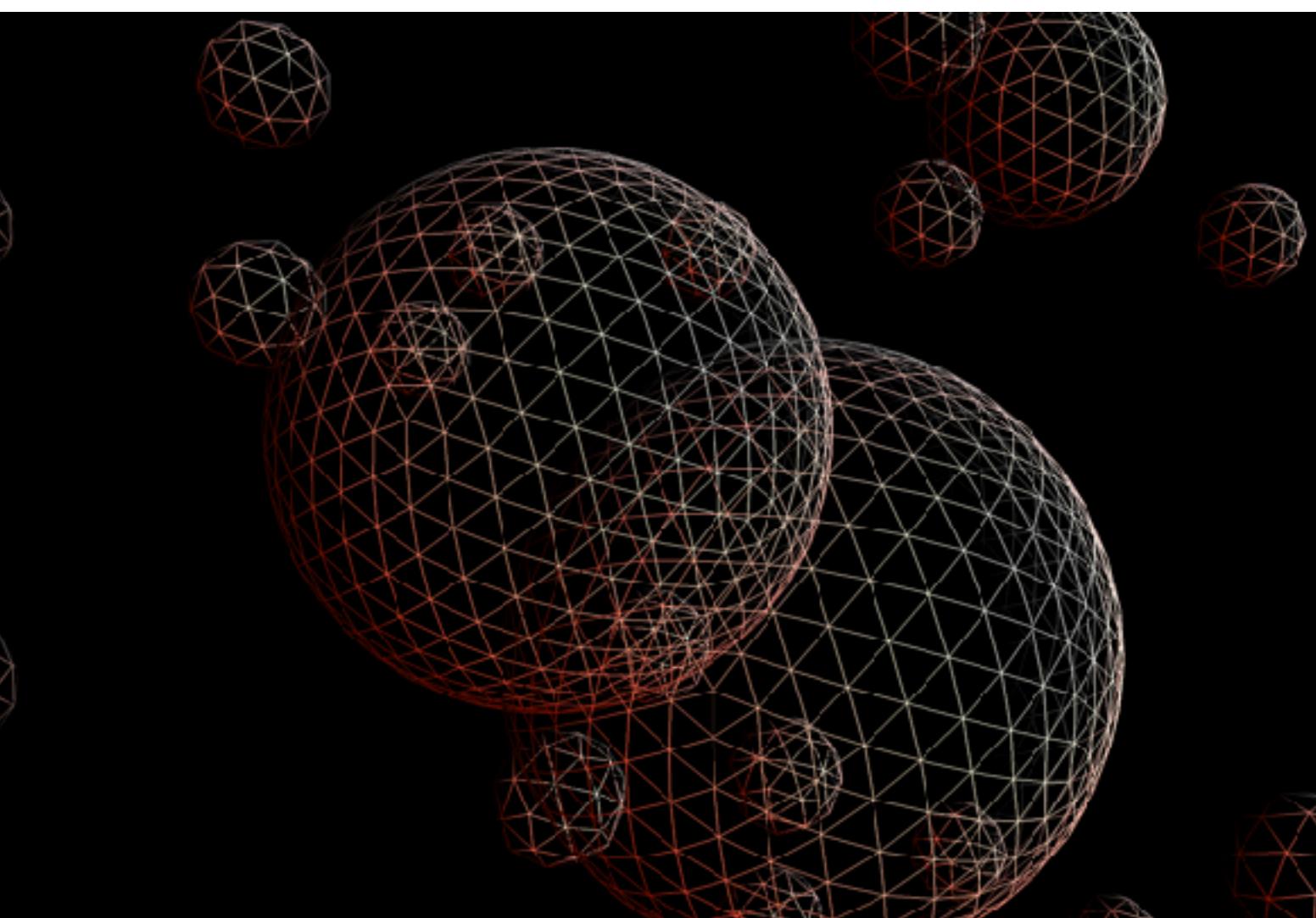
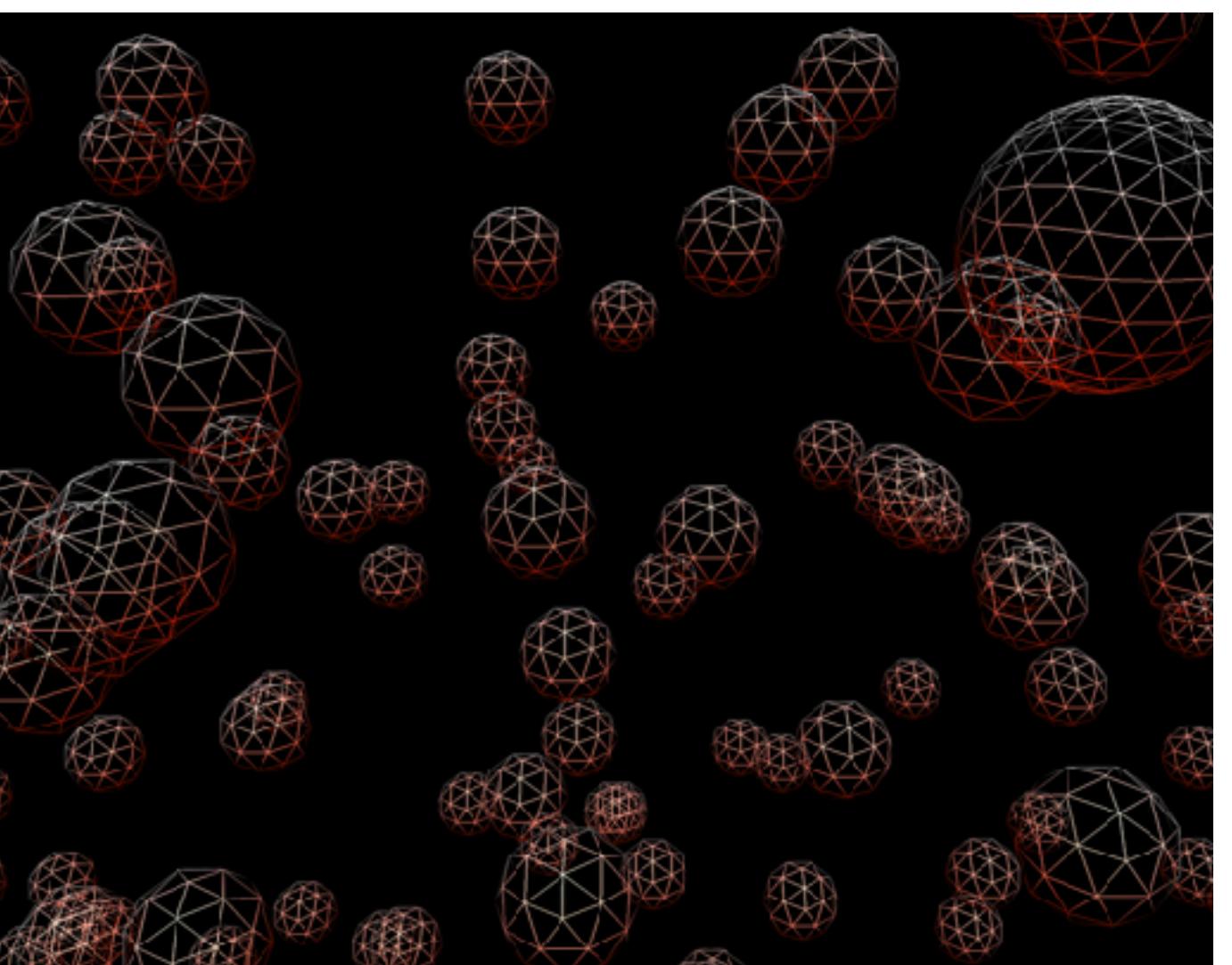
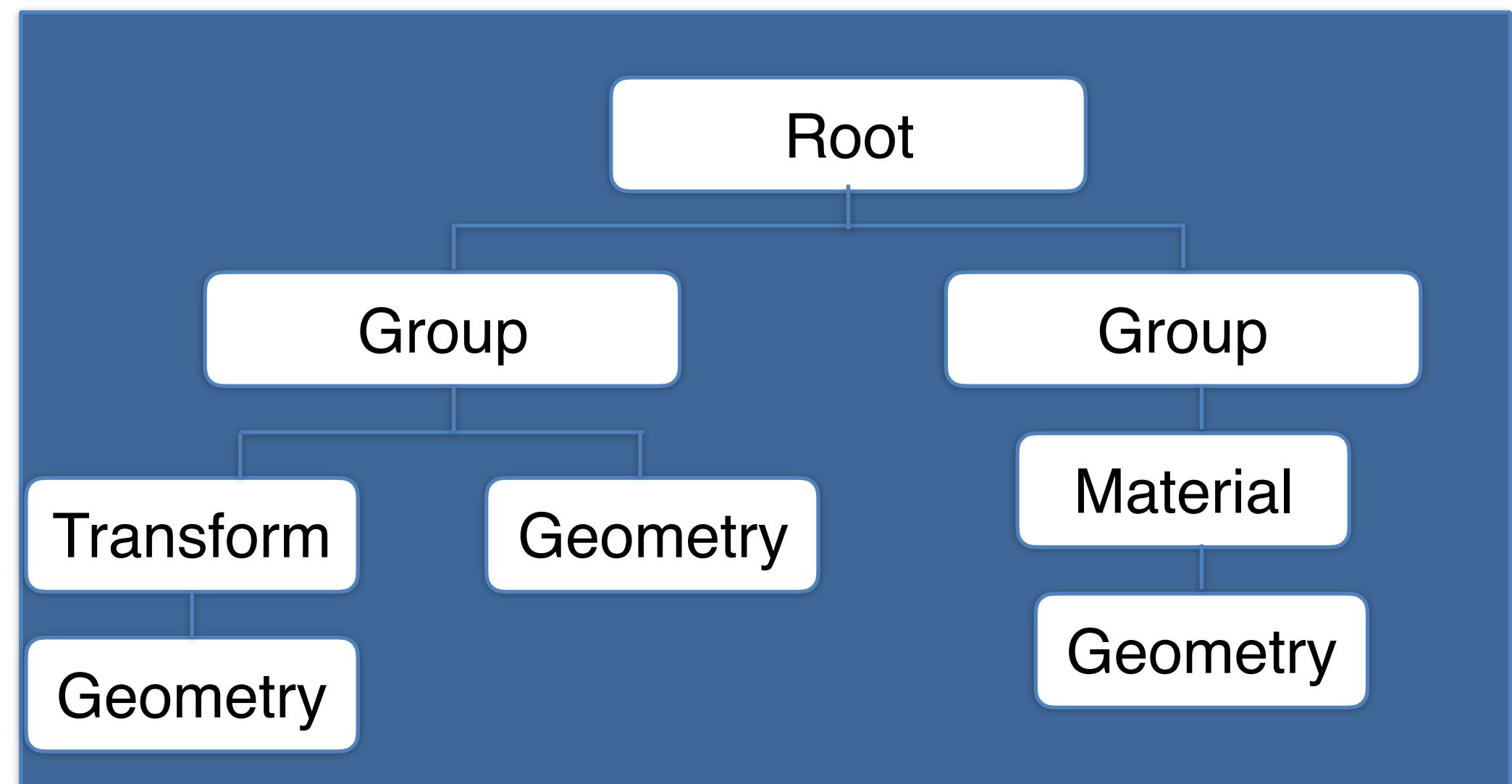


# COSC342: Computer Graphics

2017



Lecture 21

## SCENE GRAPHS

Stefanie Zollmann

# LAST TIME

WEBGL

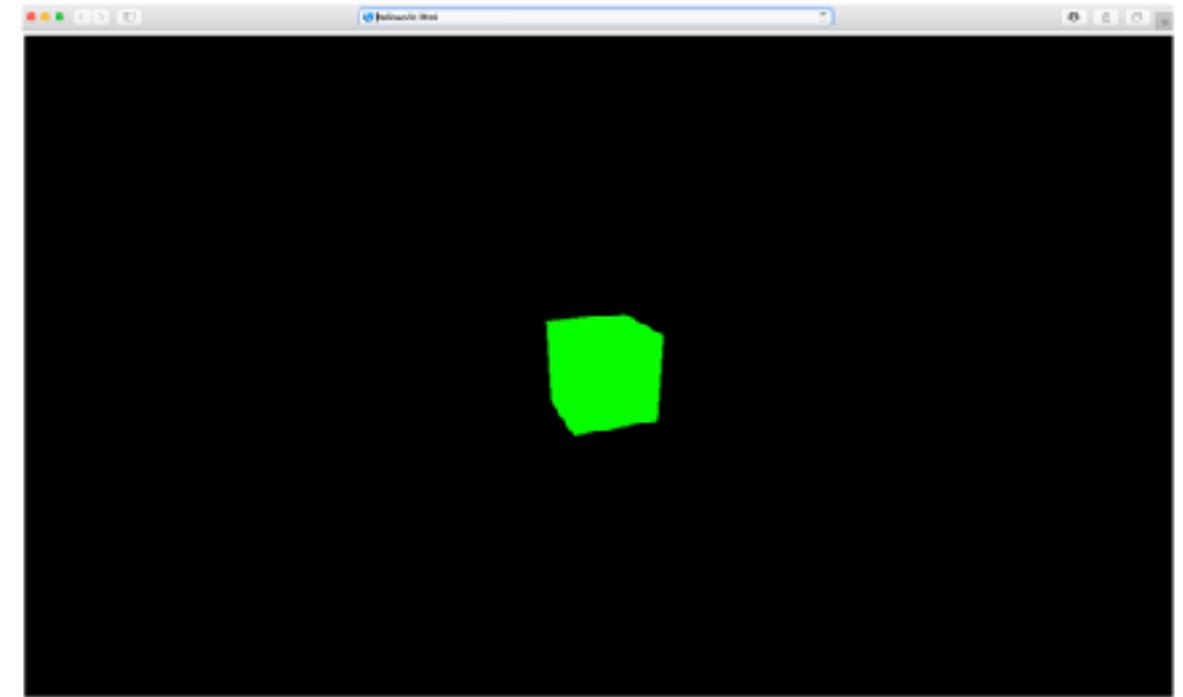


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COMPUTER GRAPHICS - WEBGL

THREE.JS

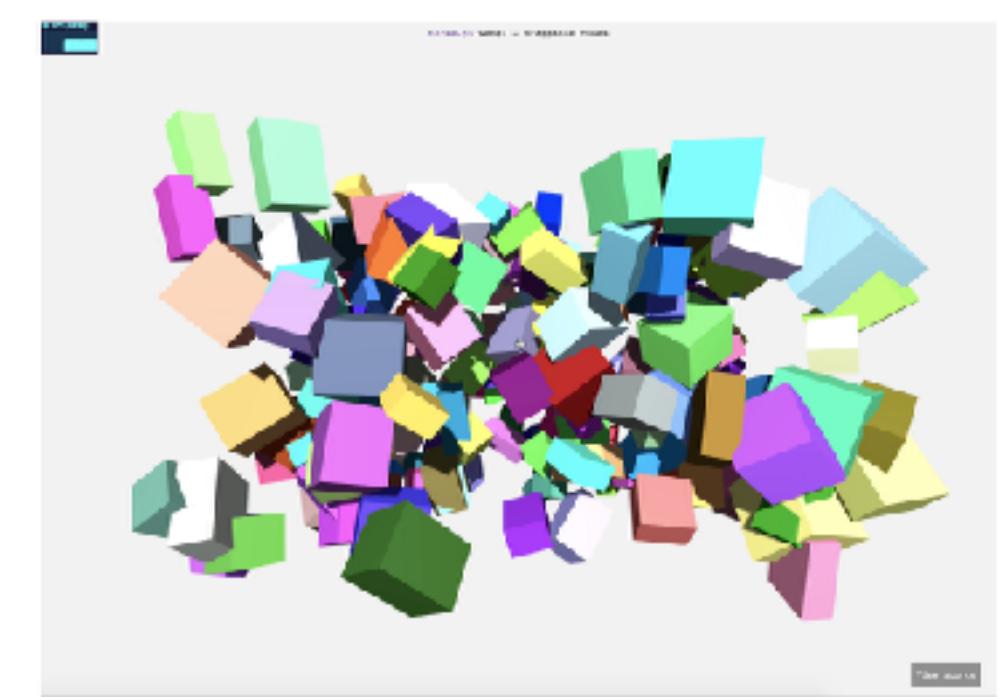


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COMPUTER GRAPHICS - WEBGL

INTERACTIVE DEMOS



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COMPUTER GRAPHICS - WEBGL

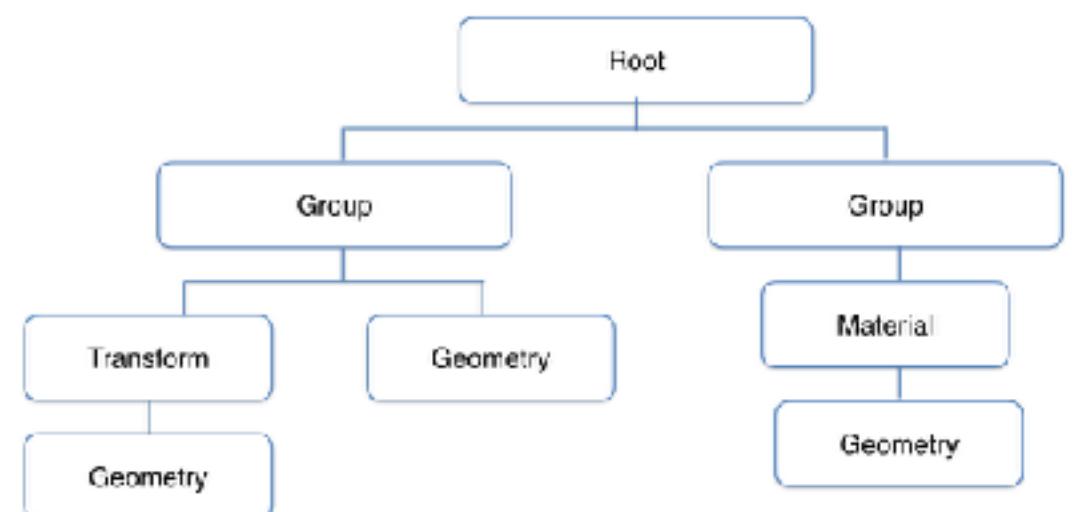
WEBGL

THREE.JS

INTERACTIVE DEMOS

# TODAY

## SCENEGRAPH



6

STEFANIE ZOLLMANN

COMPUTER GRAPHICS - SCENEGRAPHS

## SCENEGRAPH NODES

- Different types of nodes
  - Group Nodes
  - Transformation Nodes
  - Light Nodes
  - Others: Sound, fog, manipulators (animators), Collision,
  - Geometry nodes (leaf nodes)
    - Polygons, lines, points,
    - Material
    - Traversers

6

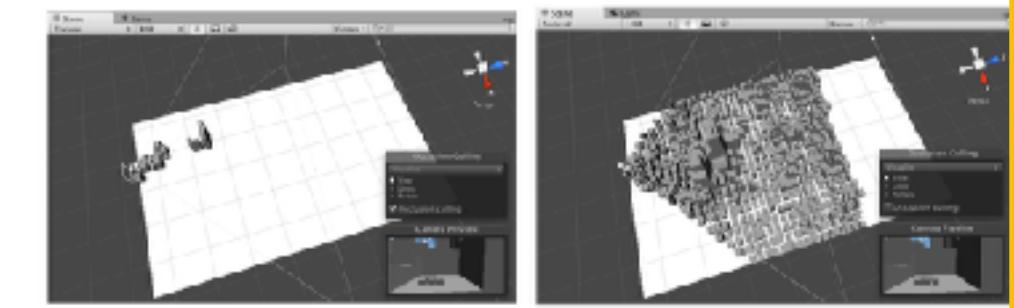
STEFANIE ZOLLMANN

COMPUTER GRAPHICS - SCENEGRAPHS

## PERFORMANCE OPTIMISATION

Visual impact comparisons and measurements				
Image				
Vertices	~6500	~2880	~1580	~670
Notes	Maximum detail for close-ups.			Minimum detail, vary for objects.

### Level-of-detail

<https://docs.unidb.com/4.0/Documentation/Manual/LevelOfDetailCulling.html>

7

STEFANIE ZOLLMANN

COMPUTER GRAPHICS - SCENEGRAPHS

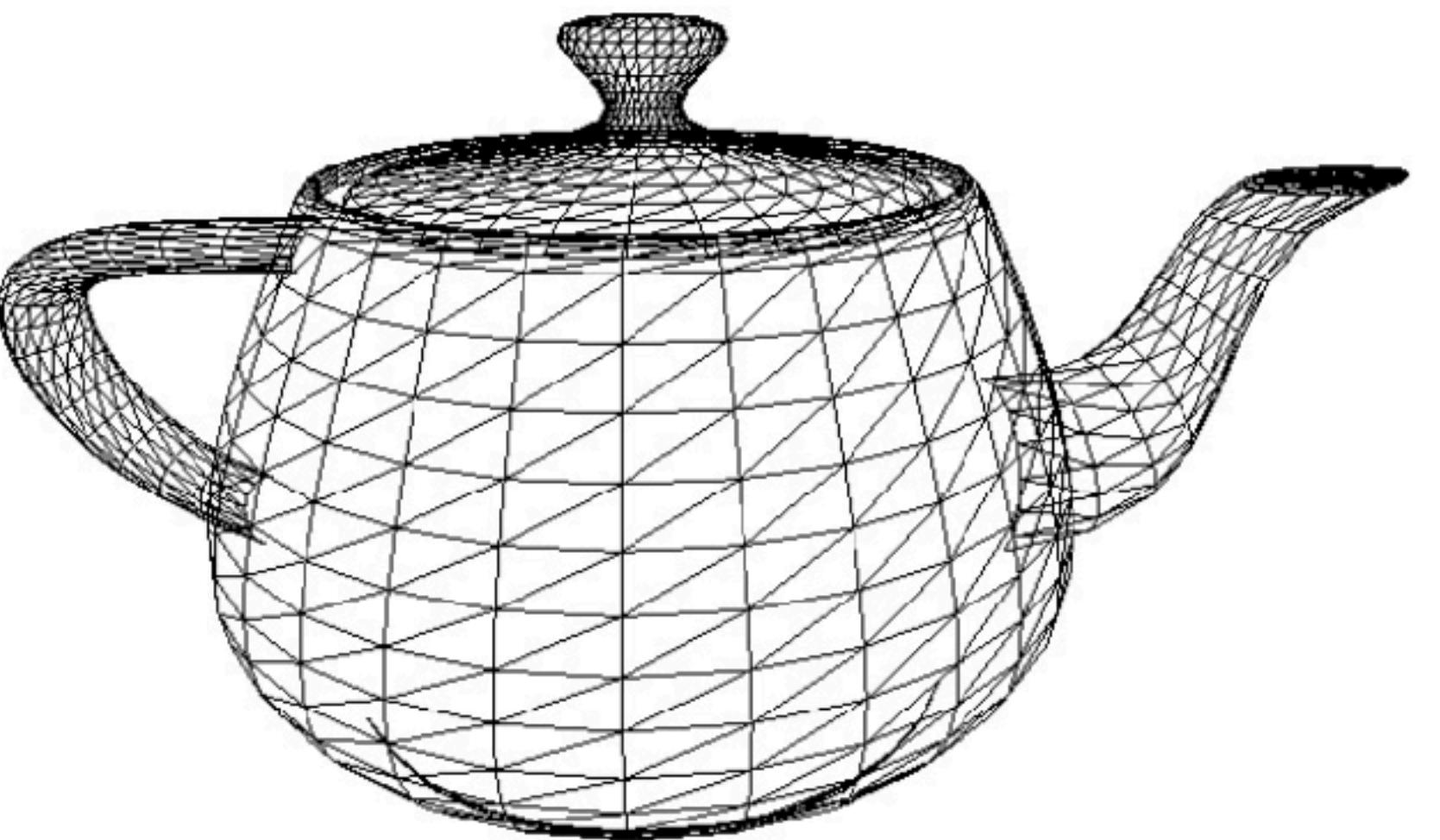
## SCENEGRAPH

## NODES

## OPTIMISATIONS

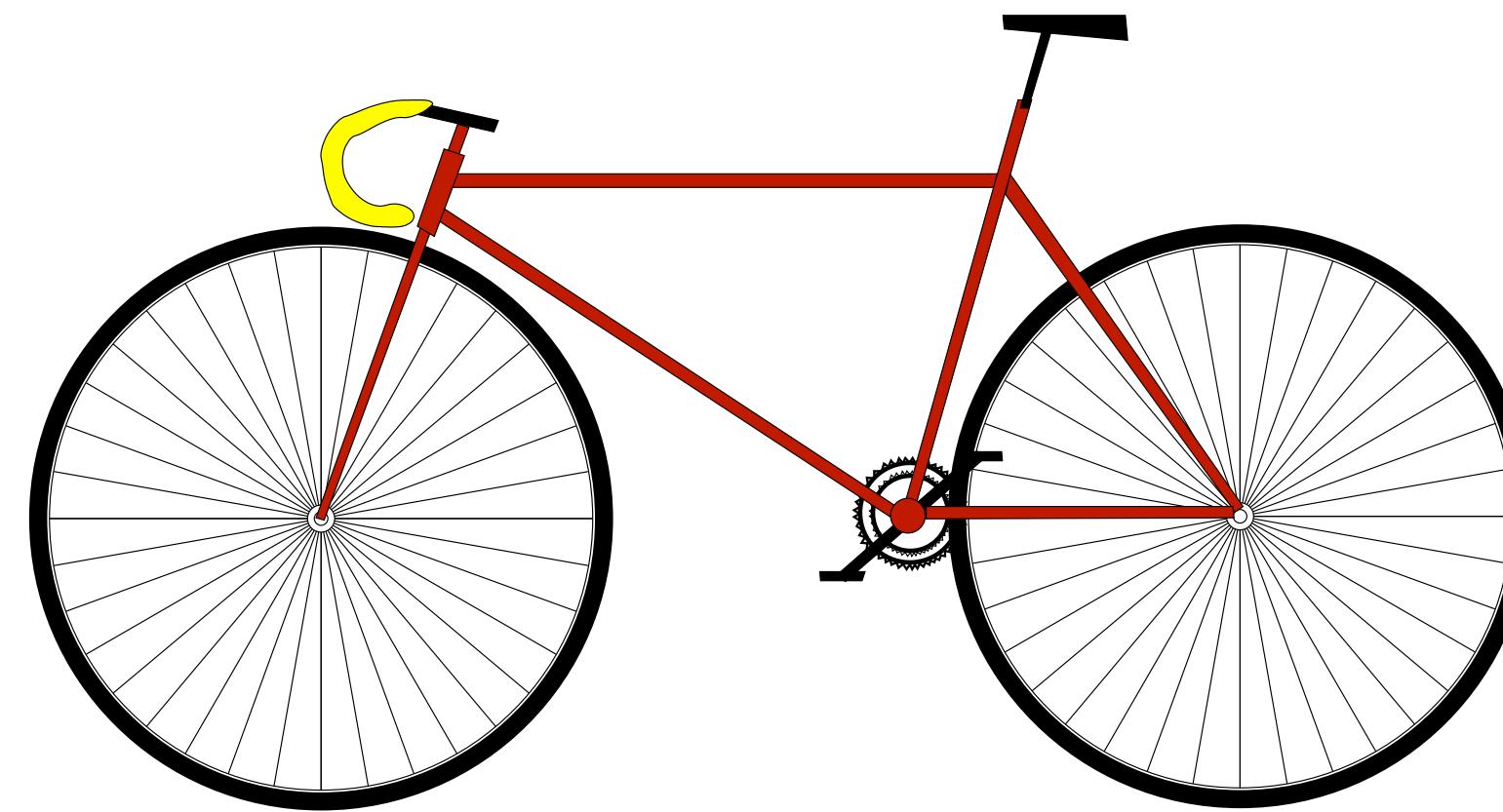
# WHY SCENE GRAPHS?

- OpenGL, WebGL
  - Designed as a state machine
  - Only aware of primitives (e.g. triangles)
  - No knowledge about complete scene



# PROBLEM

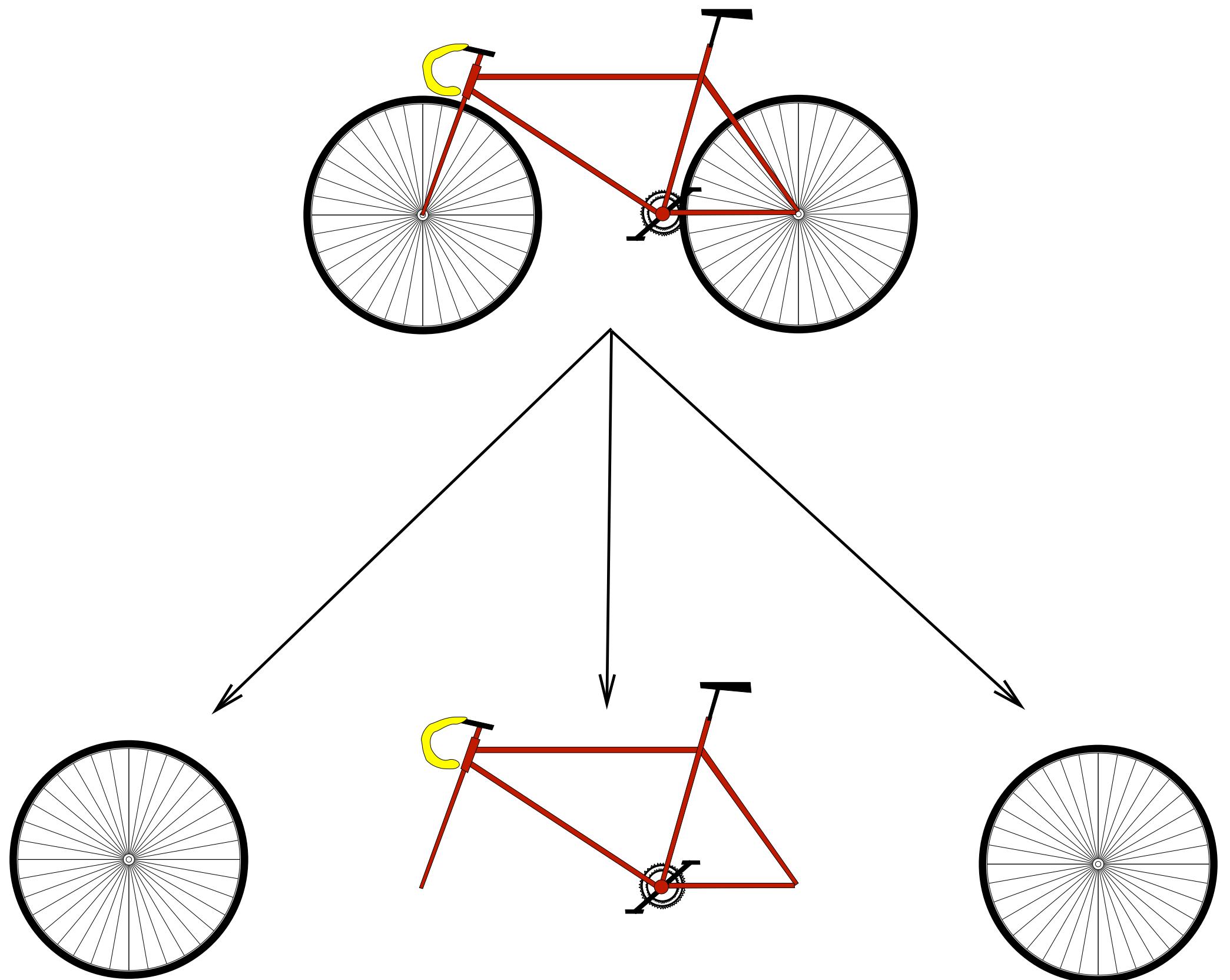
```
void drawBike(){  
    drawFrame();  
    drawFrontWheel();  
    drawRearWheel();  
}
```



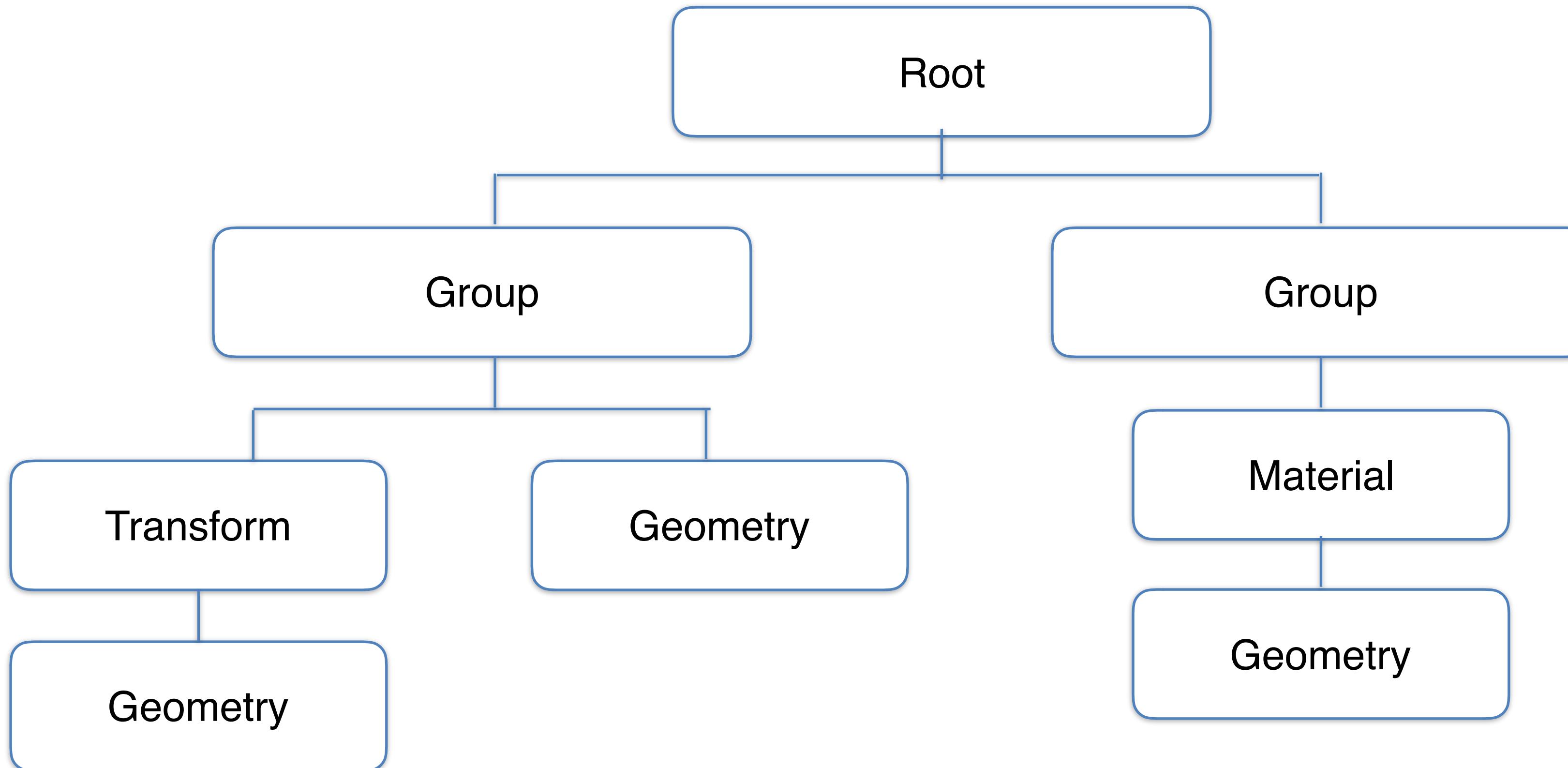
- Spatial relationship not stored
- How to move parts at the same time?
- Identical wheels are drawn twice

# WHY SCENEGRAPHS?

- Scene graphs
  - Store objects in a scene in a graph
  - Group related objects that share some properties together
  - Can optimise the way data is passed to the graphics hardware

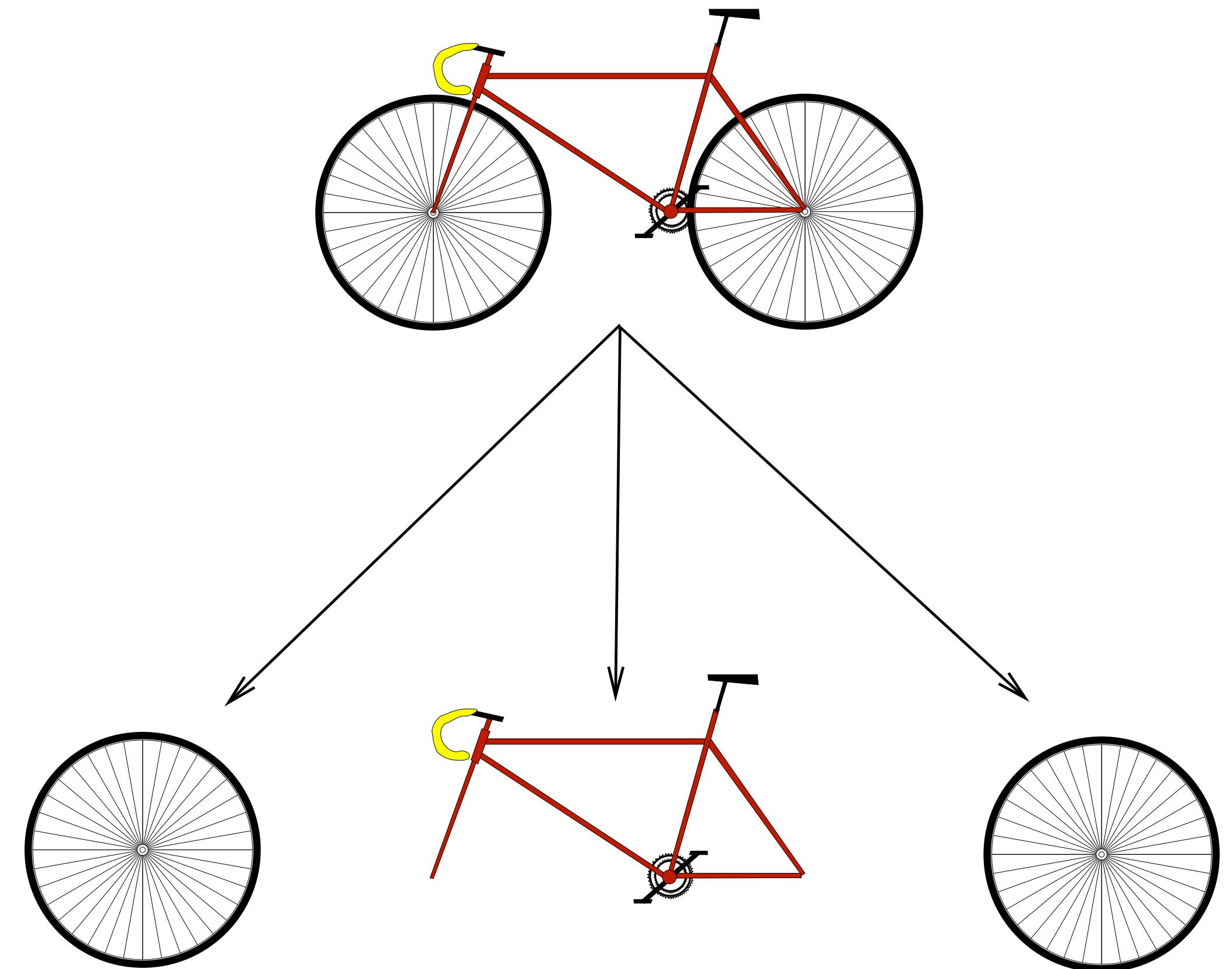


# SCENE GRAPH



# SCENEGRAPH

- Data structure
- Represented by a tree
  - Directed acyclic graph
- Root on top
- Leaves representing geometries
- Objects are placed relative to each other
- Represents logical and spatial relationship between objects in a scene



# ADVANTAGES

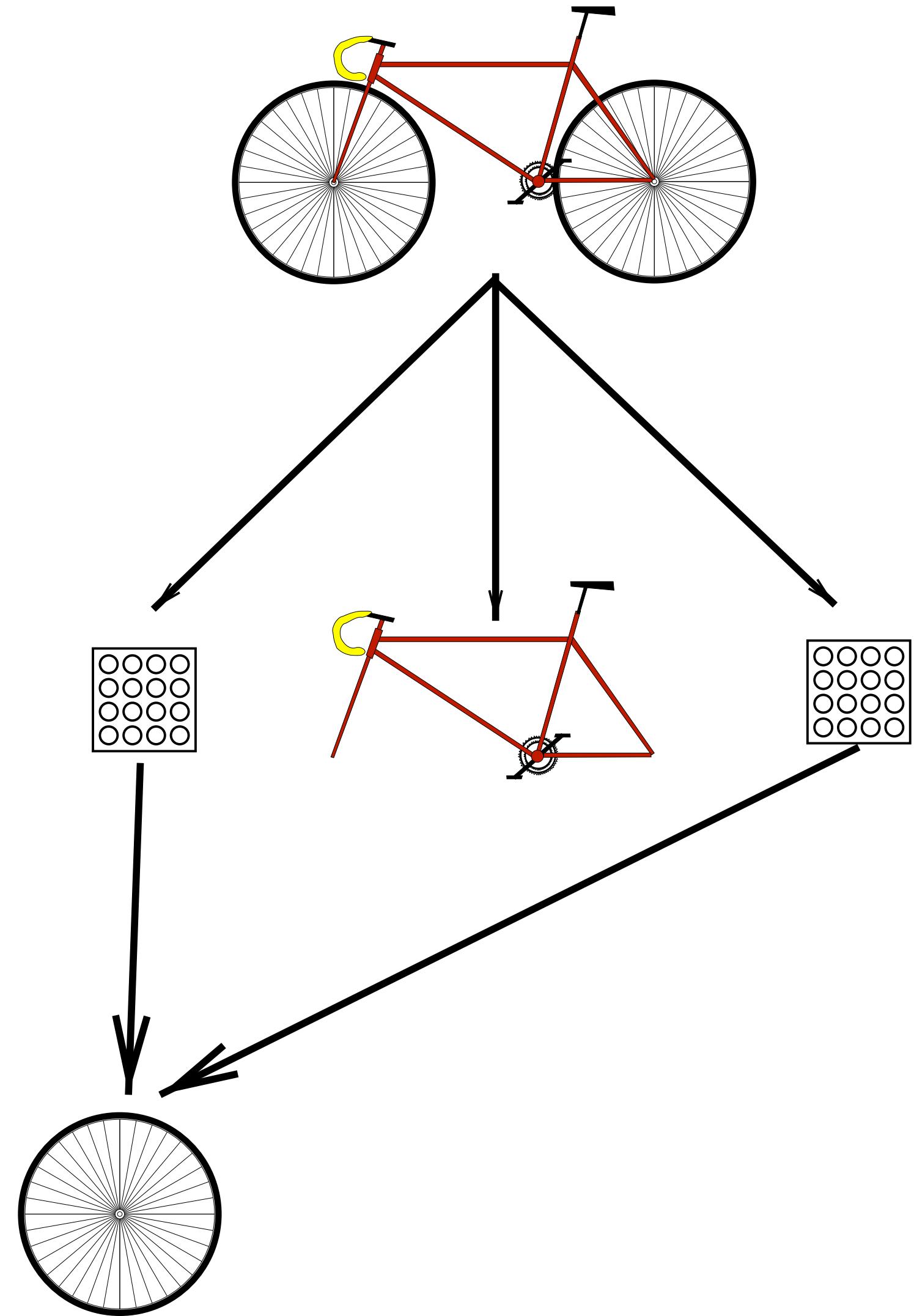
- Reuse geometry
- Reuse materials
- Optimisation based on view settings
- Optimisation based on occlusions
- Optimisation based on distance

# SCENEGRAPH

- Advantages:
  - Performance
  - Productivity
  - Portability
  - Scalability

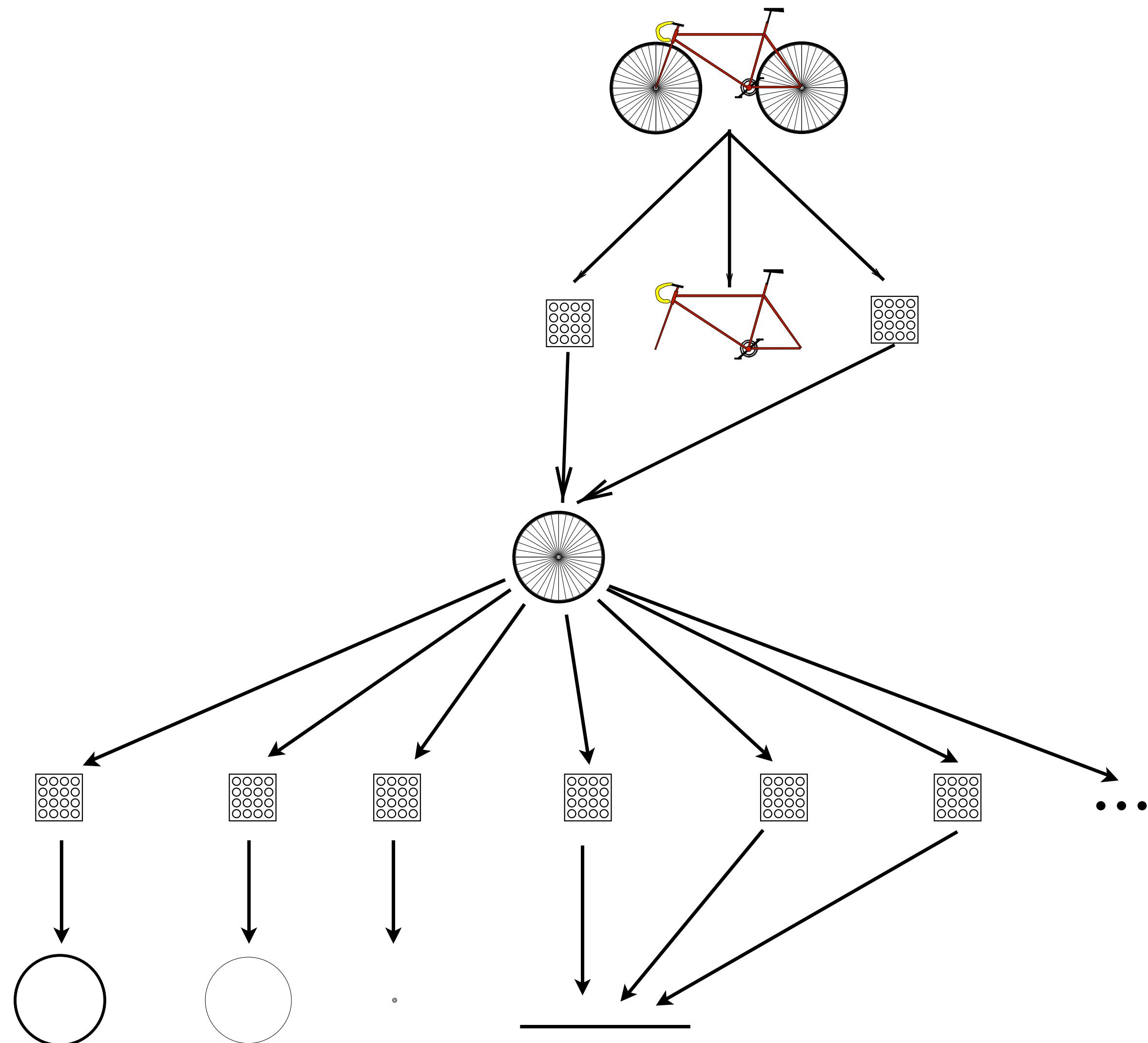
# SCENEGRAPH EXAMPLE

- Duplicated objects in our scene should share the same nodes in the scene-graph
- Note that we can use nodes to hold matrices, as well as geometry
- The transformations in a matrix node will apply to all children of that node



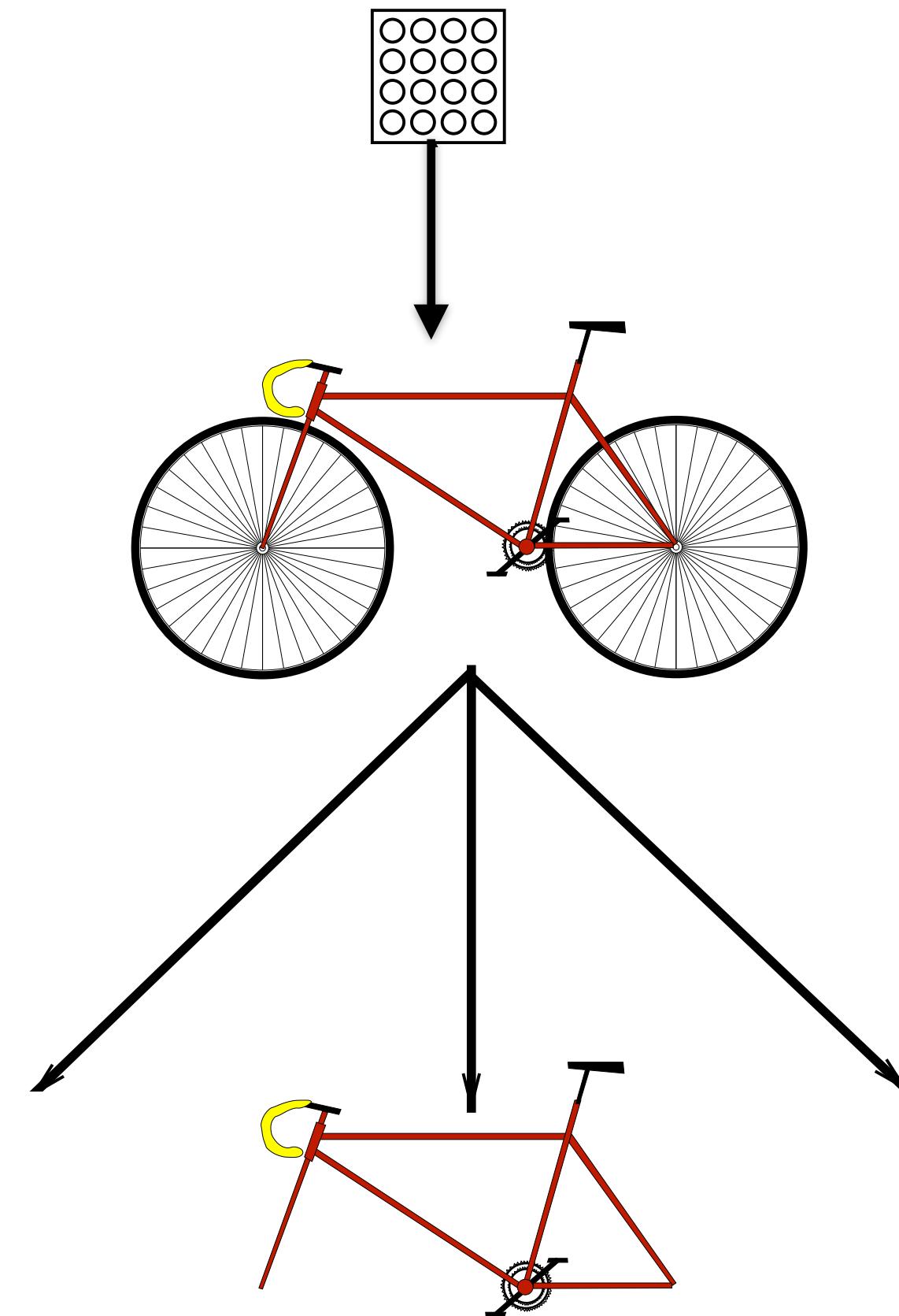
# SCENEGRAPH EXAMPLE

- Further geometric decomposition:
  - Wheel is itself made up of subcomponents



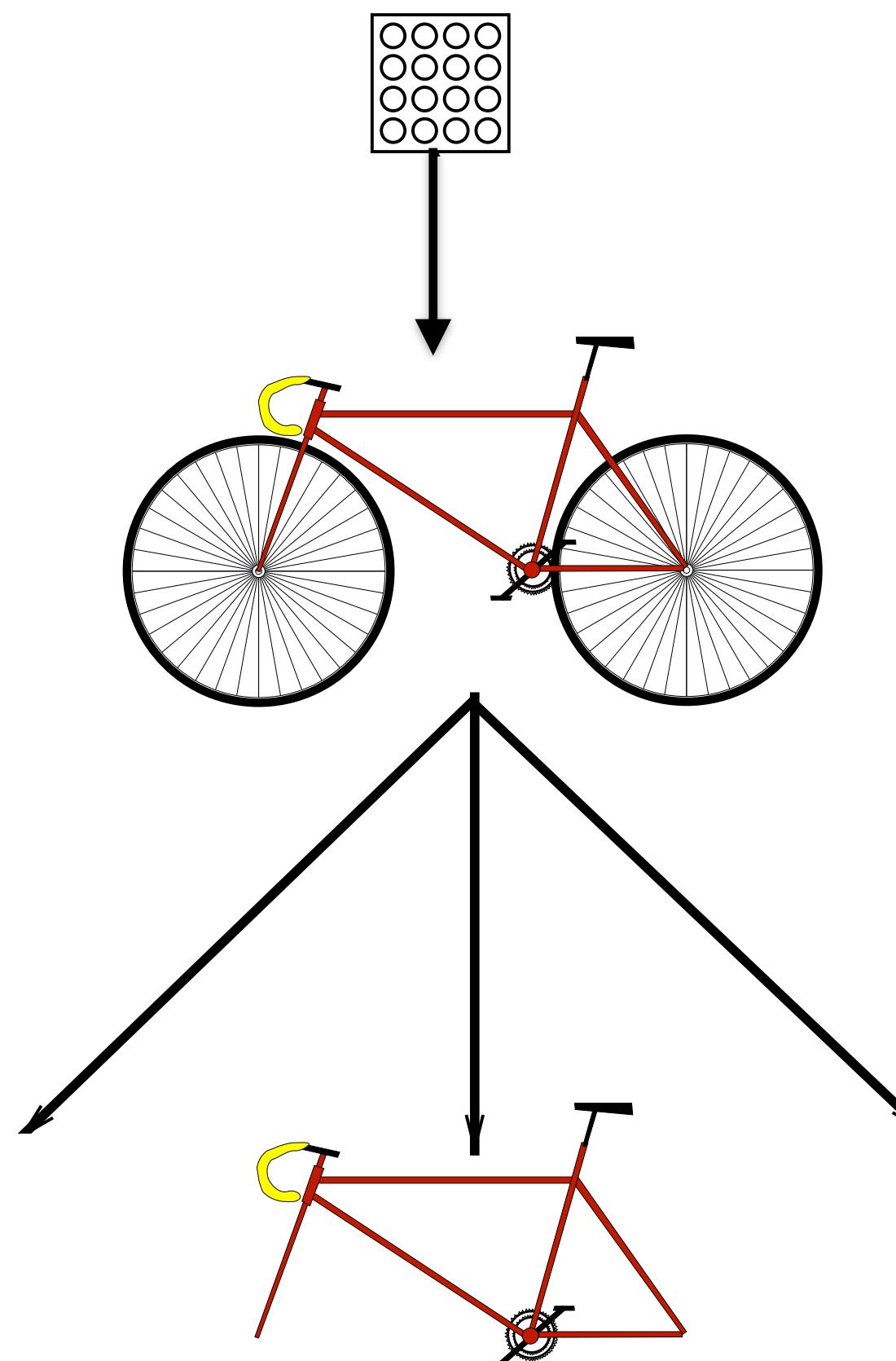
# TRANSFORMATIONS

- Object has a local transformation relative to its parent
- If bike root is transformed the frame and all child nodes would be transformed as well
- The root of the graph corresponds to “world coordinates”
- Each geometry is defined in local coordinates



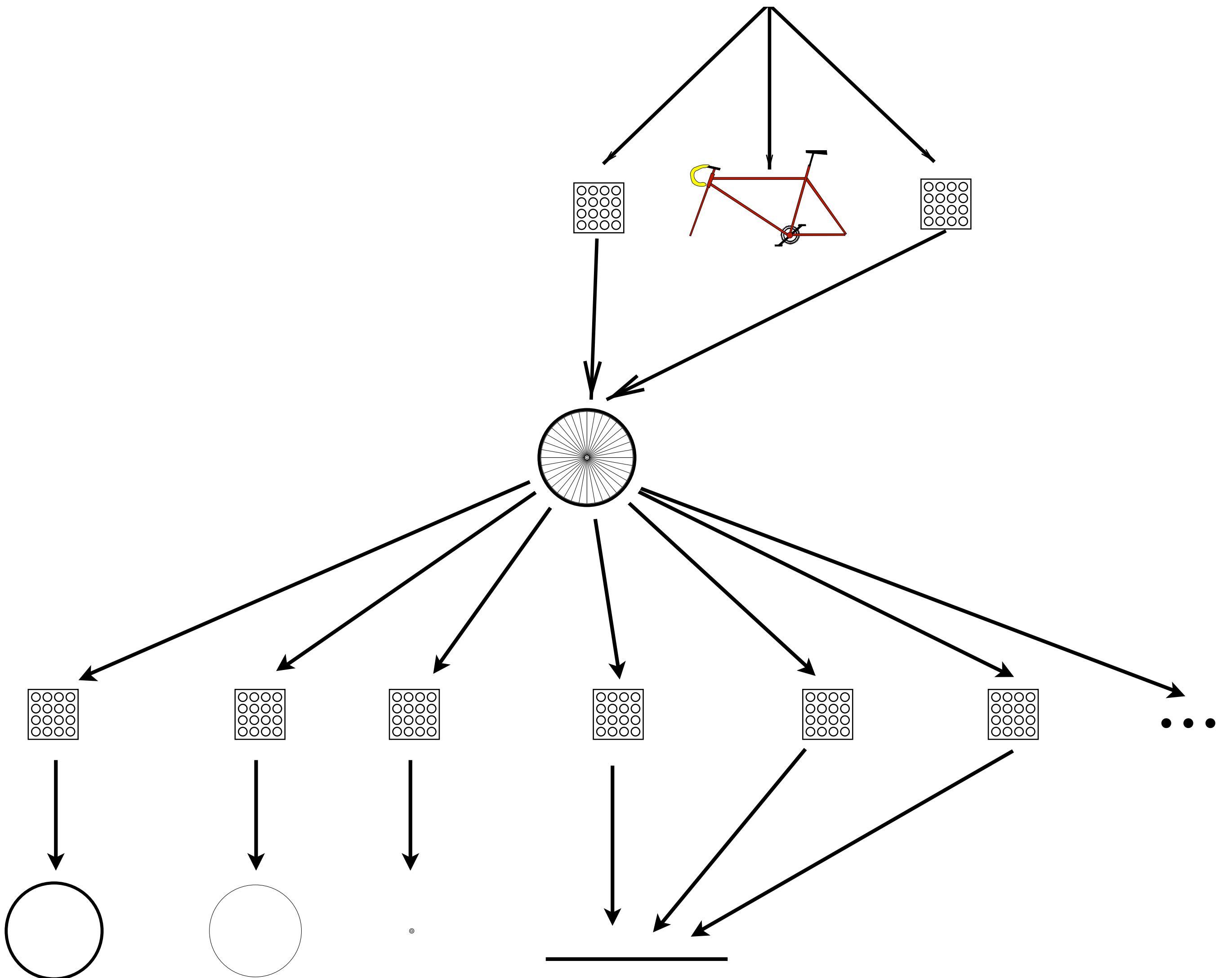
# WORLD COORDINATE SYSTEM

- Everything is positioned relative to the world coordinates
- Model matrix: Convert points in an object's local coordinate system into world coordinate system
- View matrix: Convert world coordinates to viewing coordinates

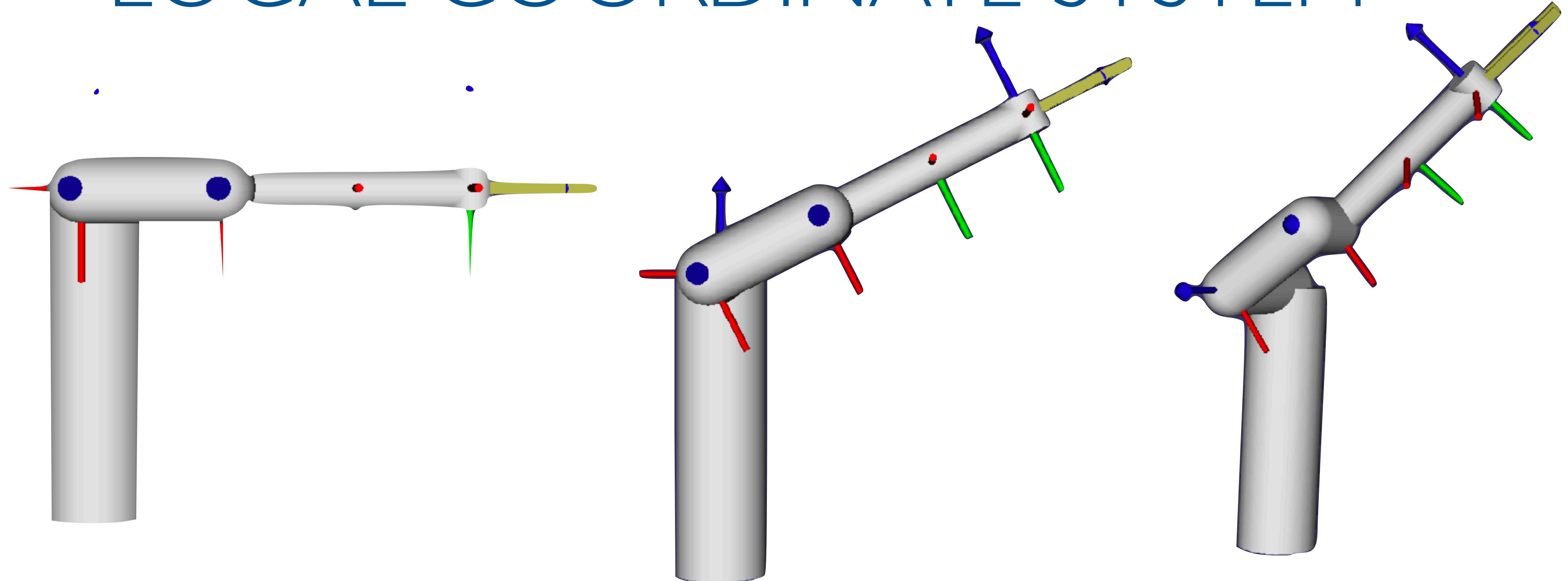


# LOCAL COORDINATE SYSTEM

- An object's local transformation describes the mapping between the object's local coordinate system to the parent's local coordinate system
- E.g. the left spoke's transformation describes the mapping between the wheel and the spoke



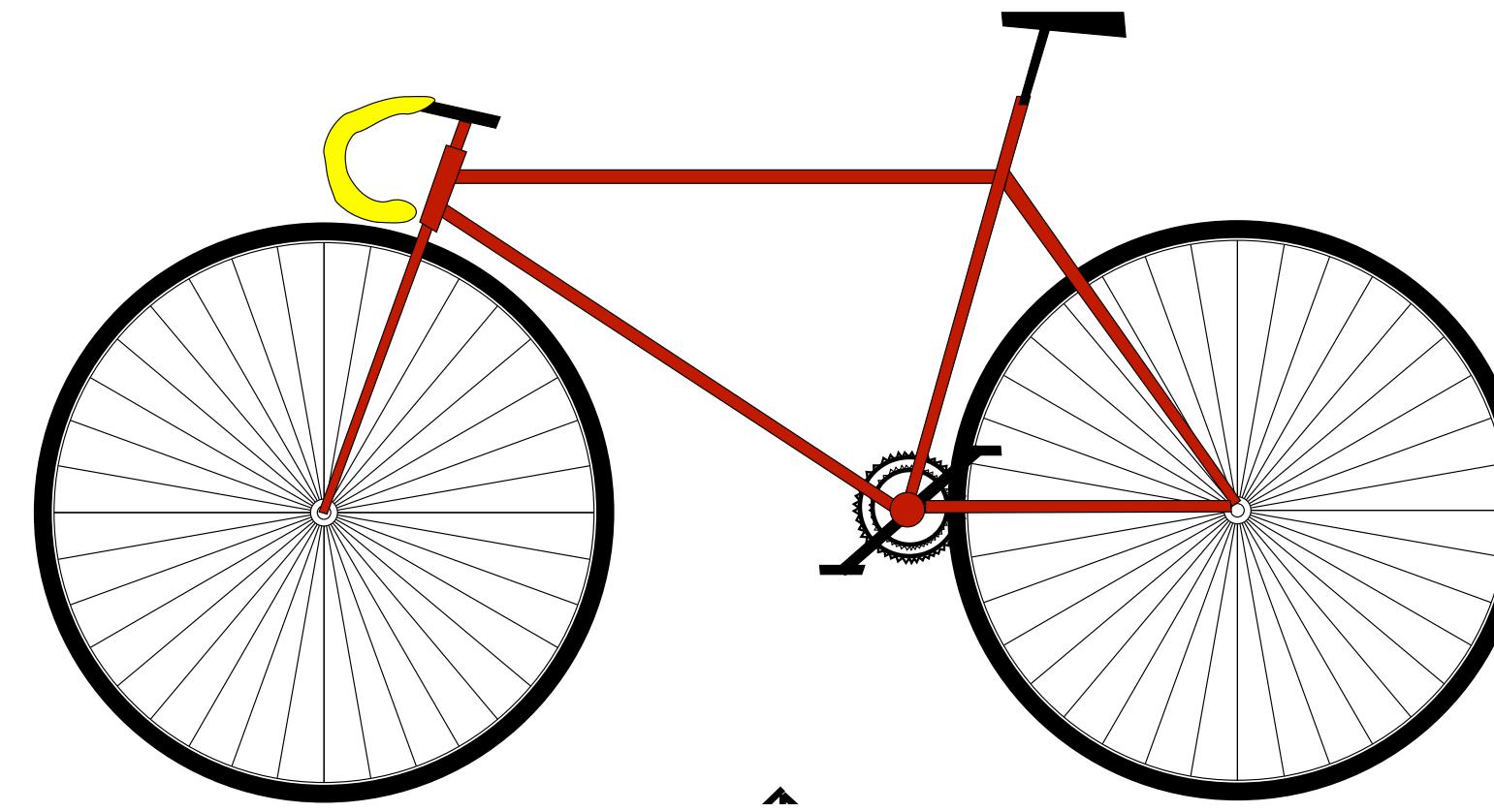
# LOCAL COORDINATE SYSTEM



- Each part of the robot is modelled in its own local coordinate system
- If the transformation of a part is changed it affects all its child nodes

# COMPARED TO OUR INITIAL PROBLEM

```
void drawBike(){  
    drawFrame();  
    drawFrontWheel();  
    drawRearWheel();  
}
```



- Spatial relationship not stored
- How to move parts at the same time?
- Identical wheels are drawn twice

# SCENE GRAPH IMPLEMENTATIONS

- OpenInventor
- OpenSceneGraph
- OpenSG (<http://www.opensg.org>)
- COIN3D (API compatible with Open Inventor 2.1)



# OPENSCENEGRAPH



<http://trac.openscenegraph.org/projects/osg/wiki/Screenshots/WSPSweden>

# OPENSCENEGRAPH



The Foundation of the Hellenic World: <http://trac.openscenegraph.org/projects/osg/wiki/Screenshots/FHW>

# OPENSCENEGRAPH



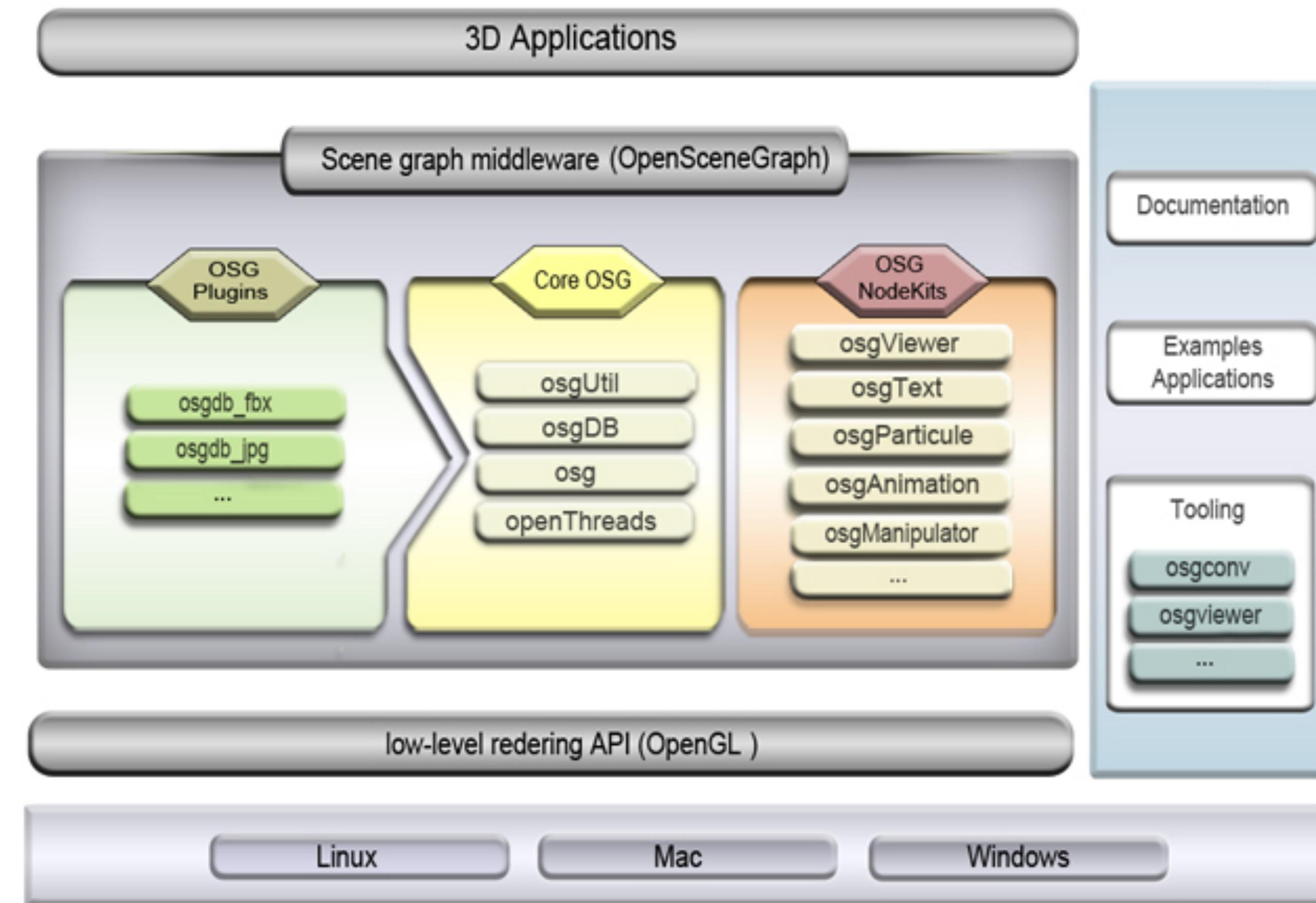
[https://live.osgeo.org/\\_images/osgearth3.jpg](https://live.osgeo.org/_images/osgearth3.jpg)

# ADDITIONAL LIBRARIES

## OSG NODEKITS

- osgText - anti-aliased text
- osgFX - special effects framework
- osgShadow - shadow framework
- osgManipulator - 3d interactive controls
- osgTerrain - terrain rendering
- osgAnimation - character and rigid body animation
- osgVolume - volume rendering
- Etc.

# OPENSCENEGRAPH



By ALJI Mohamed - Own work, CC BY-SA 3.0, <https://commons.wikimedia.org/w/index.php?curid=18209753>

# SCENEGRAPH NODES

- Child of Node parent class
- Types
  - Group Nodes
  - Transformation Nodes
  - Switch nodes
  - LOD nodes
  - Geode, geometry leaf node

# SCENEGRAPH NODES

- Drawable: abstract base class for drawable graphics
  - Geometry: vertices, normals, faces, texture coords
  - Text: drawing text
  - DrawPixels: drawing images using `glDrawPixels`
- StateSet: encapsulates OpenGL states and attributes
- Texture: encapsulates OpenGL texture functionality

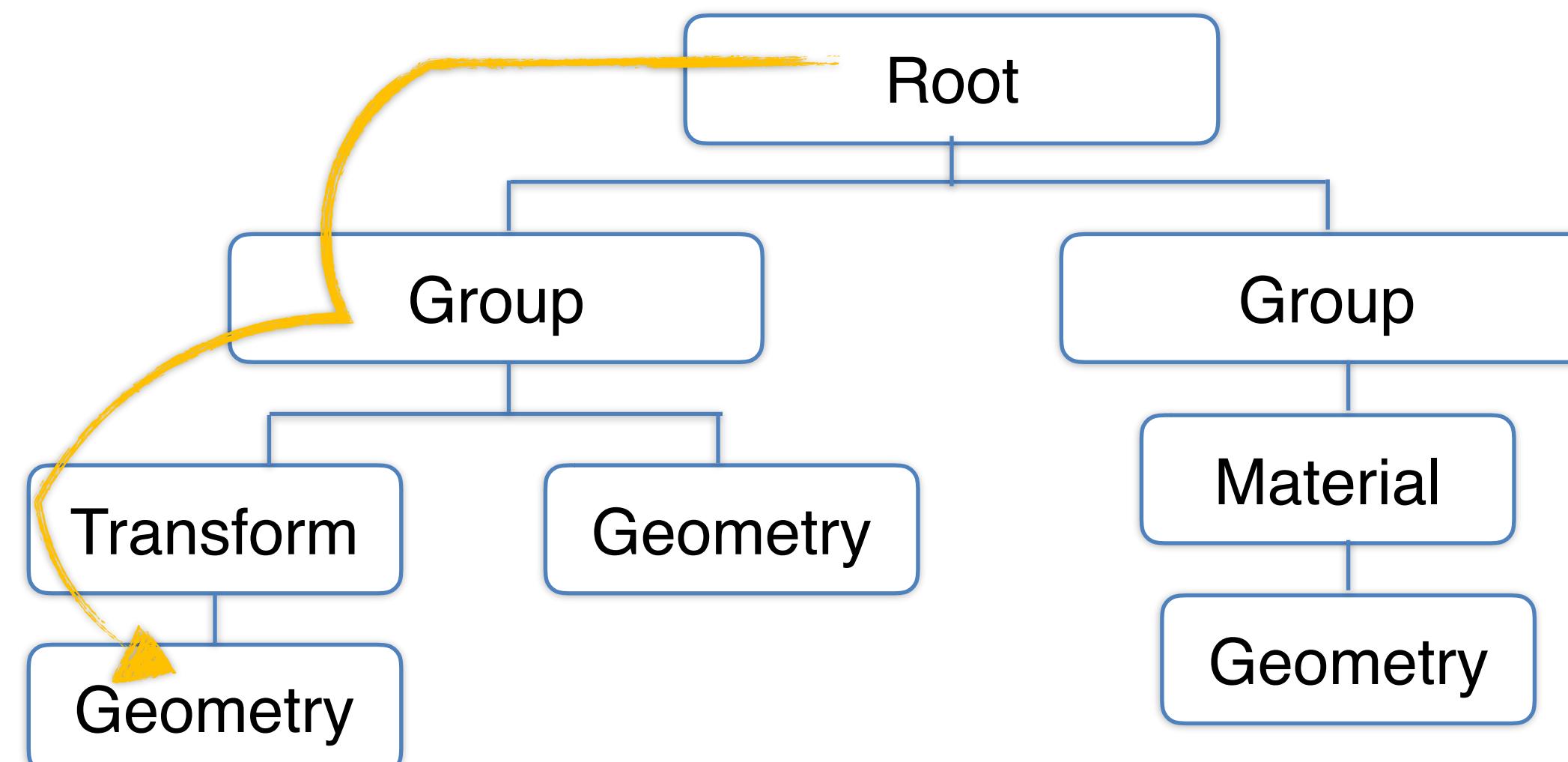
# SHAPES

- Box
- Sphere
- Cone
- Cylinder
- Capsule
- Special shapes (e.g. InfinitePlane)

# TRAVERSAL

Rendering consists of traversing the graph:

- Geometry nodes have to be rendered (primitives, meshes),
- Transform node modifies transformation matrices,
- State node change a render state (colour, material, shader)



# GEODES

```
osg:: Vec3 vcen(1.0, 1.0, 1.0);

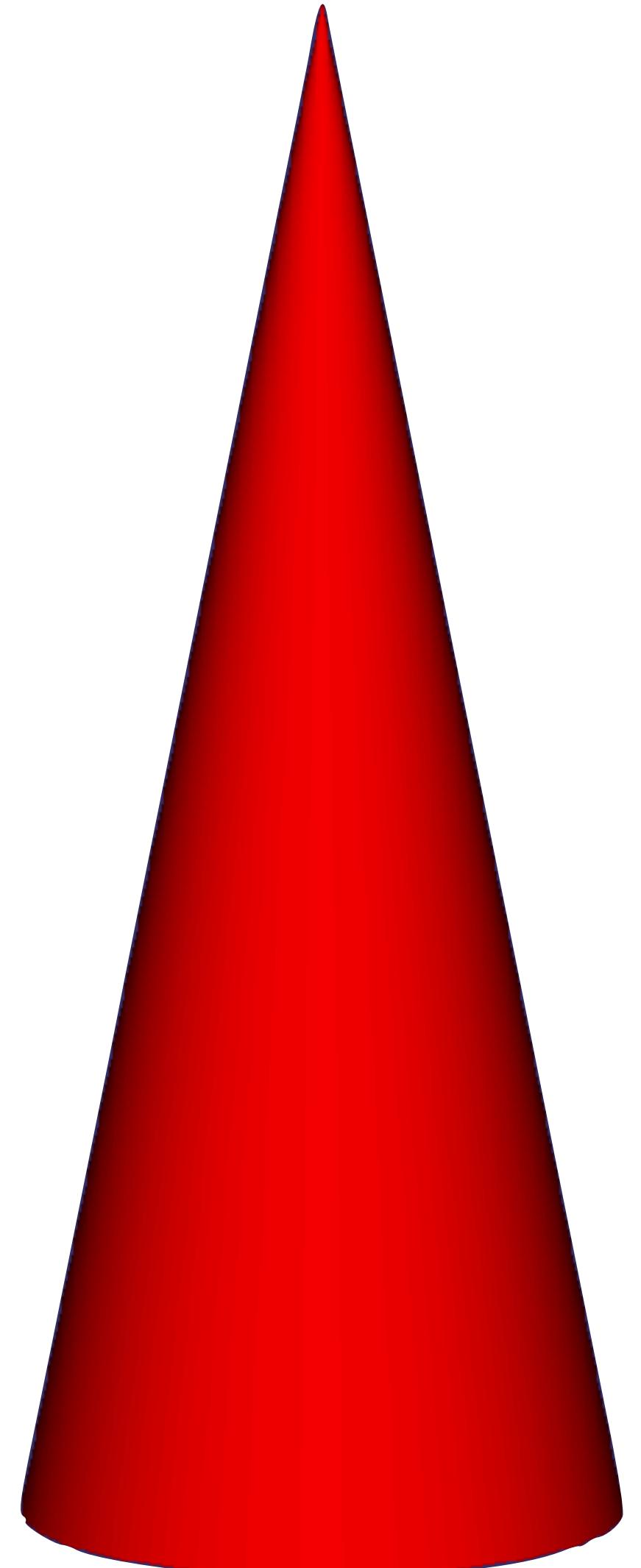
osg::Cone* cone = new osg::Cone(vcen, 2.0, 10.0);
// Create a drawable object based on the cone

osg:: ShapeDrawable *drawable = new osg::ShapeDrawable(cone);

drawable->setColor(osg::Vec4(1.0f, 0.0f, 0.0f, 1.0f));
// create a new geode

osg:: Geode* geode = new osg::Geode();
geode->addDrawable(drawable);

osg::Group * node = new osg::Group();
node->addChild(geode);
```



# GROUP NODES

```
float r = node->getBound().radius(); // diameter
osg::Group * root = new osg::Group();
osg::Group * group = new osg::Group();

// Create four matrices for translated instances of the cow
osg::MatrixTransform * transform0 = new osg::MatrixTransform();
transform0->setMatrix( osg::Matrix::translate( 0,0,r ) );

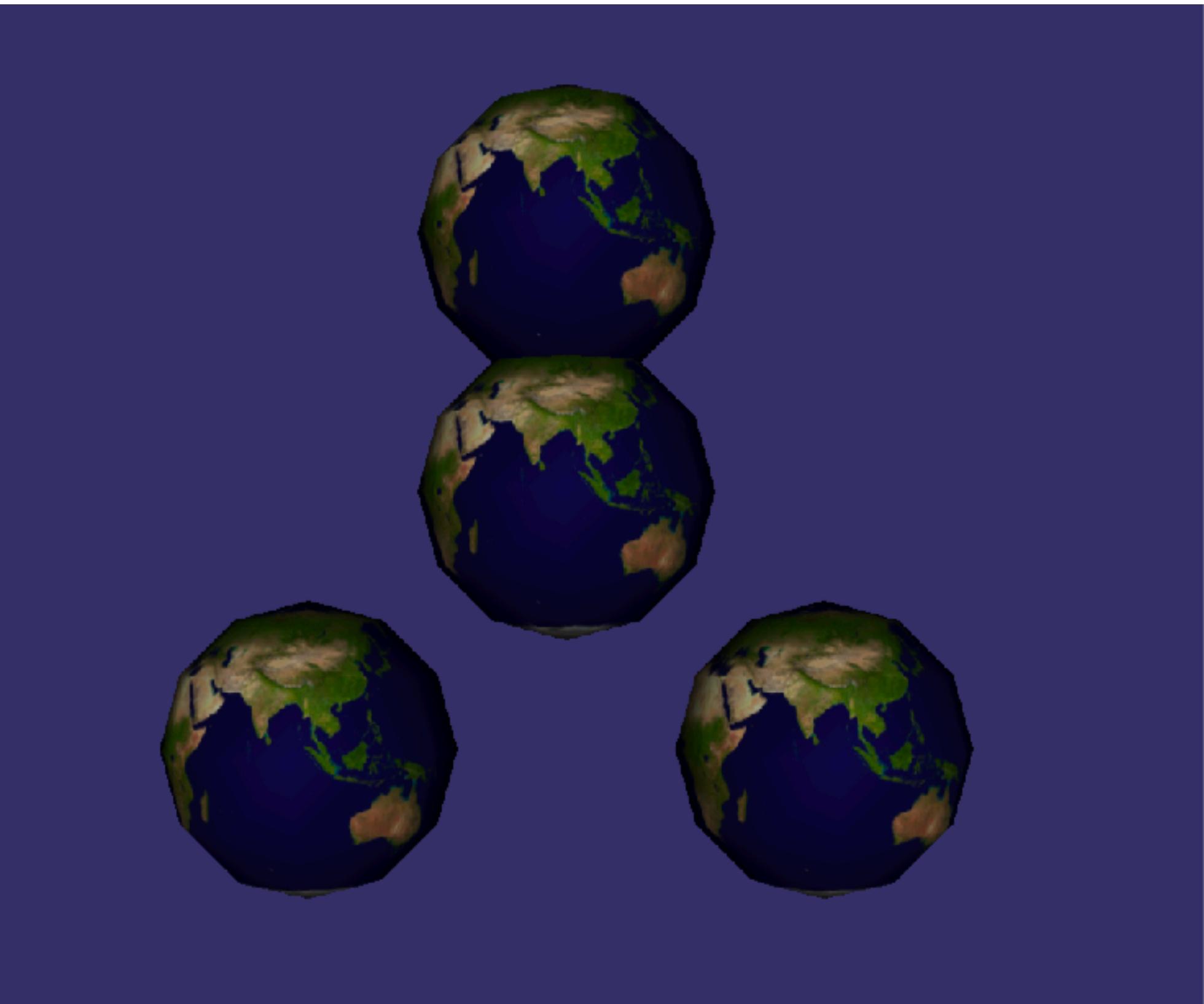
osg::MatrixTransform * transform1 = new osg::MatrixTransform();
transform1->setMatrix( osg::Matrix::translate( 0,0,0 ) );

osg::MatrixTransform * transform2 = new osg::MatrixTransform();
transform2->setMatrix( osg::Matrix::translate( -r,0,-r ) );

osg::MatrixTransform * transform3 = new osg::MatrixTransform();
transform3->setMatrix( osg::Matrix::translate( r,0,-r ) );

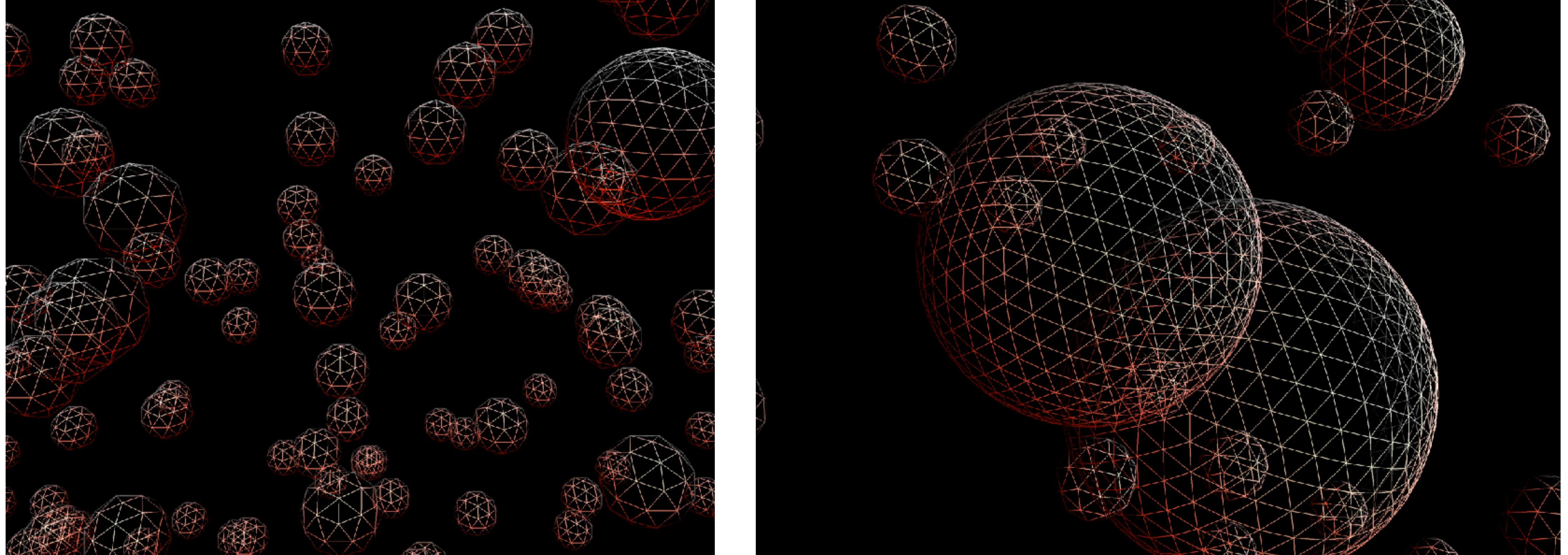
root->addChild( transform0 );
root->addChild( group );
group->addChild( transform1 );
group->addChild( transform2 );
group->addChild( transform3 );

transform0->addChild( node );
transform1->addChild( node );
transform2->addChild( node );
transform3->addChild( node );
```



# PERFORMANCE OPTIMISATION

# LEVEL OF DETAIL



- Rendering Optimisation
- Change level of detail depending on distance to the camera

# LOD NODE

- Node allows switching between children depending on distance from eye point
- Objects further away from the eye point are rendered at a lower level of detail
- Each LOD child has a corresponding valid range consisting of a minimum and maximum distance. Given a distance to the viewer ( $d$ ), LOD displays a child if  $\text{min} \leq d < \text{max}$ .
- Usage like group node: `lod.addChild(detailedNode);`
- Set the visible range from the viewer to the object:
  - `load.setRange(childNumber, near, far);`

# LOD NODES

```
LOD lod = new LOD();

lod.addChild(highDetail);

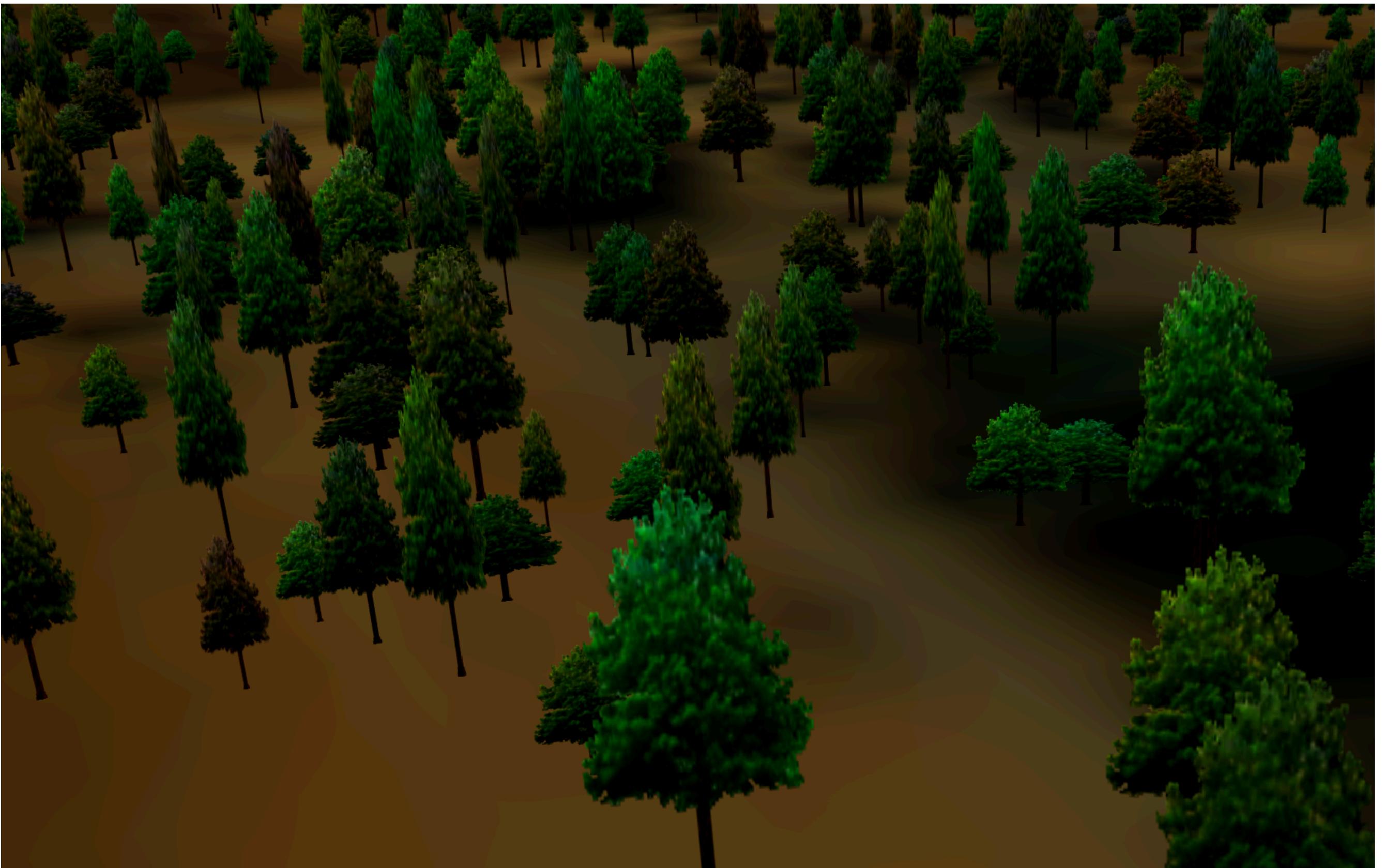
lod.setRange(0, 0, 10);
lod.addChild(medDetail);

lod.setRange(1, 10, 100);
lod.addChild(lowDetail);

lod.setRange(2, 100, 1000);
lod.addChild(noDetails);

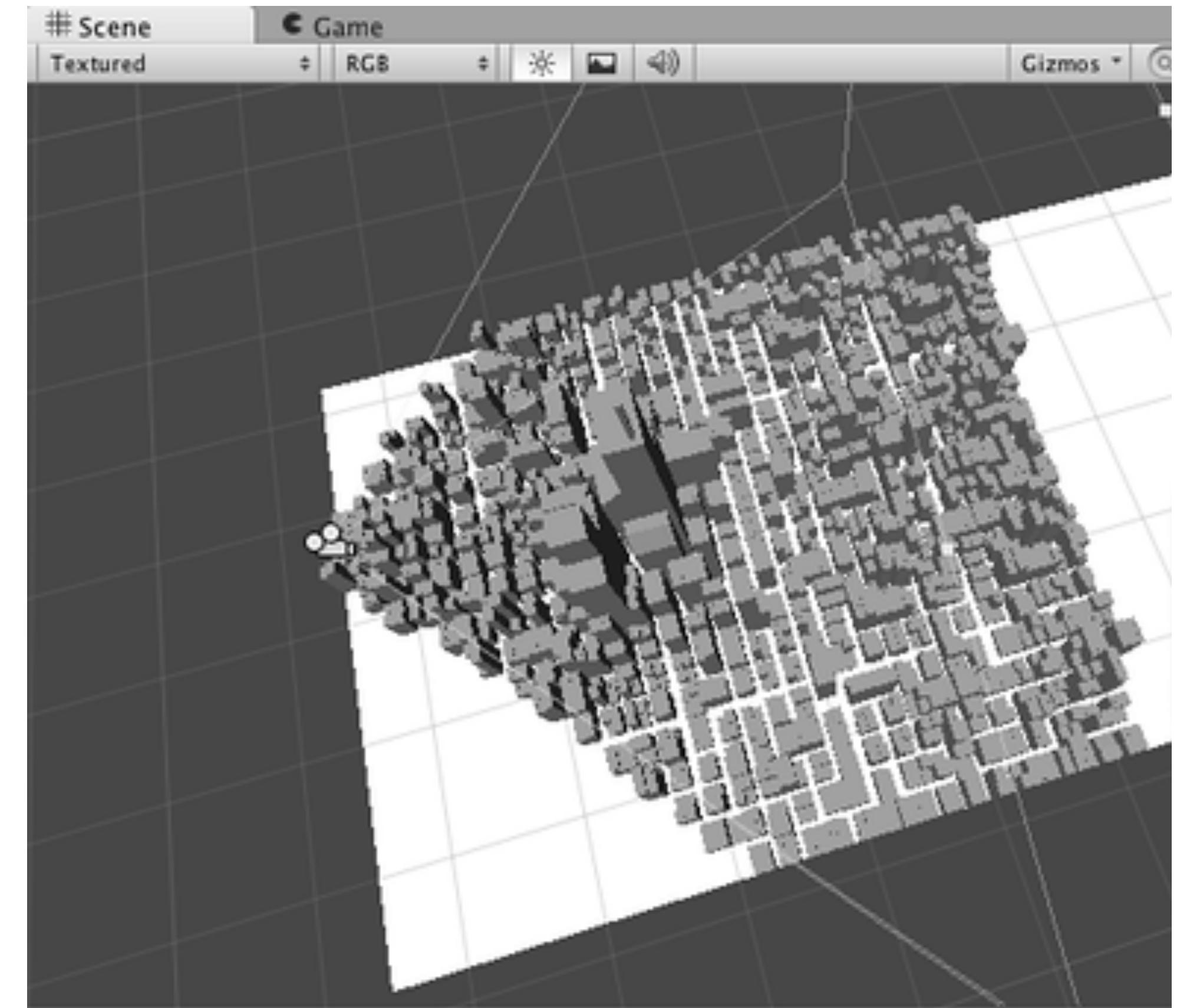
lod.setRange(2,1000,10000);
```

# BILLBOARDS



# CULLING

- Scene graph structure supports efficient culling
  - Bounding volume is calculated at each node in the scene graph
  - Includes geometry of node and child nodes
  - When traversing the scene graph, bounding volumes are evaluated against view frustum
  - If bounding volume does not intersect with view frustum -> culled
  - Culled nodes and their children are not sent to the graphic card



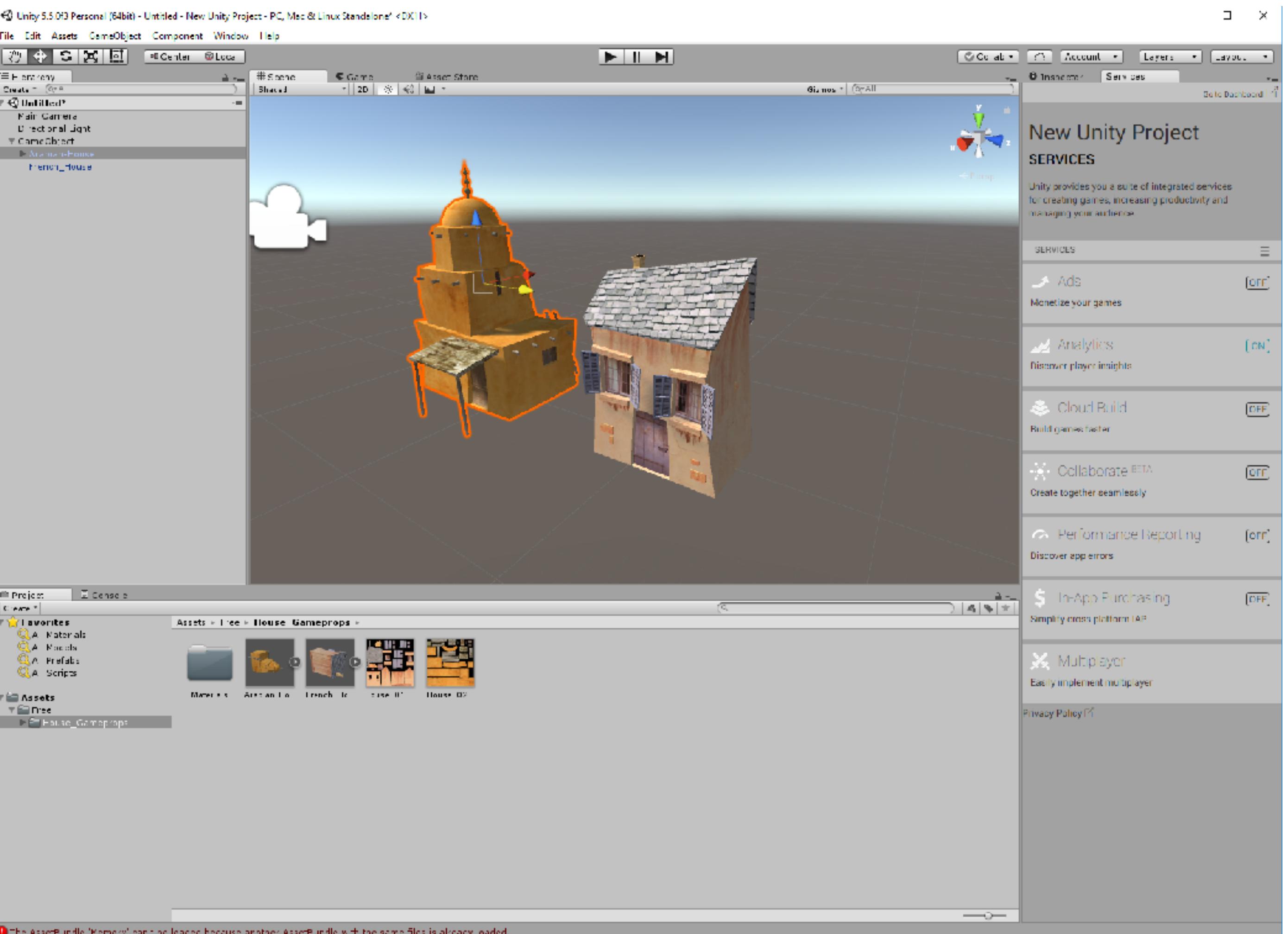
<https://docs.unity3d.com/460/Documentation/Manual/OcclusionCulling.html>

# GAME ENGINES

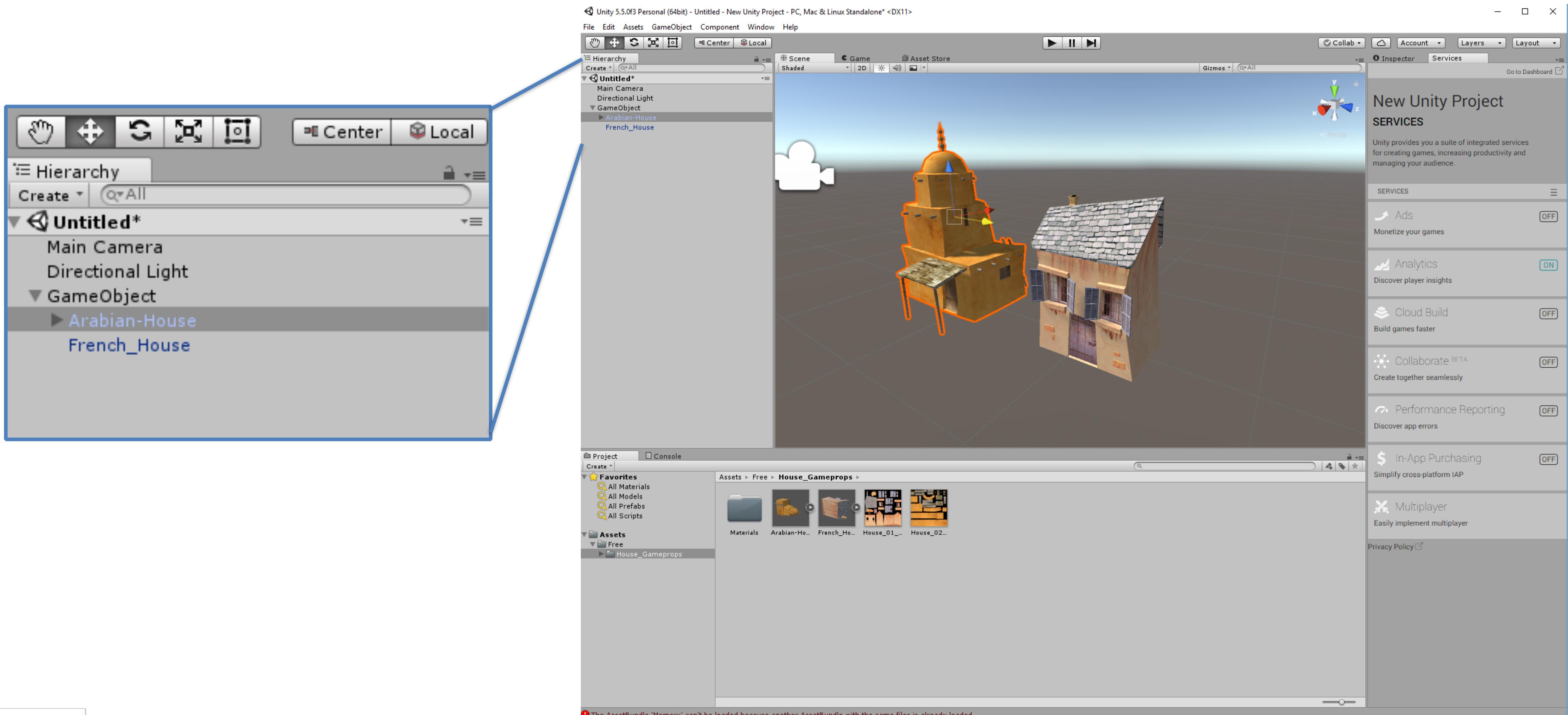
- Provide:
  - Rendering
  - Scene graph
  - Animation
  - Physics Engine
- Visual UI for scene editing

# RENDER/GAME ENGINES

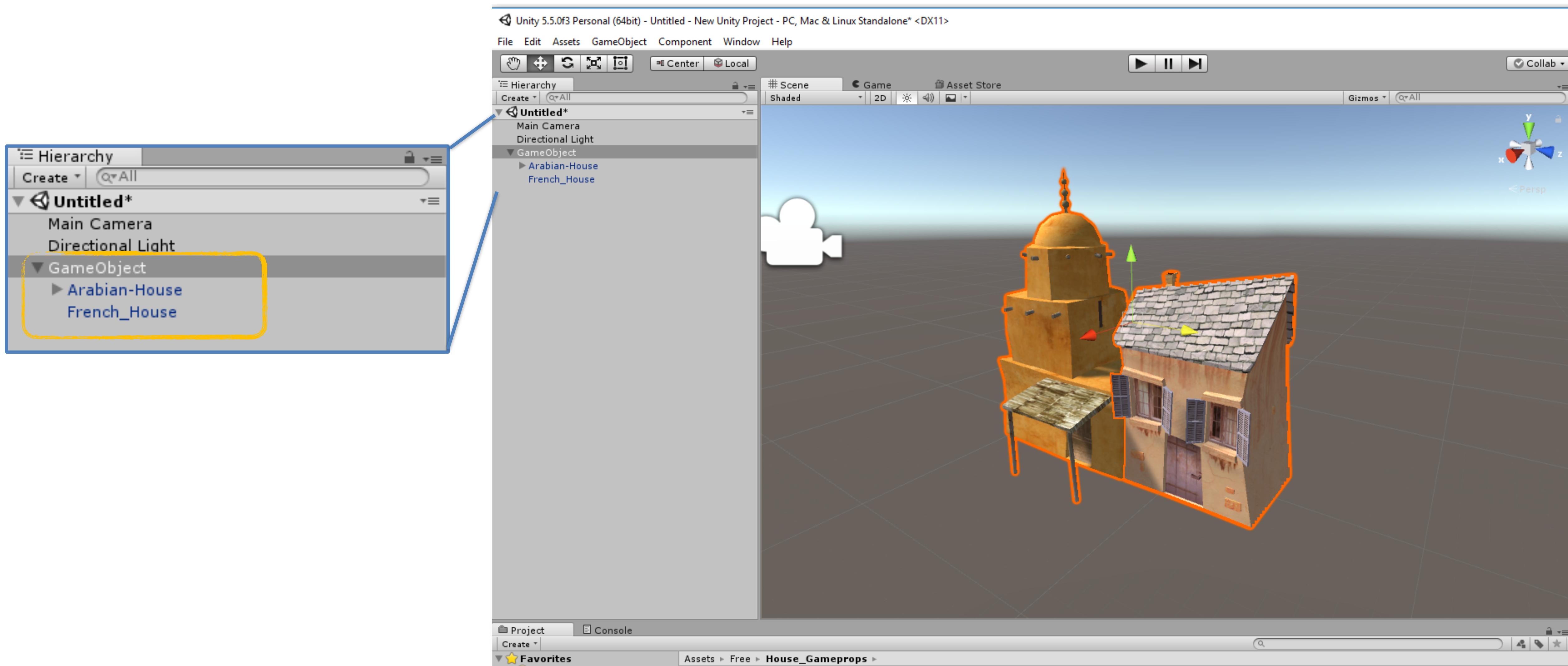
- Unity
- Unreal
- CryEngine
- Etc.



# UNITY

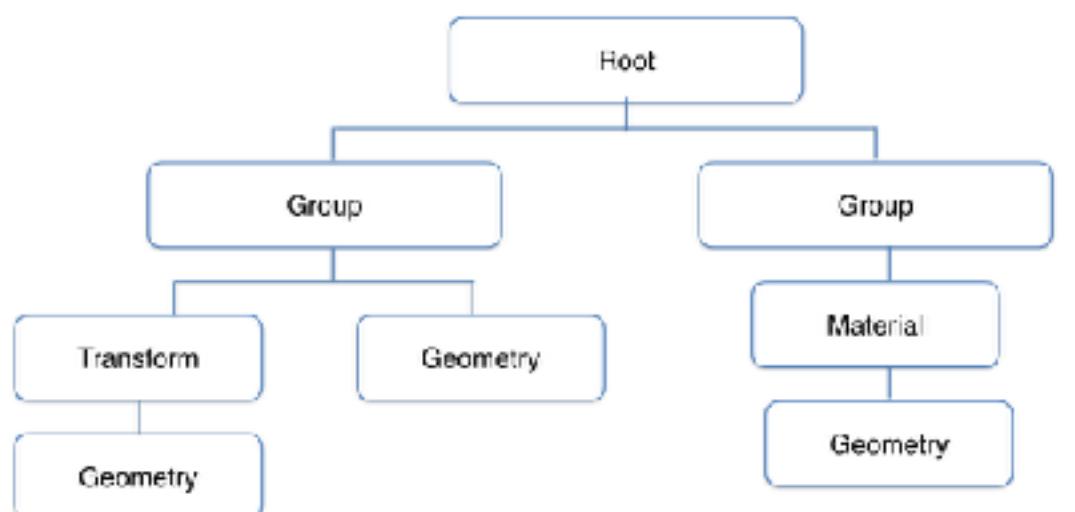


# UNITY



# SUMMARY

## SCENEGRAPH



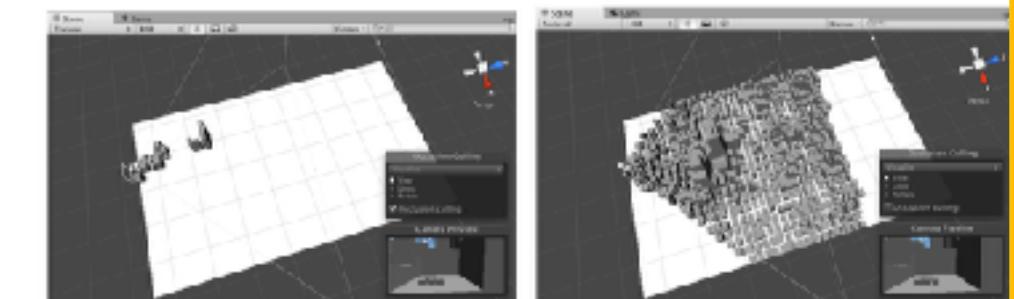
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- Different types of nodes
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## PERFORMANCE OPTIMISATION

Visual impact comparisons and measurements				
Image				
Vertices	~6500	~2880	~1580	~670
Notes	Maximum detail for close-ups.			Minimum detail, vary for objects.

### Level-of-detail



## SCENEGRAPH

## NODES

## OPTIMISATIONS

# Thank You!

For more material visit

[http://www.cs.otago.ac.nz/  
cosc342/](http://www.cs.otago.ac.nz/cosc342/)