

COSC441 Concurrent Programming

C11 Threading Basics

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C11

- ▶ The C11 standard added threads to ISO C.
- ▶ Some libraries still haven't caught up (OSX).
- ▶ <https://github.com/jtsiomb/c11threads> provides a C11 interface to POSIX threads
- ▶ `_Atomic` and `_Thread_local` need compiler support
- ▶ Look for `<threads.h>`

Threads (1)

- ▶ `thr_t` — implementation-defined type for identifying threads.
- ▶ `thr_current()` — identifier for current thread
- ▶ `thr_equal(x, y)` — do x and y refer to the same thread?
- ▶ `thr_exit(n)` — cleans up this thread's thread-specific storage, sets result to n , and terminates thread.

Threads (2)

- ▶ `thrd_create(&id, fun, arg)` calls `fun(arg)` in a new thread, setting `id` to the identifier of that thread.
- ▶ No control over size or location of stack or any other property. `fun` returns `int`.
- ▶ `thrd_join(id, &res)` — waits for thread `id` to terminate, stores result in `res`
- ▶ `thrd_detach(id)` makes `id` unjoinable.

parbegin

The older `parbegin s1; ...; sn end` is

```
thrd_create(&t1, f1, a1); // f1(a1) does s1  
...  
thrd_create(&tn, fn, an); // fn(an) does sn  
thrd_join(t1, NULL); // wait for t1 to finish  
...  
thrd_join(tn, NULL); // wait for tn to finish
```

Threads: missing operations

Some operations you might expect are missing.

- ▶ is thread x still alive?
- ▶ suspend thread x
- ▶ resume thread x
- ▶ kill thread x (in POSIX)
- ▶ enquire about properties of x

Mutexes: concepts

- ▶ A mutex is a queue of waiting threads.
- ▶ And an indication of whether (plain) or which (recursive) thread holds the mutex, if any.
- ▶ Recursive mutex has a counter.
- ▶ Support MUTual EXclusion.

Plain mutexes

- ▶ atomic lock(plain) {
if plain is unlocked then mark plain as locked
otherwise add this thread to the waiting queue
}
- ▶ atomic unlock(plain) {
it is an error if plain is not locked.
if the queue is empty mark plain as unlocked
otherwise wake one thread from the queue }
- ▶ Doing lock(&m); lock(&m); deadlocks the calling thread.

Recursive mutexes

- ▶ atomic lock(mutex) {
if mutex's count is 0 set count to 1 and record
this thread as the owner, otherwise if this
thread is recorded as the owner, increment the
count, otherwise add this thread to the waiting
queue }
- ▶ atomic unlock(mutex) {
it is an error if this thread is not the mutex's
owner.
decrement the count.
if the count is 0 and any thread is waiting,
wake a waiting thread. }
- ▶ Doing lock(&m); lock(&m); works.

Mutexes: interface (1)

- ▶ `mtx_t` — implementation-defined type of mutex objects (not pointers or identifiers). Do not copy/assign.
- ▶ `mtx_init(&mutex, type)` Do not call on mutex currently in use!
- ▶ `type` is `mtx_plain`, `mtx_timed` (allows timeouts), `mtx_plain|mtx_recursive` (can be repeatedly locked by same thread), or `mtx_timed|mtx_recursive`
- ▶ `mtx_destroy(&mutex)` — opposite of `init`. Do not call if still in use.
- ▶ No way to tell if mutex is still in use.

Mutexes: interface (2)

- ▶ `mtx_lock(&mutex)`
lock the mutex; if you can't do it now, wait until you can.
- ▶ `mtx_trylock(&mutex)`
if you can lock the mutex now, do so and return `thrd_success`, otherwise return `thrd_busy`.
- ▶ `mtx_unlock(&mutex)`
unlock the mutex. (For recursive, might still own.)
- ▶ `mtx_timedlock(&mutex, &when)`
like `mtx_lock` but gives up and returns `thrd_timedout` if the clock reaches *when* and not able to lock yet.

Barriers and ordering

- ▶ Locking and unlocking mutexes acts as a memory barrier. Pending loads and stores are completed, then the locking operation done, then new loads and stores can start.
- ▶ Actions in independent threads are generally unordered but `init`, `(lock | trylock | timedlock | unlock)*`, `destroy` operations on any one lock happen in some total order.

Mutexes: missing operations

There is no way to ask “lock exactly one of these and tell me which one”.

You can use trylock to find out if a mutex is locked, but you can't ask how many other threads want it.

Deadlock diagnosis requires a graph of which threads hold/want which locks, but you can't access it.

Mutexes: missing language feature

A mutex exists to protect specific data.

There is no link between the data and the mutex in C.

Put the data in a struct and put the mutex in the same struct.

Conditions: concepts

The basic idea is that inside a critical region, we want to wait until some logical expression is true. To make it true, some other thread will have to get the lock. Ideally, we'd write `await expr`;

A “condition variable” is a queue of threads waiting for the same condition to become true of the same protected data.

Conditions: interface (1)

- ▶ `cond_t` — implementation-defined type of condition objects (not pointers or identifiers). Do not copy/assign.
- ▶ `cond_init(&cond)`. Do not call on *cond* already in use!
- ▶ `cond_destroy(&cond)`. Opposite of `init`. Do not call if *cond* still in use.

Conditions: interface (2)

- ▶ `cond_wait(&cond, &mutex)`
atomically, add the current thread to the queue of threads in *cond*, and unlock *mutex*. When awoken, re-lock *mutex*.
- ▶ `cond_timedwait(&cond, &mutex, when)`
Like `cond_wait` but if clock reaches *when*, wake up anyway and return `thrd_timedout`.
- ▶ `cond_signal(&cond)`
wake up one waiting thread
- ▶ `cond_broadcast(&cond)`
wake up all waiting threads

Conditions: beware

- ▶ signals/broadcasts are not counted; if there are no waiting threads when you issue a signal, it's as if it never happened.
- ▶ We expect signalling a condition to wake *one* thread. The POSIX specification for this operation says it wakes *at least one* thread. This concession is for multicore machines, and some libraries *do* wake multiple threads.

Thread-local variables

- ▶ `_Thread_local` *object-declaration*;
for declaring variables such that each thread gets its own copy.
- ▶ can be combined with `static` (the name is local to this file, but every thread still has a copy)
- ▶ or `extern`, the default.
- ▶ `<threads.h>` defines `thread_local` as a synonym
- ▶ Such variables may be initialised.

Thread-specific storage (1)

- ▶ `tss_t` — implementation-defined type of thread-specific storage key type.
- ▶ `tss_create(&key, destructor)`
creates a new thread-local variable at run time; *key* identifies this (relative to the calling thread). Values are `void*`, initially `NULL`. *destructor* is called to clean up.
- ▶ `texttttss_destroy(&key)`
Reclaims storage used for this key in every thread. Does *NOT* call destructor.
- ▶ Destructor is called *ONLY* when thread exits.

Thread-specific storage (2)

- ▶ `tss_get(&key)`
return `void*` value associated with `key` in calling thread.
- ▶ `tss_set(&key, value)`
set value associated with `key` in calling thread, does not call destructor to clean up old value.
- ▶ Note: cannot get or set tss value in any other thread, or form a pointer to it so that could be done indirectly.
- ▶ Use `_Thread_local` if you can because that gets type-checked.

Lazy initialisation: single-threaded

```
static initialised = 0;
```

```
...
```

```
if (!initialised) {  
    initialised = 1;  
    do_initialisation();  
}
```

Lazy initialisation: multi-threaded

```
static once_flag initialised = ONCE_FLAG_INIT;  
...  
call_once(&initialised, do_initialisation);
```

Atomic types and operations

- ▶ `_Atomic(t)` is a type specifier provided *t* is a type name other than a function, array, atomic, or qualified type.
- ▶ `_Atomic` may be used as a qualifier along with a type that is not a function or array type.
- ▶ Operations are in `<stdatomic.h>`

Atomic operations (simplified, 1)

- ▶ `atomic_store(&dst, val)`
- ▶ `val = atomic_load(&src)`
- ▶ `old = atomic_exchange(&dst, new)`
- ▶ `if (atomic_compare_exchange_weak(&dst, &old, new) — LL+SC, _strong is CAS.`

Atomic operations (simplified, 2)

- ▶ $old = \text{atomic_fetch_op}(\&dst, operand)$
_add like $+=$, _sub like $-=$, _and like $\&=$, _or like $|=$, _xor like $\hat{=}$, except that old value is returned, not new value.
- ▶ You can atomically update integers and pointers, but apparently not floats/doubles.