

## Quicksort Lecture 8

#### COSC 242 – Algorithms and Data Structures



## Today's outline

- 1. Introduction to Quicksort
- 2. Partition
- 3. Worst case
- 4. Best case
- 5. Balanced partitioning

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## Mergsort limitations

Mergesort divides the input array A[*low..high*] into two pieces of similar size without looking at the contents.

We get pieces A[*low..mid*] and A[(*mid+1*)..*high*] by using the location  $mid \leftarrow (low + high)/2$ .

After sorting the two pieces, we have to merge them, costing us an extra *n* operations.

Can we arrange it so that we don't have to merge at the end? This is the strategy that Quicksort uses.

# Key features of Quicksort

#### **Key features**

- Worst-case running time:  $\theta(n^2)$
- Expected running time:  $\theta(n \log_2 n)$
- Constants hidden in  $\theta(n \log_2 n)$  are small.
- Sorts in place.

Quicksort is an efficient and widely used sorting algorithm.

## Divide and conquer approach

Quicksort is based on a three-step process that uses divide-andconquer.

**Recall**: divide-and-conquer splits a task into smaller pieces, and uses recursion to solve the smaller sub-problems. Once the base case is reached, it then recurses up, combining the mini-solutions.

## Quicksort process



To sort the subarray A[p...r]:

**Divide**: Partition (rearrange) A[p..r] into two (possibly empty) subarrays: A[p..q-1] and A[q+1..r]. Each element of the first subarray  $A[p..q-1] \le A[q]$ . Each element of the second subarray A[q+1..r] >A[q]. As part of this partitioning process, identify index q. We call this the "pivot".

**Conquer**: Sort A[p..q-1] and A[q+1..r] by recursive calls to quicksort.

**Combine**: Combine the two subarrays. Since both are now sorted, no work is done.

# Quicksort implementation



QUICKSORT (A, p, r):

1 **if** p < r

$$2 \quad q = PARTITION(A, p, r)$$

3 QUICKSORT(
$$A$$
,  $p$ ,  $q$ -1)

4

Recall A[p .. r] p = first index r = last index

// First half, from p up to partition point q QUICKSORT(A, q+1, r) // Second half, from q+1 up to end r

Initial call is QUICKSORT(A, 1, n)

## Need more help?

If at the end of today's notes you need some extra help, check out this Kahn academy class, co-written by the textbook's first author [1].

# Today's outline

1. Introduction to Quicksort

### 2. Partition

- 3. Worst case
- 4. Best case
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## Partitioning

The quicksort algorithm is deceptively simple. However, the key insight lies in the partitioning process.

```
PARTITION(A, p, r)

x = A[r]

i = p - 1

for j = p to r - 1

if A[j] \le x

i = i + 1

swap A[i] with A[j]

swap A[i+1] with A[r]

return i + 1
```

PARTITION always selects an element x = A[r] as a *pivot* element around which to partition the subarray A[p..r].

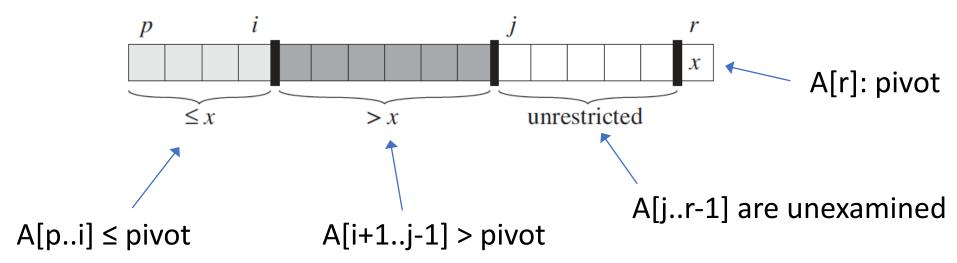
## Visualising quicksort

**Lightly shaded**: First partition  $\leq x$ , that is,  $\leq A[r]$ 

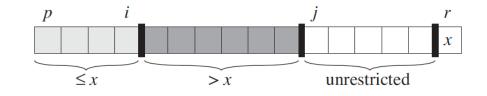
**Heavily shaded**: Second partition > x

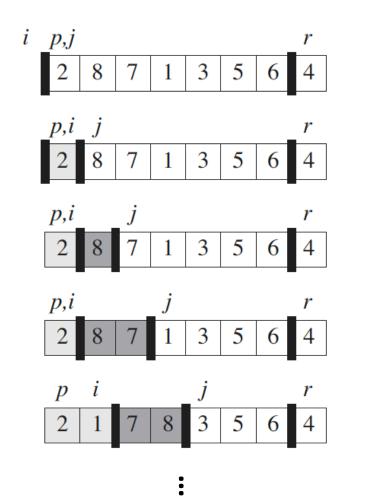
**Unshaded**: Elements not yet put in a partition

**Unshaded r**: The pivot x



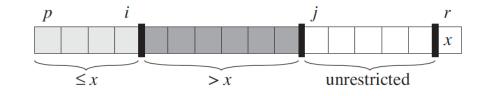
## Partition in action

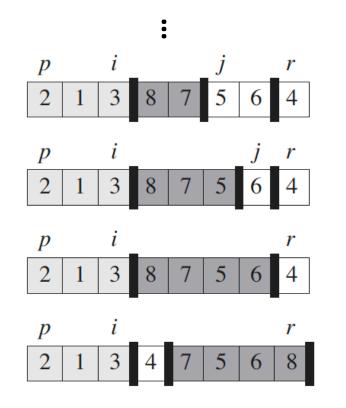




PARTITION(
$$A$$
,  $p$ ,  $r$ )  
 $x = A[r]$   
 $i = p - 1$   
for  $j = p$  to  $r - 1$   
if  $A[j] \le x$   
 $i = i + 1$   
swap  $A[i]$  with  $A[j]$   
swap  $A[i+1]$  with  $A[r]$   
return  $i + 1$ 

## Partition in action





```
PARTITION(A, p, r)

x = A[r]

i = p - 1

for j = p to r - 1

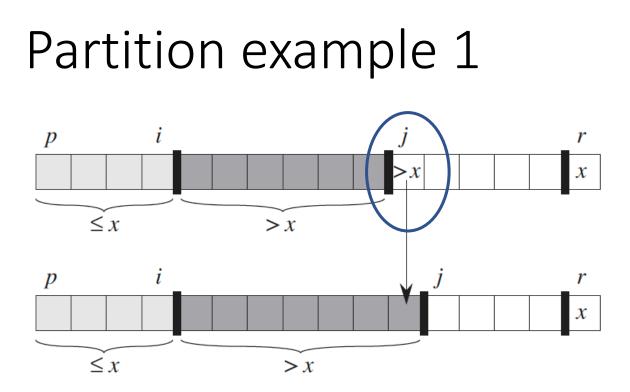
if A[j] \le x

i = i + 1

swap A[i] with A[j]

swap A[i+1] with A[r]

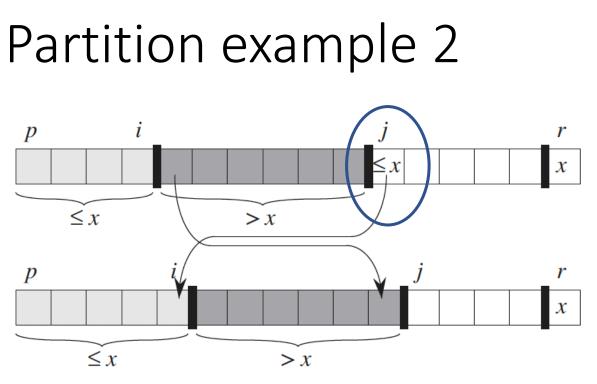
return i + 1
```



PARTITION(A, p, r) x = A[r]i = p - 1for j = p to r - 1if  $A[j] \leq x$ i = i + 1swap A[i] with A[j]swap A[i+1] with A[r]return i + 1

If A[j] > x, then: 1. *j* is incremented

That is, the heavily shaded region grows by 1.



PARTITION(A, p, r) x = A[r]i = p - 1for j = p to r - 1if  $A[j] \leq x$ i = i + 1swap A[i] with A[j]swap A[i+1] with A[r]return i + 1

If  $A[j] \leq x$ , then:

- 1. index *i* is incremented
- 2. A[i] and A[j] are swapped
- 3. *j* is incremented

That is, the heavily shaded region grows by 1.

## Class challenge 1

Apply partition to the following array:



```
PARTITION(A, p, r)

x = A[r]

i = p - 1

for j = p to r - 1

if A[j] \le x

i = i + 1

swap A[i] with A[j]

swap A[i+1] with A[r]

return i + 1
```

## Partition analysis

To analyse Partition, we can use a simple counting argument as we did for Merge:

- i starts at p-1
- j starts at p
- Each time through the for loop (line 3), j is incremented at least once (line 3).
- Only if our element is less than our pivot do we increment i (line 5), and swap elements (line 6).
- We then do our final swap of our pivot (line 7), and return the index of our pivot (line 8).

```
PARTITION(A, p, r)

1. x = A[r]

2. i = p - 1

3. for j = p to r - 1

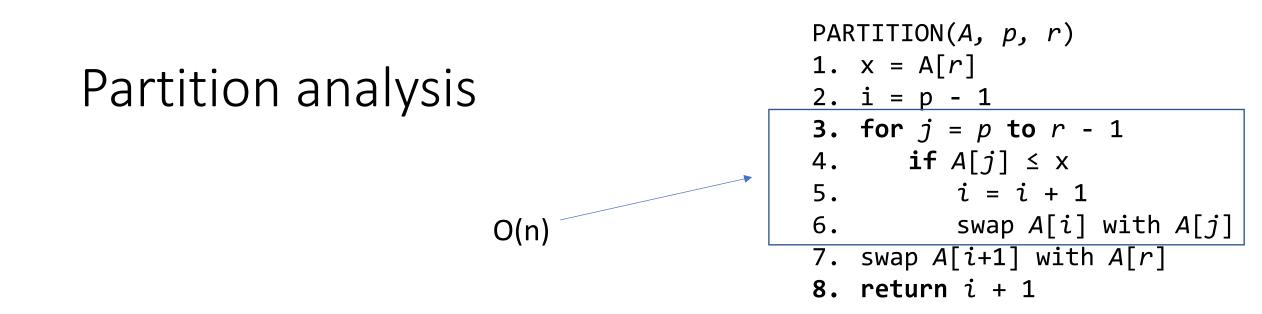
4. if A[j] \le x

5. i = i + 1

6. swap A[i] with A[j]

7. swap A[i+1] with A[r]

8. return i + 1
```



The for loop body (starts line 3) executes  $r-1-p = \Theta(n)$  times.

Why? In the worst case, every time the body of the **if** is executed, it takes constant time, or O(1). Lines 1, 2, and 7 are also constant time. However, this is the same running time if the array is already sorted. Thus the running time is  $\Theta(n)$ .

## Overview of quicksort analysis

The running time of quicksort depends on the partitioning of the subarrays:

- If the subarrays are balanced, then quicksort can run as fast as mergesort, Θ(n·logn).
- If they are unbalanced, then quicksort can run as slowly as insertion sort,  $\Theta(n^2)$ .

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## Quicksort: worst case analysis

For the worst case, suppose that we were really unlucky, and the subarray partitions are maximally unbalanced.

Specifically, the pivot is always either the **largest or smallest** element in the array.

Then one subarray will have 0 elements, while the other will contain n-1 elements; that is, all element except the pivot (hence n-1).

The two quicksort recursive calls will be on subarrays of size = 0 and size = n-1.

```
QUICKSORT (A, p, r):

1 if p < r

2 q = PARTITION(A, p, r)

3 QUICKSORT(A, p, q-1)

4 QUICKSORT(A, q+1, r) 24
```

## Quicksort: worst case analysis

QUICKSORT (A, p, r): 1 if p < r 2 q = PARTITION(A, p, r) 3 QUICKSORT(A, p, q-1) 4 QUICKSORT(A, q+1, r)

The time for partitioning is  $\Theta(n)$ .

A recursive call on the empty subarray just returns, so  $T(0) = \Theta(1)$ .

A recursive call on the full subarray is T(n-1).

Recurrence for running time:

$$T(n) = T(n-1) + T(0) + \Theta(n)$$
$$= T(n-1) + \Theta(n)$$

## Solve the recurrence



Lets state our function:

**Base case**: T(1) = 1

Thing to solve: T(n) = T(n-1) + n

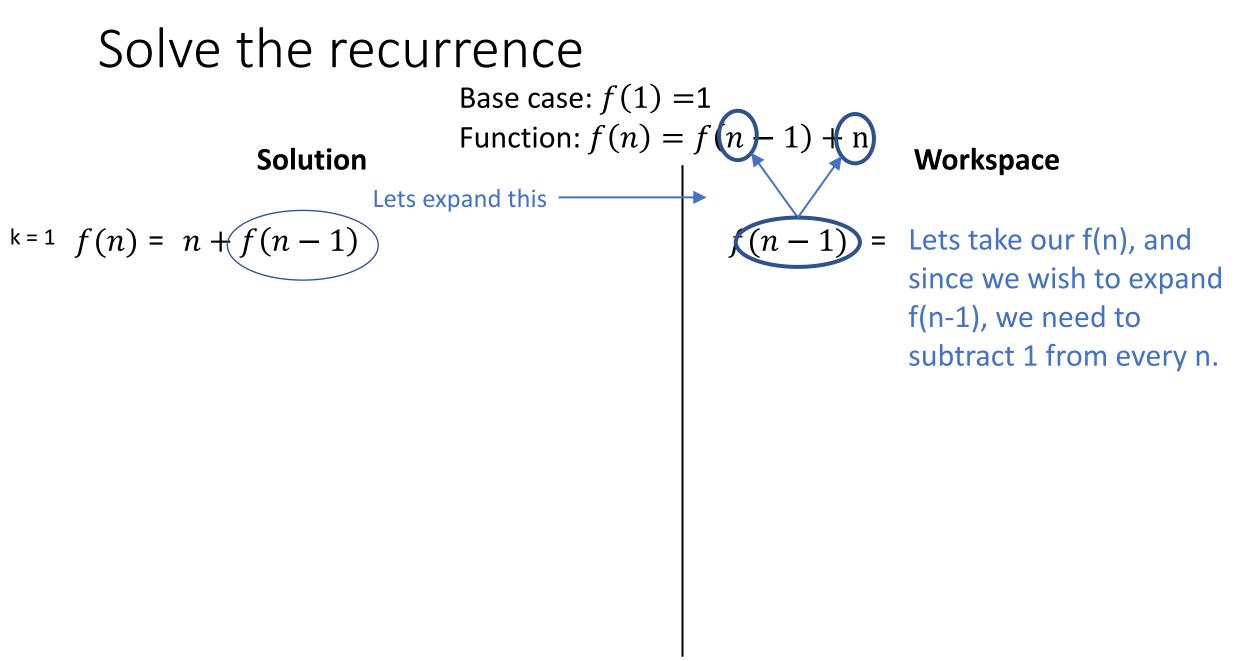
## Solve the recurrence

**Solution** 

Base case: f(1) = 1Function: f(n) = f(n - 1) + n

#### Workspace

k=1 f(n) = n + f(n-1)



## Solve the recurrence

**Solution** 

Base case: f(1) = 1Function: f(n) = f(n - 1) + n

k=1 f(n) = n + f(n-1)

f(n-1) = f((n-1) - 1) + n - 1= f(n-2) + n - 1

Workspace

# Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + nWorkspace **Solution** f(n-1) = f((n-1)-1) + n - 1 $k=1 f(n) = n + f(n-1)^{2}$ = f(n-2) + n - 1Lets now plug our workspace f(n-1) expansion back into our solution side

#### Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + nWorkspace k=1 f(n) = n + f(n-1)f(n-1) = f((n-1) - 1) + n - 1

= 
$$n + [n - 1 + f(n - 2)]$$

f(n-1) = f((n-1) - 1) + n - 1= f(n-2) + n - 1

Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + nWorkspace **Solution** f(n-1) = f((n-1) - 1) + n - 1= f(n-2) + n - 1k=1 f(n) = n + f(n-1)= n + [n - 1 + f(n - 2)]= n + (n - 1) + f(n - 2)k = 2

Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + n**Solution Workspace** f(n-1) = f((n-1)-1) + n - 1k=1 f(n) = n + f(n-1)= f(n-2) + n - 1= n + [n - 1 + f(n - 2)]= n + (n - 1) + f(n - 2)→ f(n-2) = f((n-2) - 1) + n - 2k = 2 = f(n-3) + n - 2Lets expand this

Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + n**Workspace Solution** f(n-1) = f((n-1)-1) + n - 1k=1 f(n) = n + f(n-1)= f(n-2) + n - 1= n + [n - 1 + f(n - 2)]= n + (n - 1) + f(n - 2)f(n-2) = f((n-2)-1) + n - 2k = 2 = f(n-3) + n - 2Lets now plug our workspace f(n-2) expansion back into our solution side

Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + n**Workspace Solution** f(n-1) = f((n-1)-1) + n - 1k=1 f(n) = n + f(n-1)= f(n-2) + n - 1= n + [n - 1 + f(n - 2)]f(n-2) = f((n-2)-1) + n - 2= n + (n - 1) + f(n - 2)k = 2 = f(n-3) + n - 2= n + (n - 1) + [(n - 2) + f(n - 3)]k = 3 = n + (n - 1) + (n - 2) + f(n - 3)

Solve the recurrence  
Base case: 
$$f(1) = 1$$
  
Function:  $f(n) = f(n-1) + n$   
Workspace  
 $f(n-1) = f((n-1) - 1) + n - 1$   
 $= n + [n - 1 + f(n - 2)]$   
 $= n + (n - 1) + f(n - 2)$   
 $= n + (n - 1) + [(n - 2) + f(n - 3)]$   
 $= n + (n - 1) + (n - 2) + f(n - 3)]$   
 $= n + (n - 1) + (n - 2) + f(n - 3)$   
Lets expand this  
 $f(n-1) = f((n-1) - 1) + n - 1$   
 $= f(n-2) + n - 1$   
 $f(n-2) = f((n-2) - 1) + n - 2$   
 $= f(n-3) + n - 2$   
 $f(n-3) = f((n-3) - 1) + n - 3$ 

Solve the recurrence  
Base case: 
$$f(1) = 1$$
  
Function:  $f(n) = f(n-1) + n$   
Solution  
 $k=1 \ f(n) = n + f(n-1)$   
 $= n + [n-1 + f(n-2)]$   
 $k=2 = n + (n-1) + f(n-2)$   
 $= n + (n-1) + [(n-2) + f(n-3)]$   
 $k=3 = n + (n-1) + (n-2) + f(n-3)]$   
 $k=3 = n + (n-1) + (n-2) + f(n-3)$   
 $k=3 = n + (n-1) + (n-2) + f(n-3)$ 

Lets now plug our workspace f(n-3) expansion back into our solution side

Solve the recurrence Base case: f(1) = 1Function: f(n) = f(n-1) + n**Solution Workspace** f(n-1) = f((n-1)-1) + n - 1k=1 f(n) = n + f(n-1)= f(n-2) + n - 1= n + [n - 1 + f(n - 2)]f(n-2) = f((n-2)-1) + n - 2= n + (n - 1) + f(n - 2)k = 2 = n + (n - 1) + [(n - 2) + f(n - 3)]= f(n-3) + n - 2f(n-3) = f((n-3)-1) + n - 3k = 3 = n + (n - 1) + (n - 2) + f(n - 3)f(n-4) + n - 3= n + (n - 1) + (n - 2)+ [(n-3) + f(n-4)]= n + (n - 1) + (n - 2) + (n - 3)k = 4 + f(n-4)

$$f(n) = n + f(n - 1)$$
  
=  $n + (n - 1) + f(n - 2)$   
=  $n + (n - 1) + (n - 2) + f(n - 3)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + f(n - 4)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + \dots + 3 + 2 + f(1)$ 

$$f(n) = n + f(n - 1)$$
  
=  $n + (n - 1) + f(n - 2)$   
=  $n + (n - 1) + (n - 2) + f(n - 3)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + f(n - 4) = 0$   
=  $n + (n - 1) + (n - 2) + (n - 3) + \dots + 3 + 2 + f(1)$  With 1 element subarray, cost is 0

$$f(n) = n + f(n - 1)$$
  
=  $n + (n - 1) + f(n - 2)$   
=  $n + (n - 1) + (n - 2) + f(n - 3)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + f(n - 4)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + \dots + 3 + 2 + 0$   
=  $(n + (n - 1) + (n - 2) + (n - 3) + \dots + 3 + 2 + 1) - 1$   
Lets rewrite that 0 as 1 - 1

$$f(n) = n + f(n - 1)$$
  
=  $n + (n - 1) + f(n - 2)$   
=  $n + (n - 1) + (n - 2) + f(n - 3)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + f(n - 4)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + \dots + 3 + 2 + 0$   
=  $(n + (n - 1) + (n - 2) + (n - 3) + \dots + 3 + 2 + 1) - 1$ 



Hmm, doesn't this look like the sum of an arithmetic series?

$$f(n) = n + f(n - 1)$$
  
=  $n + (n - 1) + f(n - 2)$   
=  $n + (n - 1) + (n - 2) + f(n - 3)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + f(n - 4)$   
=  $n + (n - 1) + (n - 2) + (n - 3) + ... + 3 + 2 + 0$   
=  $(n + (n - 1) + (n - 2) + (n - 3) + ... + 3 + 2 + 1) - 1$   
=  $n(n + 1)/2 - 1$   
Replaced with the closed-form solution

### Worst case

So in the worst case Quicksort is  $O(n^2)$ . That's not good.

The worst case occurs exactly when Quicksort is run on an already sorted array. But insertion sort takes only O(n) in this case.

We can avoid the worst case by choosing a better pivot. The most common choices are: choose a random element as the pivot, or choose the median of 3 elements (e.g. first, middle, last) as the pivot.

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## Quicksort: best case analysis

The best case occurs when partition produces two subarrays, each of which is no more than n/2. That is, completely balanced subarrays every time. Our function here is:

**Base case:** T(1) = 1

**Thing to solve**: T(n) = T(n/2) + T(n/2)

This is the same equation as mergesort (phew!) In the best case, Quicksort is  $O(n \log_2 n + n)$ 

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## Balanced partitioning

That's the worst case and best case. But what about the **average case**?

The average-case running time of quicksort is much closer to the best case than to the worst case.

Consider a pivot that always gives us a 9-to-1 (90%/10%) split of the data (hmm, that sounds bad...). In that case, the function is:

$$T(n) = T(9n/10) + T(n/10) + \theta(n)$$

This is tricky to solve with the substitution method, so we will use a **recursion tree** instead.

### Recursion tree

We use a recursion tree to help solve a recurrence equation.

This visual technique is analogous to using the substitution method, as the basic idea is the same:

#### Intuition

- 1. Keep expanding the recursive sub-calls until we reach a base case.
- 2. Identify the depth of our recursion tree
- 3. Identify the number of operations done at each level
- 4. Sum up the work across all levels

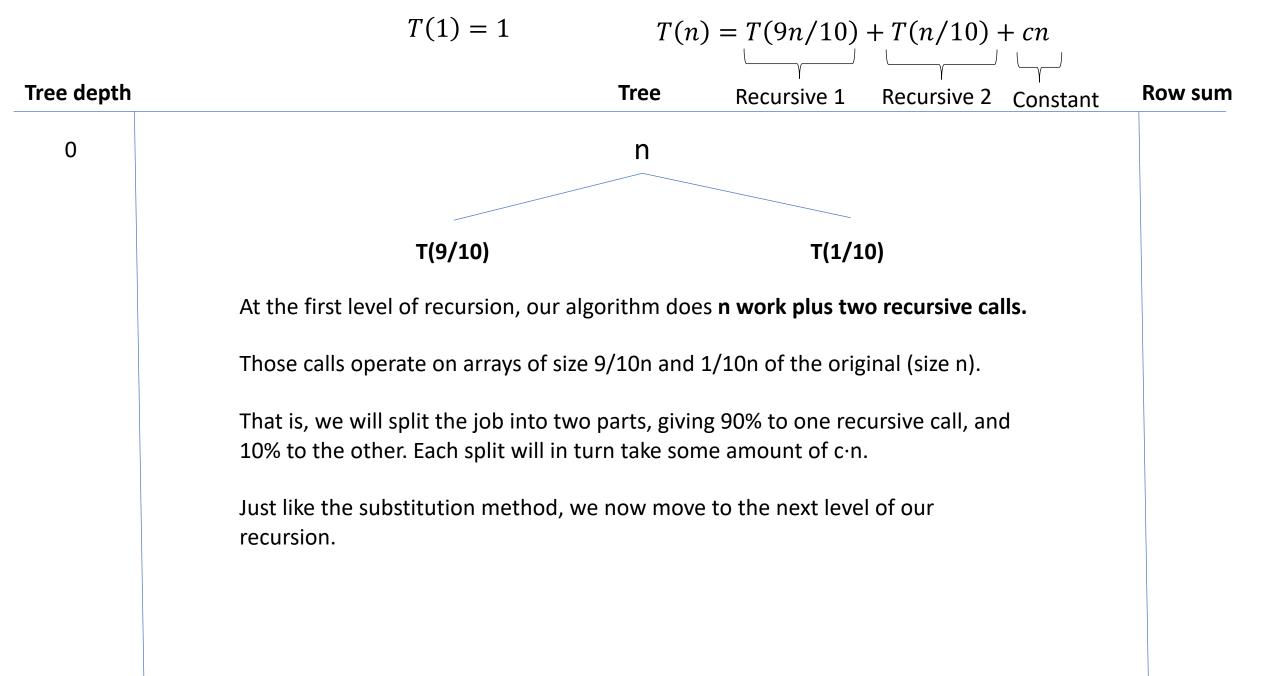
## Our equations

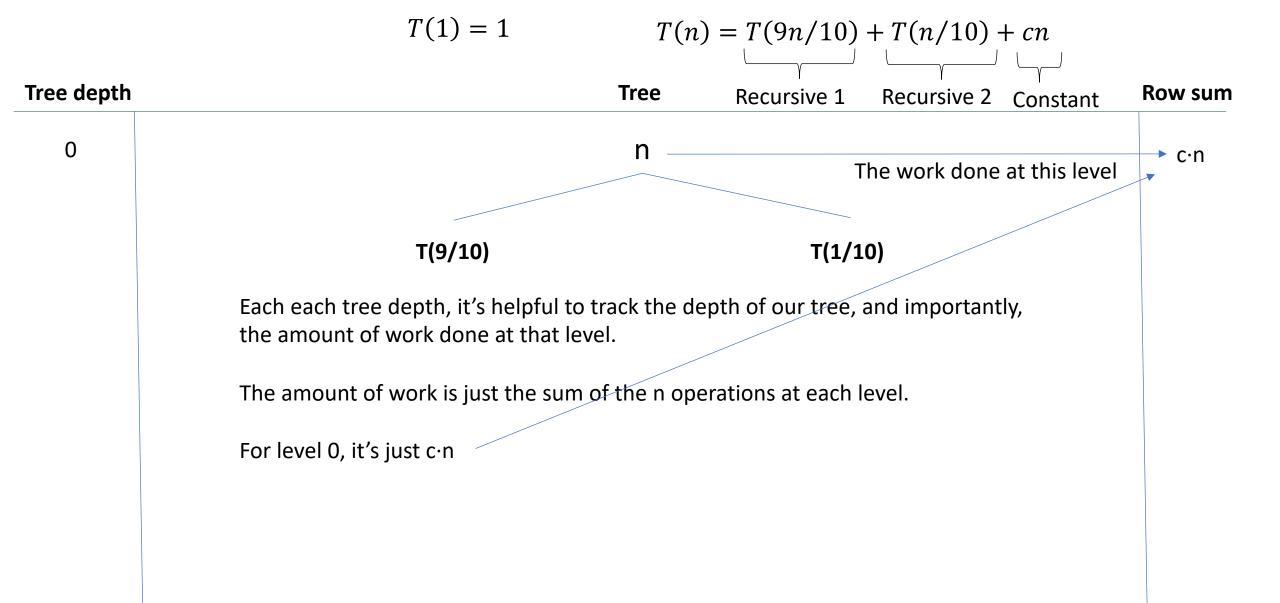


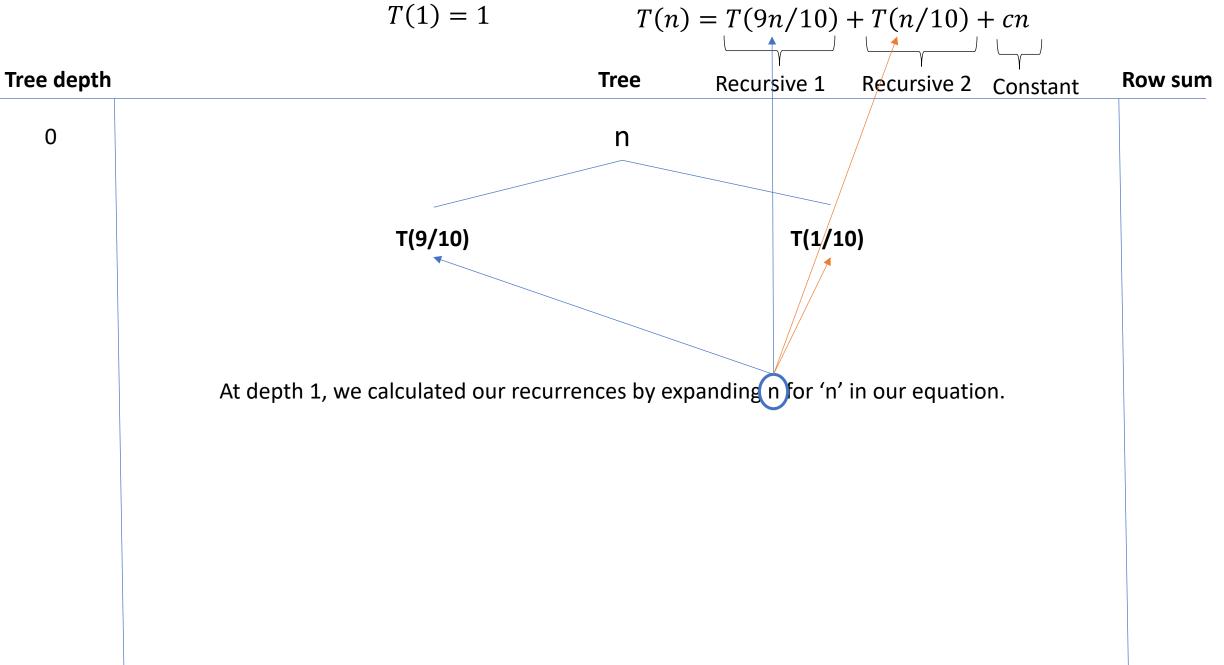
Lets start by restating our equations:

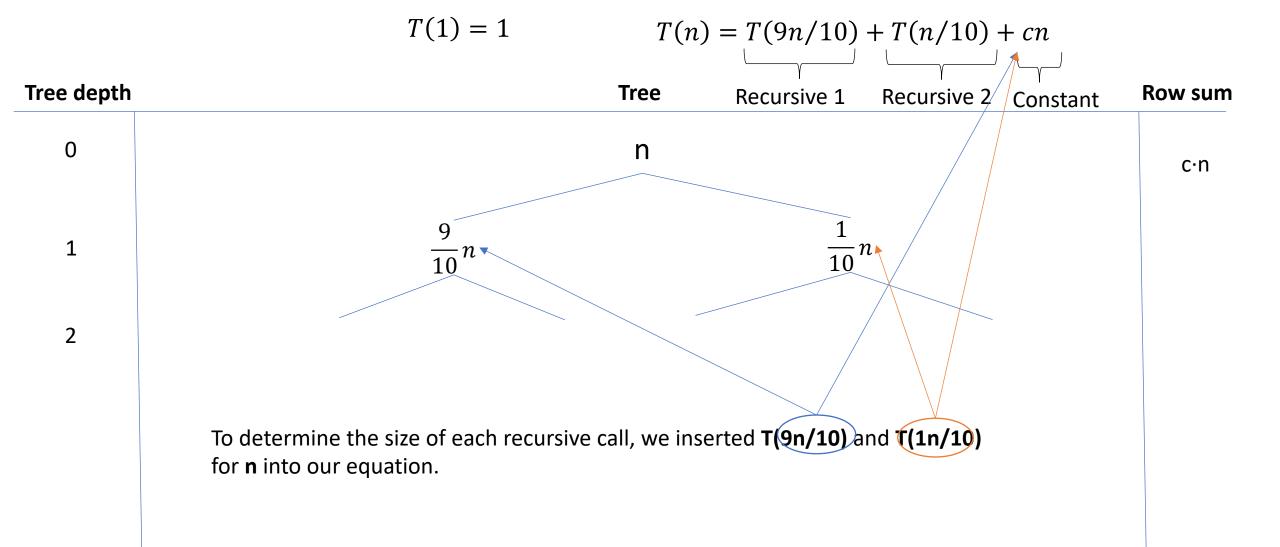
Base case: T(1) = 1Recurrence:  $T(n) = T(9n/10) + T(n/10) + c \cdot n$ 

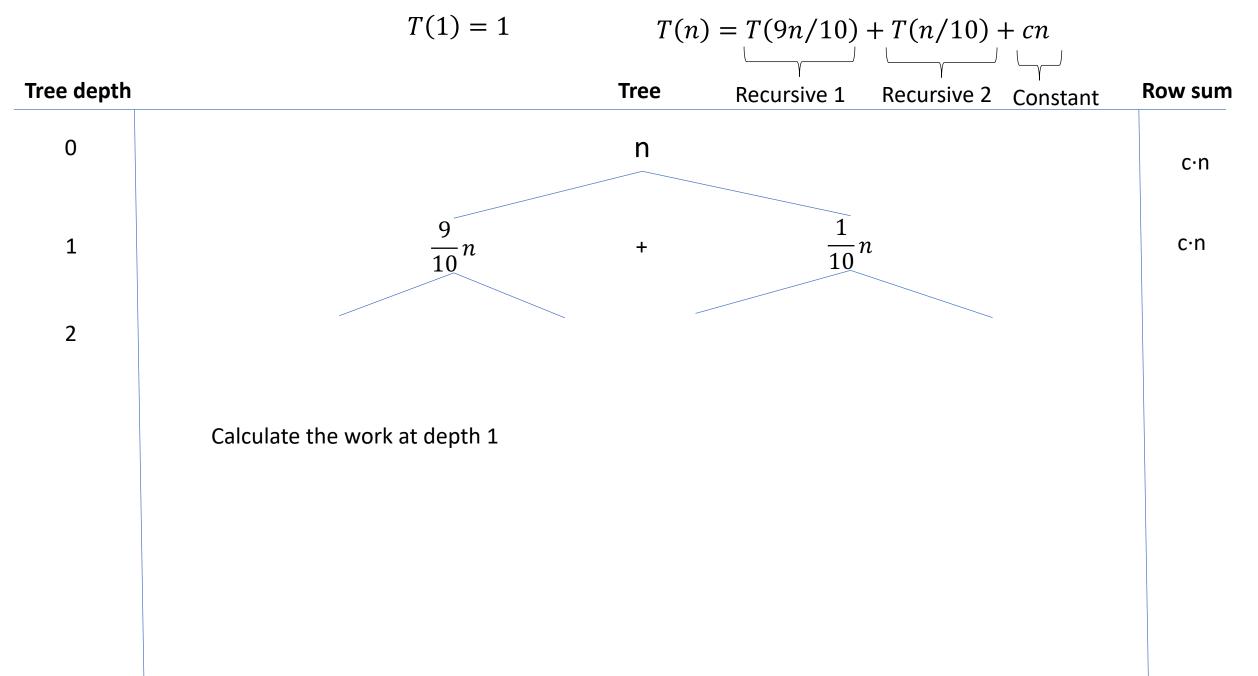
Here we've explicitly included the constant hidden in our  $\Theta(n)$  term. As you will see, this is important in a recursion tree.

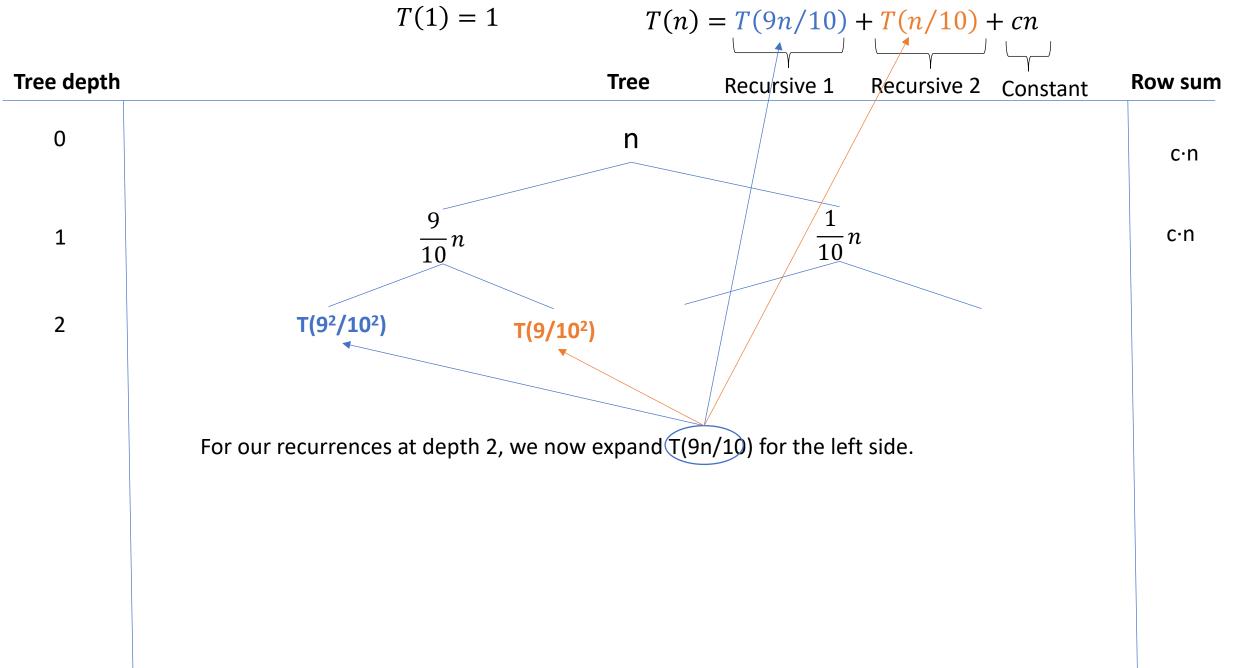


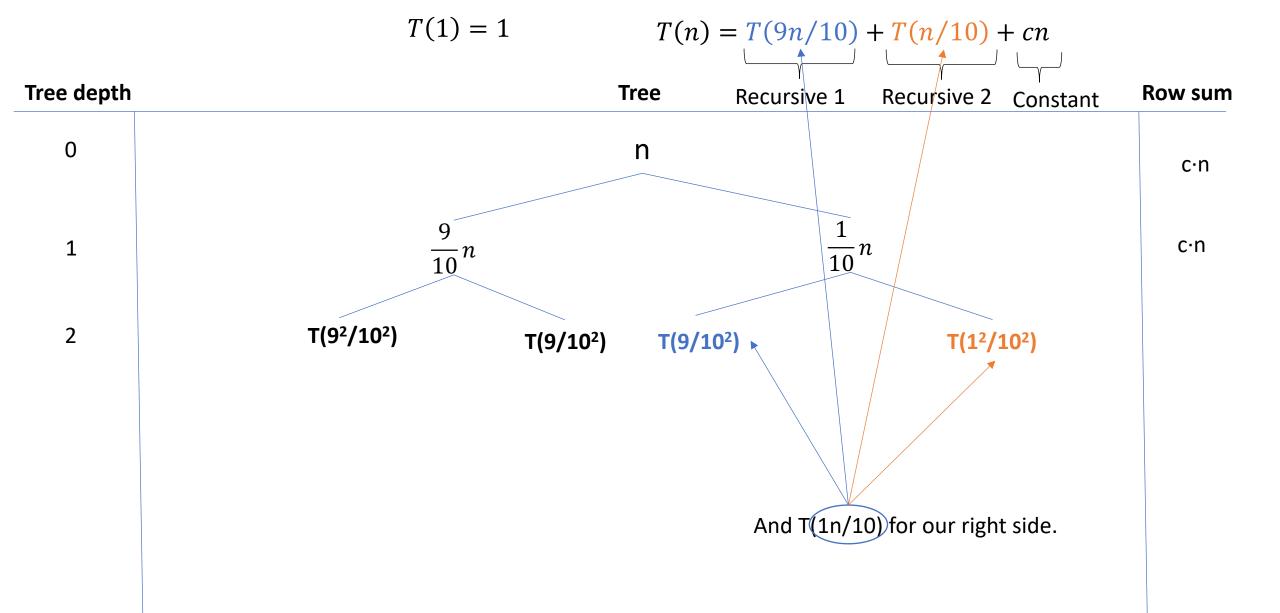


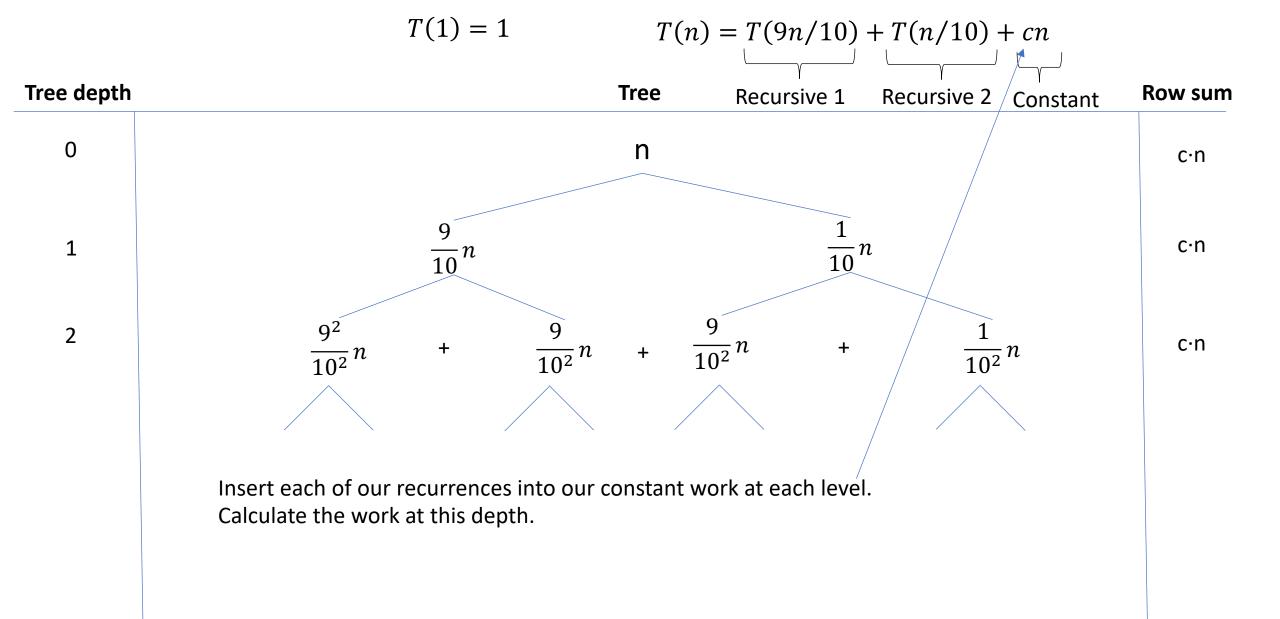


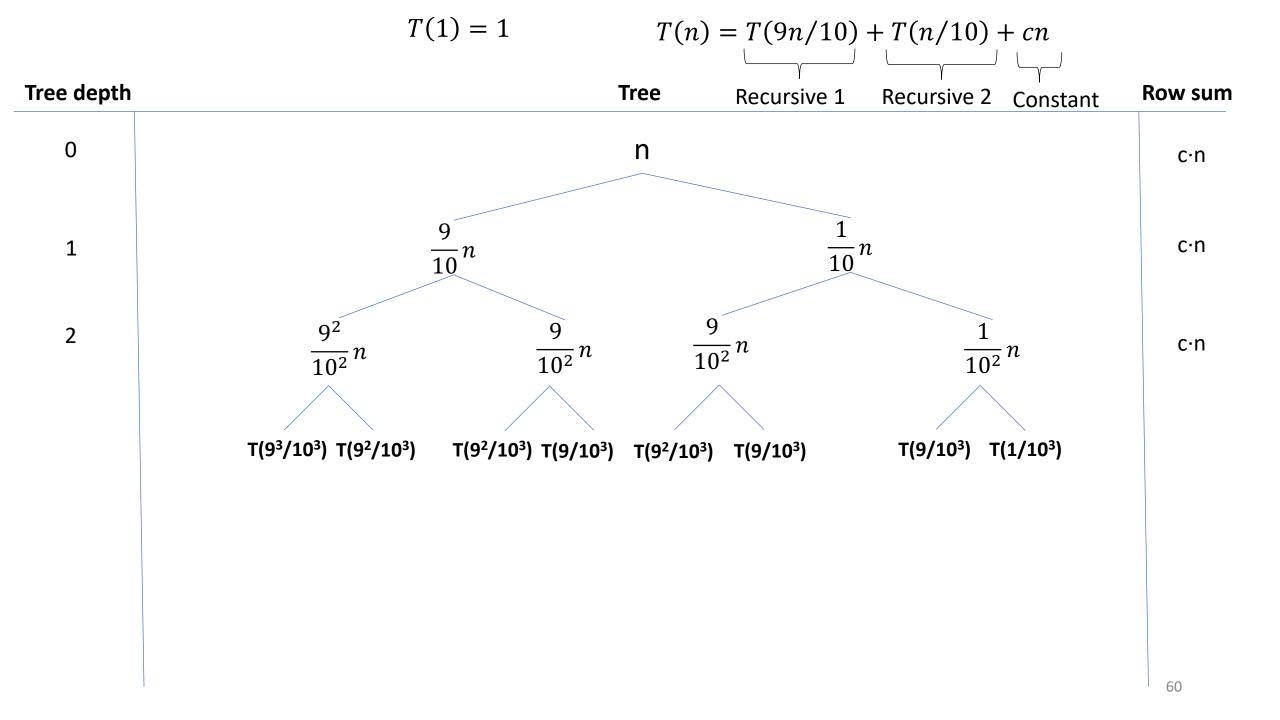


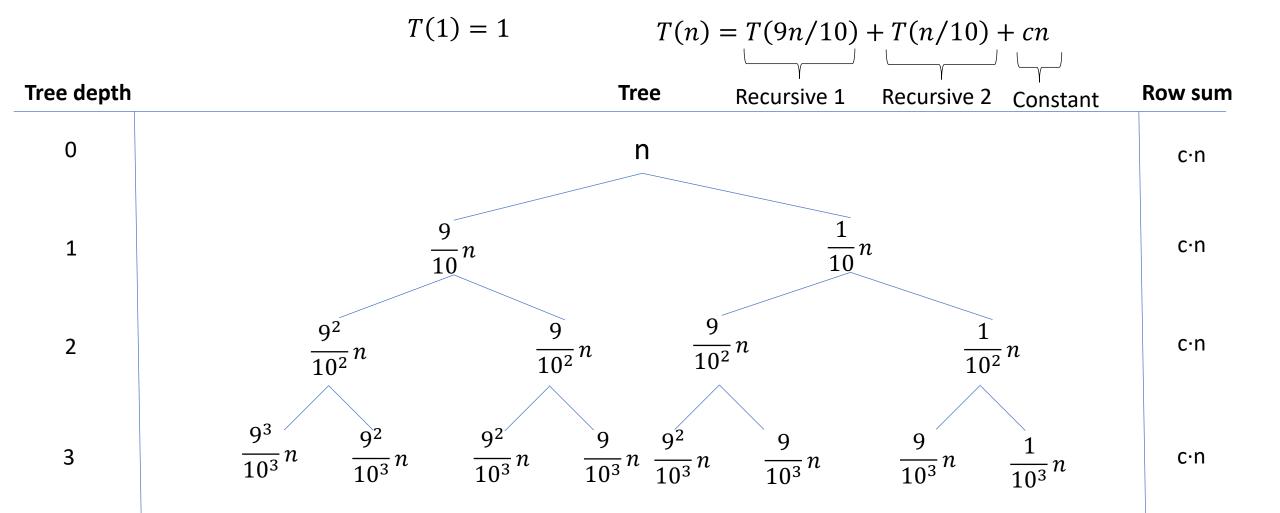




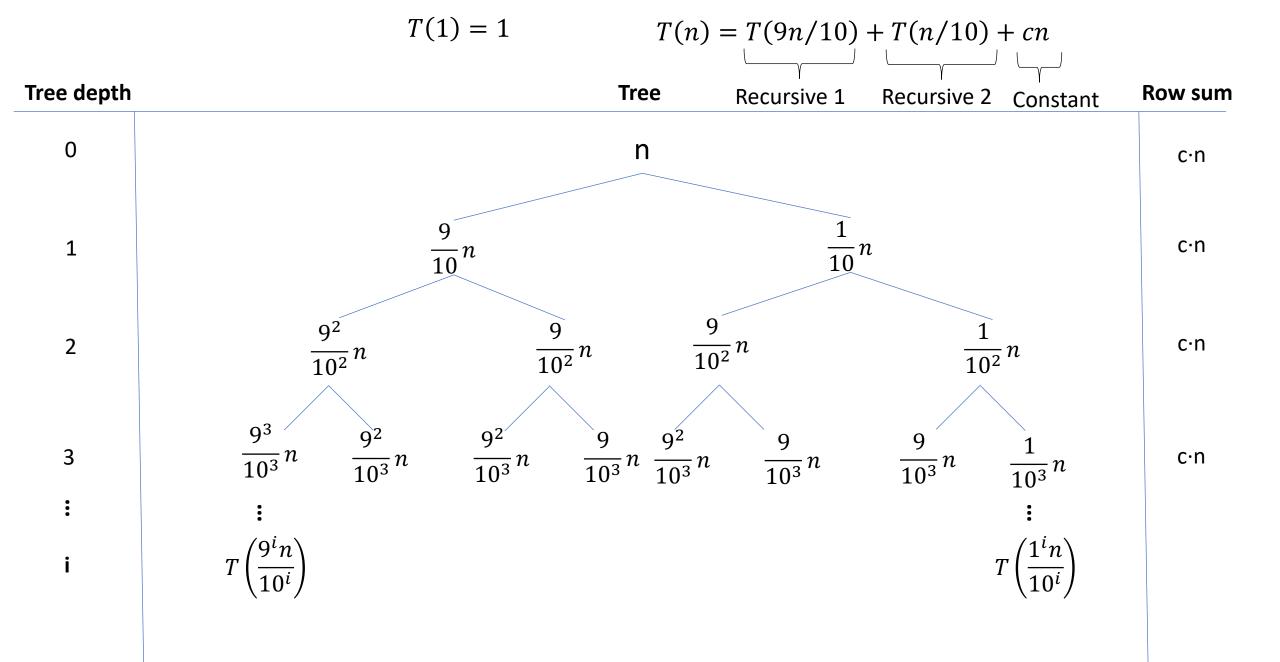


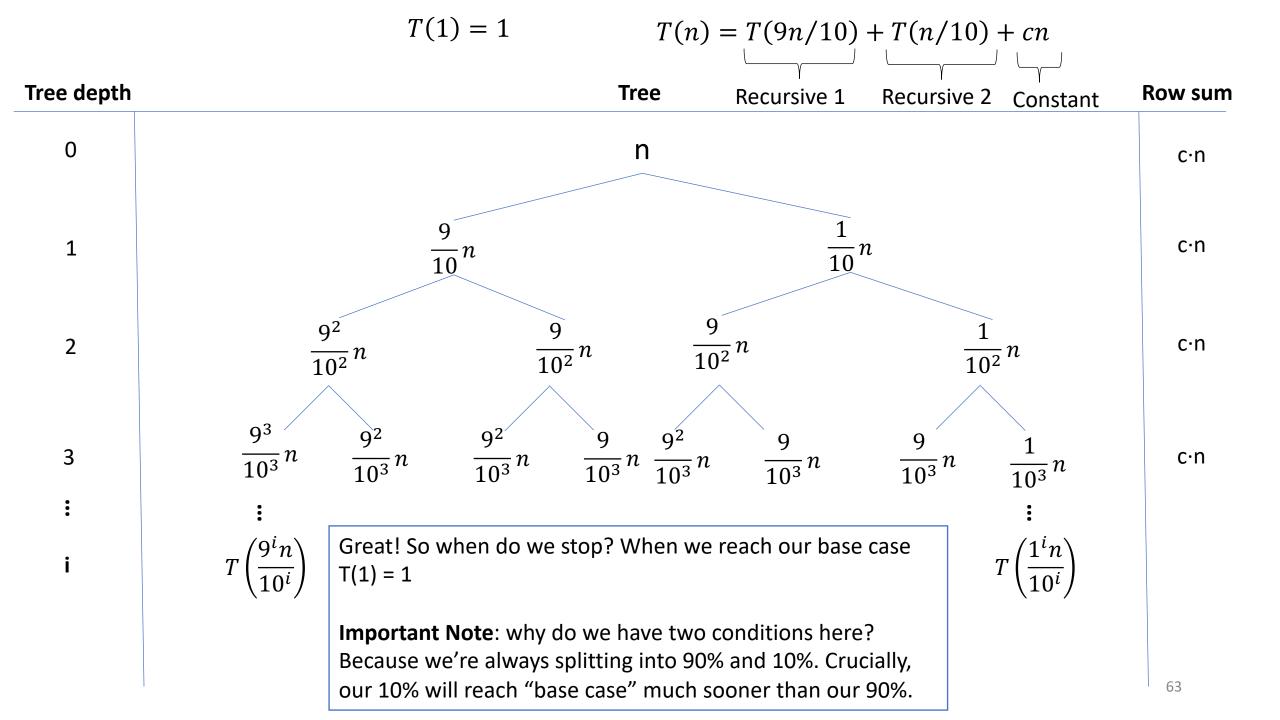


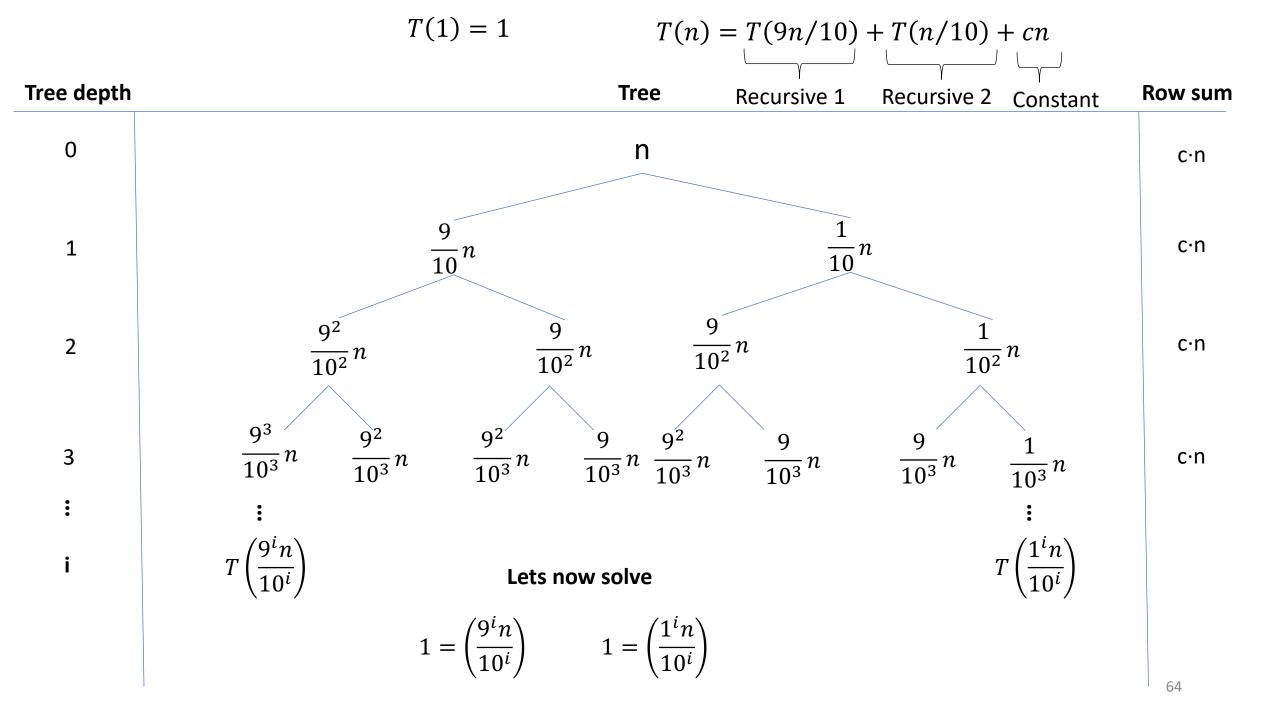


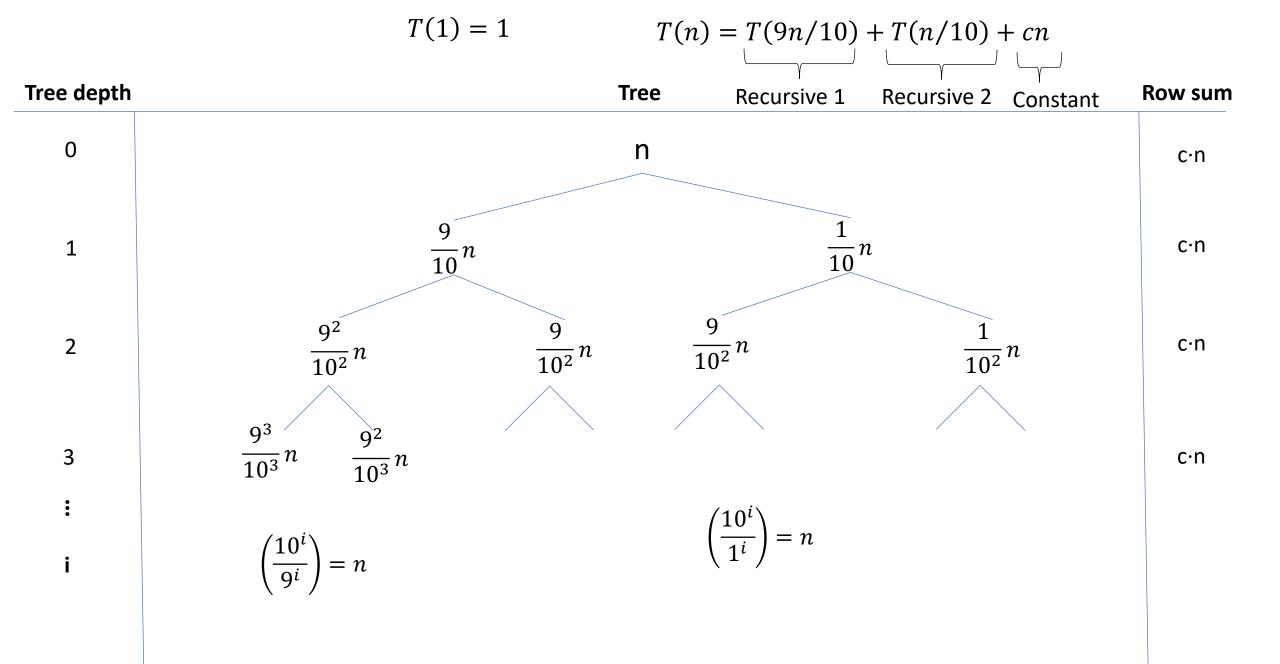


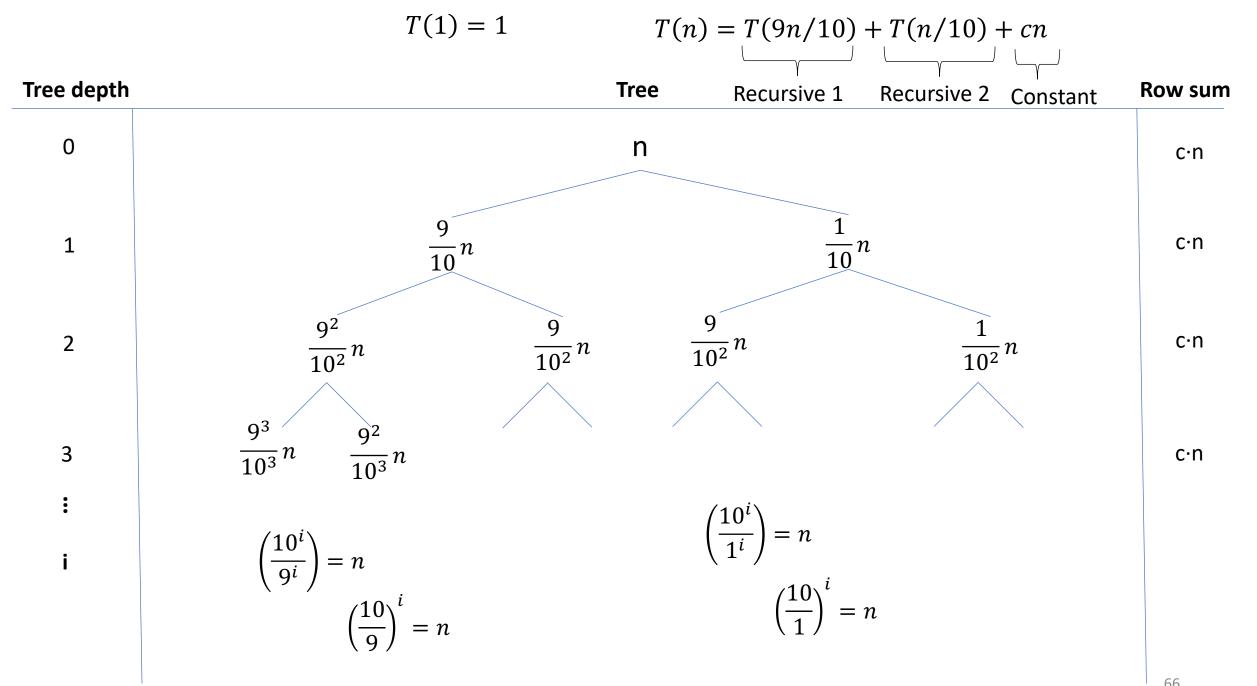
We've now expanded 3 levels of our recursion tree. This allows us to see a pattern forming.

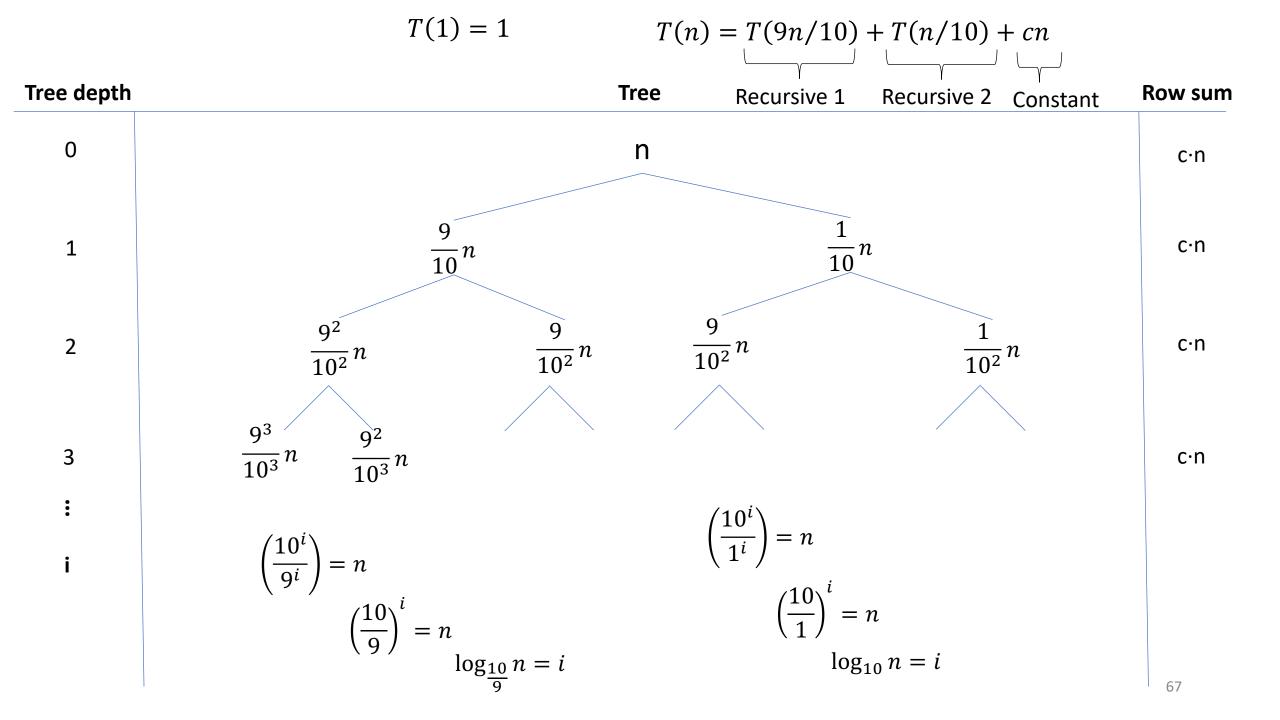


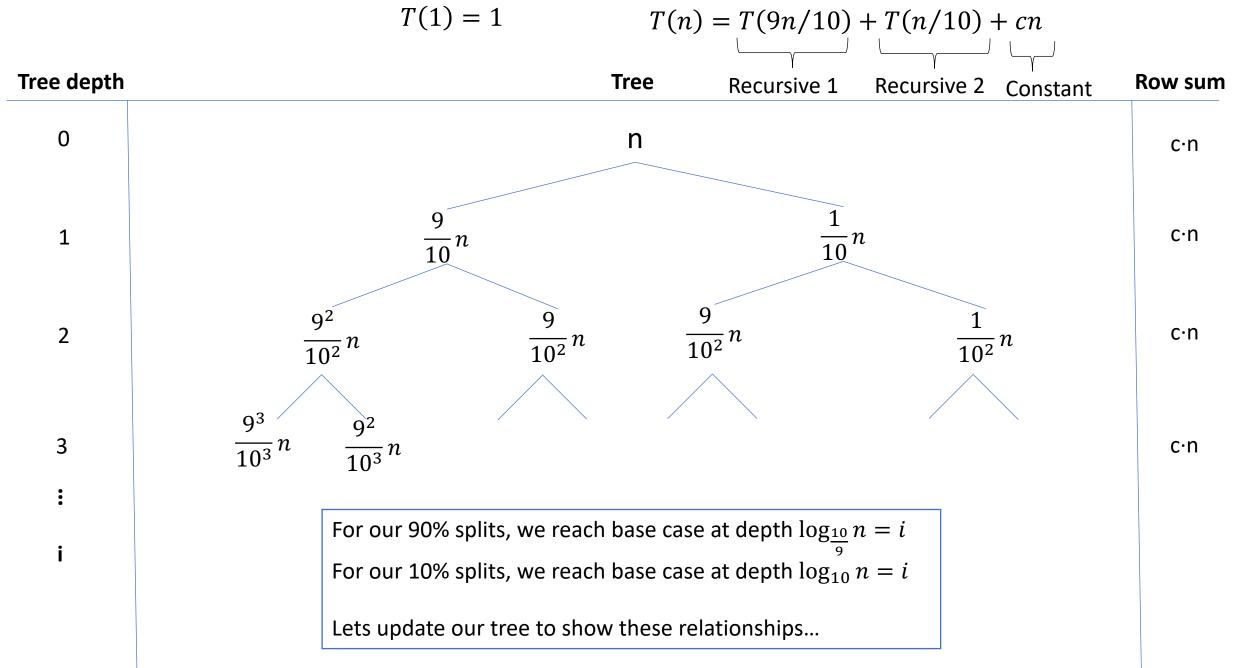


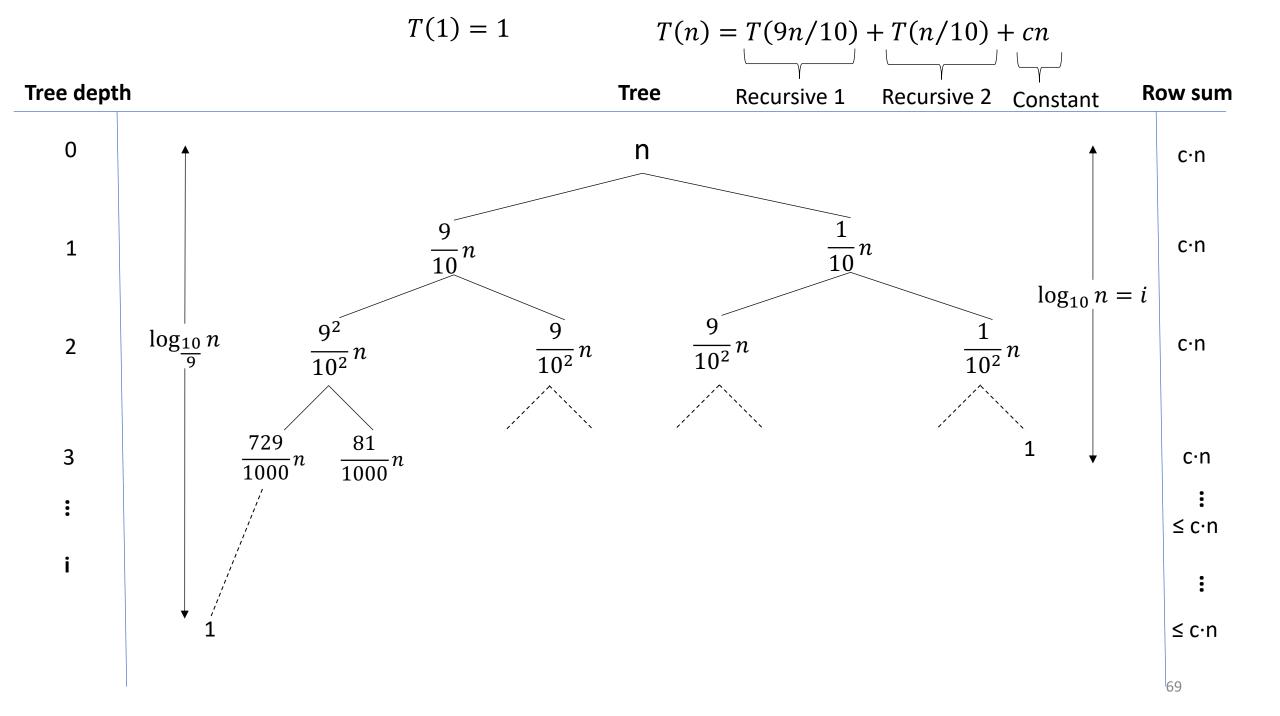


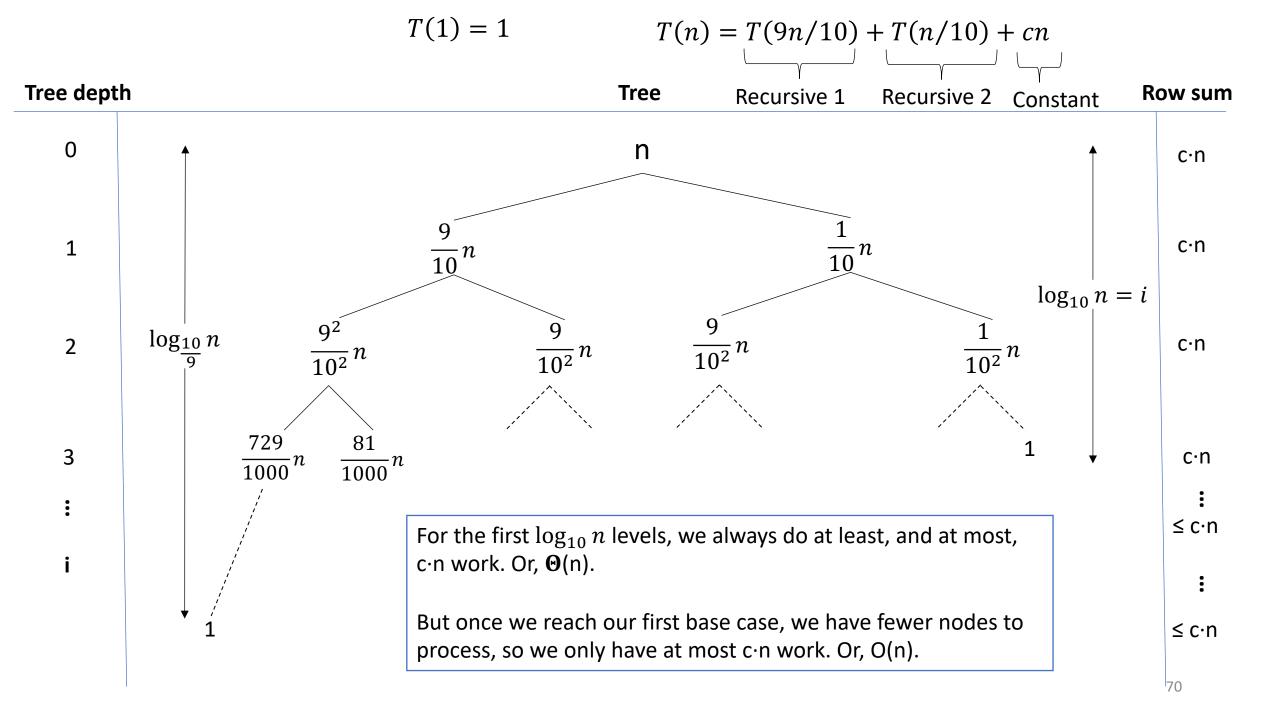


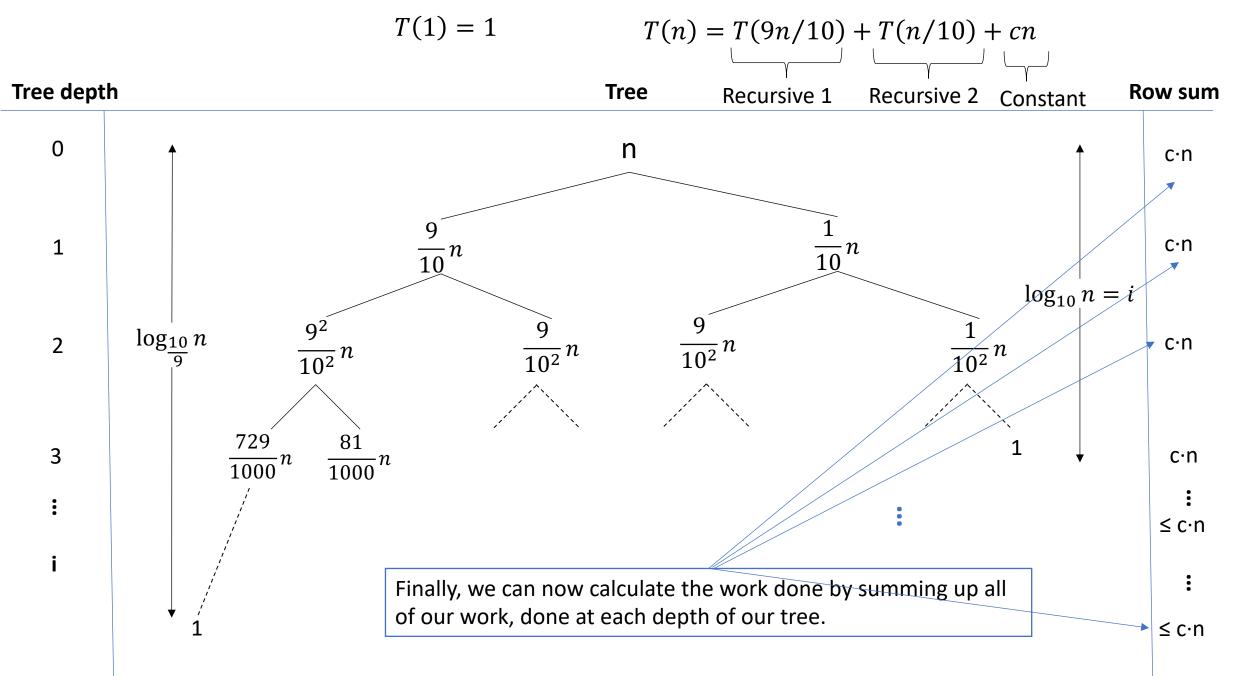












## Calculating our total work

We now sum all the work done at each tree depth to get the total cost of quicksort average case.

Since we have  $\log_{\frac{10}{9}} n$  levels, each doing 'n' work, we have:  $O\left(n \times \log_{\frac{10}{9}} n\right)$  work.

But the base of our log is messy for asymptotic notation. Let use the following mathematical fact:  $\log_a n = \frac{\log_b n}{\log_b a}$ 

## Calculating our total work



Using this fact, our equation can be rewritten as:

$$\log_{\frac{10}{9}} n = \frac{\log_2 n}{\log_2 \frac{10}{9}} = c \cdot \log_2 n$$

Since  $1/\log_2 \frac{10}{9}$  is a constant, we replace it with c. As long as this value is a constant, the log doesn't matter in asymptotic notation.

Again, we do 'n' work per level, so rewriting  $O\left(n \times \log_{\frac{10}{9}} n\right)$  we get:

 $T(n) = O(n\log_2 n)$ 

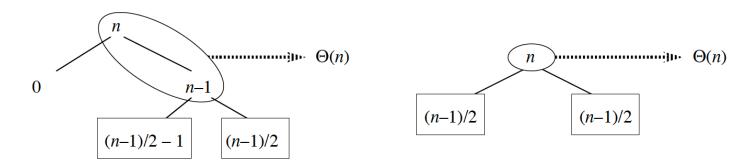
## Intuition for average case

Splits in the recursion tree will not always be constant.

What about alternating a perfect split with a bad split?

In this case, the tree is at most twice as high as for all perfect splits, so still O(n log n + n)

Both figures result in O(n  $\log_2 n$ ) time, though the constant for the figure on the left is higher than that of the figure on the right.



## Suggested reading

Chapter 7 covers quicksort. Today's material is covered in sections 7.1 and 7.2, and are a "must read".

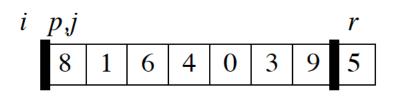
Recurrence trees<sup>[2]</sup> are covered in section 4.4.

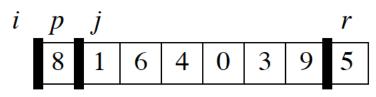
### References

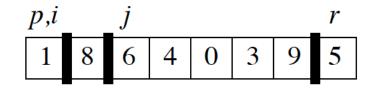
- The first author of the text has a <u>gentle introduction to quicksort</u> on Kahn academy.
- 2. Dr Bower's <u>video</u> of solving recurrence trees is also helpful.

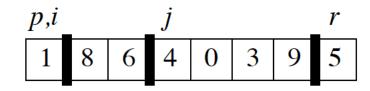
## Solutions

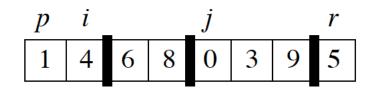
## Class challenge 1





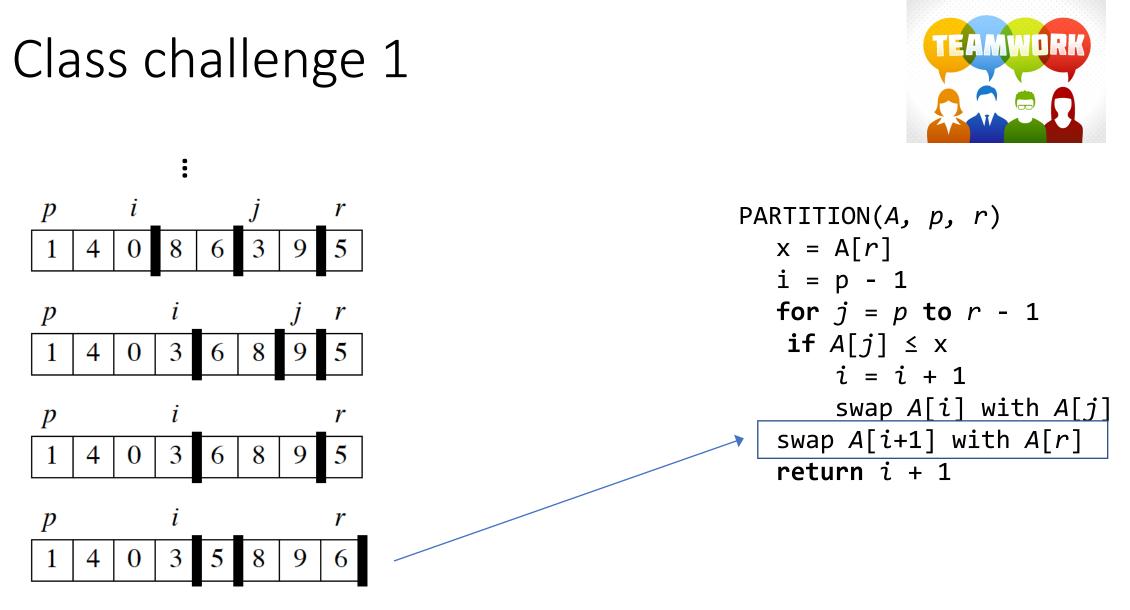








PARTITION(A, p, r) x = A[r] i = p - 1for j = p to r - 1if  $A[j] \le x$ i = i + 1swap A[i] with A[j]swap A[i+1] with A[r]return i + 1



For loop exits, no need for index j

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