

# Overview

- This Lecture
  - Debugging & Concurrency in kernel
  - Source: LDD ch4 & ch5, ELDD ch2, ch21

# Kernel debugging options

- There are some configuration options for supporting debugging in the kernel
  - CONFIG\_DEBUG\_KERNEL
  - CONFIG\_DEBUG\_SLAB/SLUB
  - CONFIG\_DEBUG\_PAGEALLOC
  - CONFIG\_DEBUG\_SPINLOCK
  - CONFIG\_DEBUG\_SPINLOCK\_SLEEP
  - CONFIG\_DEBUG\_INFO
  - CONFIG\_MAGIC\_SYSRQ
  - CONFIG\_DEBUG\_STACKOVERFLOW
  - CONFIG\_DEBUG\_STACK\_USAGE

# Kernel debugging options (cont.)

- CONFIG\_KALLSYMS
- CONFIG\_IKCONFIG
- CONFIG\_IKCONFIG\_PROC
- CONFIG\_DEBUG\_DRIVER
- CONFIG\_INPUT\_EVBUG
- CONFIG\_PROFILING
- .....

# Debugging by printing

- Use **printk**
- Be aware of eight priority levels
  - KERN\_EMERG, KERN\_ALERT, KERN\_CRIT, KERN\_ERR, KERN\_WARNING, KERN\_NOTICE, KERN\_INFO, KERN\_DEBUG
- Mind the console level
  - Not all printk messages appear at the console
  - Check `/proc/sys/kernel/printk`
- You may need a separate console for debugging
  - Use `ioctl(TIOCLINUX)` to redirect the console message
- `klogd` is used to read all kernel messages from `/proc/kmsg`

# Turn debugging messages on/off

- You may turn on/off debugging message using conditional compilation

```
#undef PDEBUG          /* undef it, just in case */
#ifdef SCULL_DEBUG
#  ifdef __KERNEL__
    /* This one if debugging is on, and kernel space */
#    define PDEBUG(fmt, args...) printk( KERN_DEBUG "scull: " fmt,
    ## args)
#  else /* This one for user space */
#    define PDEBUG(fmt, args...) fprintf(stderr, fmt, ## args)
#  endif
#else
#  define PDEBUG(fmt, args...) /* not debugging: nothing */
#endif
#undef PDEBUGG
#define PDEBUGG(fmt, args...) /* nothing: it's a placeholder */
```

# Rate limit

- Use `printk_ratelimit` to limit printing rate  
if (`printk_ratelimit()`)  
`printk(KERN_NOTICE "The printer is still on  
fire\n");`
- Print device numbers
  - `int print_dev_t(char *buffer, dev_t dev);`
  - `char *format_dev_t(char *buffer, dev_t dev);`

# Debugging by querying

- Use /proc to query important variables
- Create a /proc entry
  - struct proc\_dir\_entry \*proc\_create\_data(const char \*name, mode\_t mode, struct proc\_dir\_entry \*base, struct file\_operations \*proc\_fops, void \*data);
  - Example
    - proc\_create\_data("scullmem", 0 /\* default mode \*/, NULL /\* parent dir \*/, &test\_proc\_fops, NULL /\* driver data \*/);
  - remove\_proc\_entry("scullmem", NULL /\* parent dir \*/);

# Querying with ioctl

- Use undocumented ioctl commands to expose internal status of driver programs.
- More details for ioctl will be addressed later (refer to chapter 6 of LDD)



# Debugging by watching

- Watch behavior of user space applications
  - Use strace
  - ...

# Debugging system faults

- Check oops message
  - Important fields: EIP, stack, call trace
  - Examples
- System hangs
  - Use `schedule` call
  - Use the magic **SysRq** key
    - Use “`echo 1 > /proc/sys/kernel/sysrq`” to enable it
- They are for advanced kernel programmers!

# Using debuggers

- Using gdb
  - `gdb /usr/src/linux/vmlinux /proc/kcore`
  - But the changing variables are found the same
  - Use the command `core-file /proc/kcore` to get updated.
  - For modules, the `add-symbol-file` command should be used.
    - `add-symbol-file scull.ko 0xd0832000 -s .bss 0xd0837100 -s .data 0xd0836be0`
- Using kdb and kgdb (need special patches)
- QEMU, Linux Trace Toolkit, and Dynamic Probes

# Data race

- Data race condition
  - occurs when a variable is accessed concurrent R/W operations and one of them is write
- Semaphores, mutexes and locks are used to prevent data races
- Linux semaphores
  - `void sema_init(struct semaphore *sem, int val);`
  - `DECLARE_MUTEX(name);`
  - `DECLARE_MUTEX_LOCKED(name);`
  - `Void init_MUTEX(struct semaphore *sem);`
  - `void init_MUTEX_LOCKED(struct semaphore *sem);`

# Linux semaphores

- Operations on semaphores
  - `void down(struct semaphore *sem);`
  - `int down_interruptible(struct semaphore *sem);`
  - `int down_trylock(struct semaphore *sem);`
  - `void up(struct semaphore *sem);`
- Reader/writer semaphores
  - Allow multiple readers access the resource simultaneously.
- Completion
  - A faster constructor for synchronization between processes/threads

# Mutex

- Mutex API
  - `DEFINE_MUTEX(name);`
  - `mutex_init(mutex);`
  - `void mutex_lock(struct mutex *lock);`
  - `int mutex_lock_interruptible(struct mutex *lock);`
  - `int mutex_trylock(struct mutex *lock);`
  - `void mutex_unlock(struct mutex *lock);`
  - `int mutex_is_locked(struct mutex *lock);`
  - `void mutex_lock_nested(struct mutex *lock, unsigned int subclass);`
  - `int mutex_lock_interruptible_nested(struct mutex *lock, unsigned int subclass);`
  - `int atomic_dec_and_mutex_lock(atomic_t *cnt, struct mutex *lock);`
  - Why mutex? [http://www.kernel.org/doc/Documentation/mutex-](http://www.kernel.org/doc/Documentation/mutex-design.txt)

# Spinlocks

- Spinlock is a busy waiting lock
  - Used to protect quick accesses to resources
- Spinlock API
  - `spinlock_t my_lock = SPIN_LOCK_UNLOCKED;`
  - `void spin_lock_init(spinlock_t *lock);`
  - `void spin_lock(spinlock_t *lock);`
  - `void spin_unlock(spinlock_t *lock);`
- When a spinlock is acquired, the critical section shouldn't lose CPU, meaning the critical section should be atomic
  - Functions such as `copy_to_user` shouldn't be called.

# Spinlocks (cont.)

- More spinlock functions
  - `void spin_lock(spinlock_t *lock);`
  - `void spin_lock_irqsave(spinlock_t *lock, unsigned long flags);`
  - `void spin_lock_irq(spinlock_t *lock);`
  - `void spin_lock_bh(spinlock_t *lock)`
  - `void spin_unlock(spinlock_t *lock);`
  - `void spin_unlock_irqrestore(spinlock_t *lock, unsigned long flags);`
  - `void spin_unlock_irq(spinlock_t *lock);`
  - `void spin_unlock_bh(spinlock_t *lock);`
- Reader/Writer spinlocks

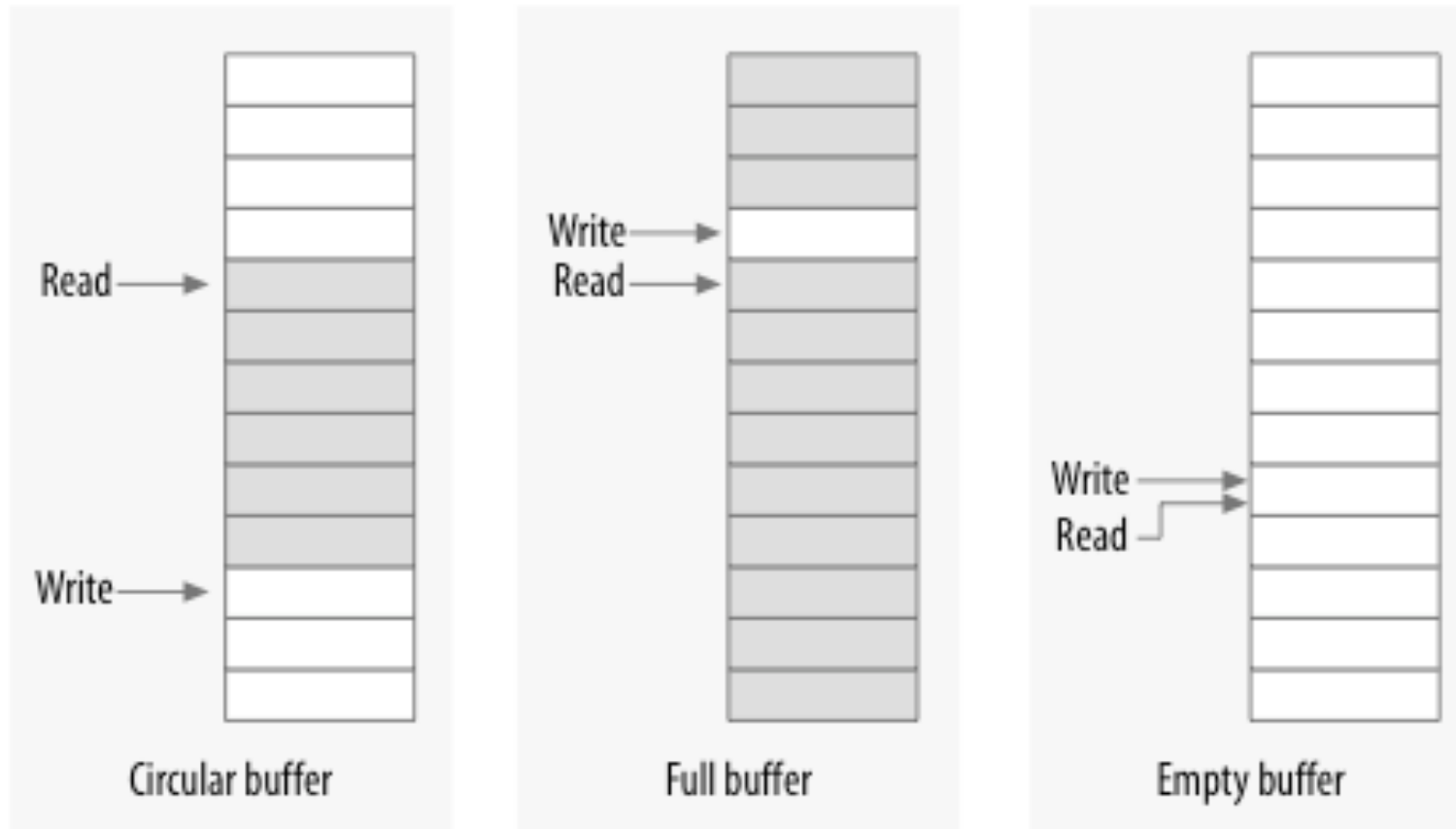


# Tips for locking

- Locking order
  - Always the same order for acquiring multiple locks
- Locking granularity
  - As fine as possible so that parallelism is maximized, but there is a tradeoff between locking overhead and parallelism.
- Don't protect unnecessary code sections
- ...

# Lock-free data structure

- Circular buffer



# Other lock-free algorithms

- Using CAS (compare-and-swap)
  - For integers  $n$  and  $n'$  and a memory location  $a$
  - CAS(  $n, a, n'$  )
    - If the value at address  $a$  is  $n$ , write the value of  $n'$  to address  $a$ ; return true
    - Otherwise, return false
- Lock-free algorithm for shared stack

# Shared stack

- Example
  - Push an item onto a lock-free stack (using linked list)
- Pseudo-code
  - Push(new){
  - do {
  - T' = Top;
  - new->next = T';
  - ret = CAS(T', &Top, new);
  - } while(!ret);
  - }

# Atomic variables

- Use type *atomic\_t*
- Functions and macros
  - void atomic\_set(atomic\_t \*v, int i);
  - atomic\_t v = ATOMIC\_INIT(i);
  - int atomic\_read(atomic\_t \*v);
  - void atomic\_add(int i, atomic\_t \*v);
  - void atomic\_sub(int i, atomic\_t \*v);
  - void atomic\_inc(atomic\_t \*v);
  - void atomic\_dec(atomic\_t \*v);
  - int atomic\_inc\_and\_test(atomic\_t \*v);
  - int atomic\_dec\_and\_test(atomic\_t \*v);
  - int atomic\_sub\_and\_test(int i, atomic\_t \*v);

# Other solutions for data race

- Bit operations
  - Linux kernel provides atomic functions for bit-wise operations
- Seqlocks
  - For situations where the resource to be protected is small, simple, and frequently accessed, and where write access is rare but must be fast.
- Read-Copy-Update (RCU)
  - for situations where reads are common and writes are rare