {...}

UNITSOFF
PROCEDURE settables(v (mV)) {...}
UNITSON
```

- the commands `UNITSON` and `UNITSOFF` in the file activate the units checking (e.g. mV, mA etc.) and deactivate it respectively.

# Speed of simulation

- To speed up a simulation we can reduce the number of segments **nseg** or increase **dt**. However, this will decrease the accuracy of results.
- Another strategy is a variable time step method. The principle is that the **dt** is longer when quantities are not changing much (such as between spikes) and shorter when quantities are changing quickly (such as during a spike).
- By default, NEURON uses fixed time step integration. The command  
**cvode\_active()**
- returns 0, indicating that variable time step is turned off. To turn on the variable time step integration we type: **cvode\_active(1)**