

Divide and Conquer Lecture 6

COSC 242 – Algorithms and Data Structures



Today's outline

- 1. Divide and conquer
- 2. Binary search
- 3. Binary search analysis
- 4. Merge
- 5. Mergesort

Types of algorithms

In COSC242, we will be looking at 3 general types of algorithms:

- 1. Divide-and-conquer algorithms
- 2. Greedy algorithms
- 3. Dynamic programming algorithms

Each type of algorithm can be used to naturally, or more easily, solve a particular type of problem.

It is useful to keep a list of the typical problems that a given type of algorithm is good for.

Incremental approach

In LO1 we looked at Insertion sort. This algorithm applied an incremental approach:

Having already sort A[1..j-1], we insert the single element A[j] into its proper place, yielding the sorted subarray A[1..j].

Today we will look at a different approach, known as "divide and conquer".

Divide and conquer

Many useful algorithms are **recursive** in structure. To solve a given problem, they call themselves recursively one or more times to deal with closely related smaller problems.

These algorithms typically follow a divide-and-conquer approach.

Divide-and-conquer algorithms usually work on sequential data structures of known size. Thus, they are commonly used when working with *arrays*.

Divide, then conquer. But first lets divide...

The divide-and-conquer paradigm involves three steps at each level of the recursion:

- 1. Divide the problem into a number of subproblems that are smaller instances of the same problem.
- 2. Conquer the subproblems by solving them recursively. If the subproblem sizes are small enough, however, just solve the subproblems in a straightforward manner.
- **3. Combine** the solutions to the subproblems into the solution for the original problem.

Divide, then conquer. But first lets divide...

Divide-and-conquer processes the data structure X as:

- if X is an atom then
- 2. process X directly
- 3. else
- 4. divide X into two or more smaller pieces
- 5. apply the algorithm to each piece "recursively"
- 6. combine the processed pieces (if necessary)

Looking up a name

Lets say you're looking for company in the phone book. We'll call them the "Max's mini donuts".

How would you go about finding them, assuming for a moment there's no search function?

Would you start at "AAA aardvarks" and work your way forward, one entry at a time? Or would you start in the middle, as "M" is not too far from the middle.

Discussion: Guessing game



Your friend asked you to guess a number between 1 and 100. You have 7 tries, and they will only respond with: correct, higher, or lower.

Questions

What number would you start with?

Can you win in 7 tries?

Would this work for pulling numbers out of a jar? Why, why not?

Binary search

The strategy we've just seen is an example of **binary search**. It's an efficient algorithm for finding an item in a *sorted list*.

Consider an array A[0..n-1] of sorted keys, and suppose we want to locate a target value x. The simplest way to search is sequentially, but sequential search is linear: O(n).

In binary search, we find the index $m = \lfloor (n-1)/2 \rfloor$ of the middle element, then compare x with A[m].

Binary search

There are 4 possibilities:

If x = A[m], we have found x.

If x < A[m], we have the smaller array A[0..m-1]

If x > A[m], we search the smaller array A[m+1..n-1]

If the breaking down process ever gives an empty array, we've gone too far and can stop.

A 0 mid n-1

Binary search pseudocode

```
Binary_search(A, x, low, high):
```

- 1. if low > high then
- 2. report failure and stop
- 3. else
- 4. $mid \leftarrow (low + high) / 2$
- 5. **if** x = A[mid] **then**
- 6. report success and return mid
- 7. else if x < A[mid] then
- 8. return Binary_search(A, x, low, mid 1)
- 9. **else if** x > A[mid] **then**
- 10. return Binary_search(A, x, mid+1, high)



Questions

- 1. Write the function call execute a binary search on A, below, searching for number 31.
- 2. Trace the operations of the binary search.

Α	8	13	20	21	22	31	33	39	42	55
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Binary search analysis

To look for x in an array A of length n, you would call Binary_search(A, x, 0, n - 1)

Analysis: How many times (in the worst case) can we divide the length n in half? Try it for 8, 16, 32, 64.

 $2^n = 2x2x2x...2$. How many times can I divide that by 2?

Complexity function is f =

Merge two arrays

We have two arrays X and Y each in sorted order. We want to build array Z containing all the keys of X and Y in sorted order. Length(X) = l, length(Y) = m:

```
initialise i, j, k to 0 (i, j, k index the arrays X, Y, Z)
      while i < l and j < m do
3.
        if X[i] < Y[j] then
           Z[k] \leftarrow X[i]
     i ← i + 1
       else if X[i] \ge Y[j] then
6.
           Z[k] \leftarrow Y[i]
           i \leftarrow i + 1
8.
         k \leftarrow k + 1
9.
```

- 10. **if** $i \ge l$ then copy the end of Y to the end of Z
- 11. **else** copy the end of X to the end of Z

Merge analysis

How many times through the merge while loop?

One thing we notice is that i, j, k all start at 0. Each time through the loop k is incremented and either i or j is incremented. Neither i, j or k ever gets smaller.

At the end of the loop:

either (i = l and j < m) or (j = m and i < l),

k is just the sum of i and j, so k < l + m.

Merge analysis

Since k is incremented every time through the loop, the number of times through the loop is less than l+m. Then, whichever array has not been fully scanned is copied onto the end of Z.

So the number of operations is some constant times l+m. Let n=l+m, so Merge is O(n). Or more specifically, it's O(n).

Mergesort

To mergesort an array A[0 .. n - 1] of keys, we repeatedly split A, and after getting to the bottom we rebuild by merging the pieces. To identify the pieces that must be split or patched together, we use indices *left* and *right*.

Mergesort(A, left, right) // sorts the keys in A[left .. right]

- 1. **if** $left \ge right$ **then**
- 2. stop since A[left .. right] is sorted
- 3. else
- 4. $mid \leftarrow (left + right) / 2$
- 5. Mergesort(A, left, mid)
- 6. Mergesort(A, mid + 1, right)
- 7. Merge subarrays A[left .. mid] and A[mid + 1 .. right]

Pop quiz 1



What is the primary way in which binary search and mergesort algorithms are related?

Mergesort analysis

Let's call the time complexity function T.

If n = 1, then mergesort takes constant time, so T(1) = 1.

Otherwise the number of operations needed to mergesort n keys is equal to the number of operations needed to do two mergesorts of size n/2 (the recursive calls), plus the merge needed to patch the two sorted arrays of length n/2 together (which is linear, shown previously).

So
$$T(n) = 2T(n/2) + n$$
.

We'll see how to analyse these sorts of complexity functions in the next lecture.

Suggested reading

Divide and conquer algorithms are discussed in section 2.3 of the textbook, including a look at mergesort and its analysis*.

^{*}Section numbers refer to those in the 3rd edition.

Solutions

Discussion: Guessing game



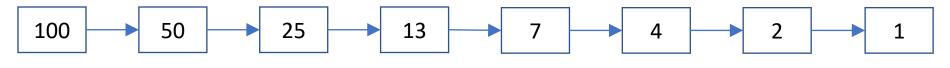
Your friend asked you to guess a number between 1 and 100. You have 7 tries, and they will only respond with: correct, higher, or lower.

Questions

What number would you start with?

Can you win in 7 tries?

Would this work for pulling numbers out of a jar? Why, why not?

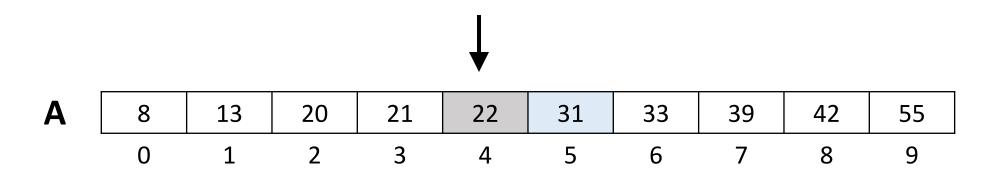


7 guesses



Binary_search(A, 31, 0, 9)

1. Mid =
$$|0 + (9)|/2 = 4$$
. x!= 22, and x > 22

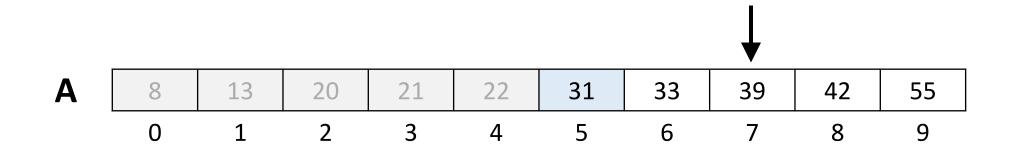




Binary_search(A, 31, 0, 9)

1. Mid =
$$[0 + (9)]/2 = 4$$
. x!= 22, and x > 22

2. Low = mid + 1 = 5. Mid =
$$[5 + (9)]/2 = 7$$
. x!= 39, and x < 39





Binary_search(A, 31, 0, 9)

1. Mid =
$$[0 + (9)]/2 = 4$$
. x!= 22, and x > 22

2. Low = mid + 1 = 5. Mid =
$$[5 + (9)]/2 = 7$$
. x!= 39, and x < 39

3. High = mid – 1 = 6. Mid = [5 + (7)]/2 = 6. x!= 6, and x < 33.

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Α	8	13	20	21	22	31	33	39	42	55
	0	1	2	3	4	5	6	7	8	9



Binary_search(A, 31, 0, 9)

1. Mid =
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. x!= 22, and x > 22

2. Low = mid + 1 = 5. Mid =
$$[5 + (9)]/2 = 7$$
. x!= 39, and x < 39

3. High = mid
$$-1$$
 = 6. Mid = $|5 + (7)|/2 = 6$. x != 6, and x < 33.

4. High = mid -1 = 5. x == 5, report success and return 5.

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A	8	13	20	21	22	31	33	39	42	55
	0	1	2	3	4	5	6	7	8	9

Pop quiz 1



What is the primary way in which binary search and mergesort algorithms are related?

Answers

Use of a divide and conquer, which entails recursion

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