# McErlang – a Model Checker for Erlang Programs

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#### **McErlang basics**

- McErlang is useful for checking concurrent software,
   not for checking sequential software
- The Erlang runtime system for processes&communication is replaced with a new runtime system written in Erlang (erlang:send, spawn, ... have been reimplemented)
- A concurrent program is checked under **all** possible schedulings
- McErlang is open source, available under a BSD license



# The McErlang model checker: Design Goals

- Reduce the gap between program and verifiable model (the program *is* the model)
- Write correctness properties in Erlang
- Implement verification methods that permit partial model checking when state spaces are too big (Holzmann's bitspace algorithms)
- Implement the model checker in a parametric fashion (easy to plug-in new algorithms, new abstractions, ...)



### McErlang In Practise: A Really Small Example

Two processes are spawned, the first starts an "echo" server that echoes received messages, and the second invokes the echo server:

```
-module(example).
-export([start/0]).
start() ->
  spawn(fun() -> register(echo, self()), echo() end),
  spawn(fun() ->
           echo! {msg, self(), 'hello world'},
           receive
              {echo, Msg} -> Msq
           end
        end).
echo() ->
  receive
    {msg,Client,Msg} ->
      Client!{echo,Msg}, echo()
  end.
```



#### **Example under normal Erlang**

Let's run the example under the standard Erlang runtime system:

```
> erlc example.erl
> erl
Erlang R13B02 (erts-5.7.3) ...

1> example:start().
<0.34.0>
2>
```

That worked fine. Let's try it under McErlang instead.



# **Example under McErlang**

First have to recompile the module using the McErlang compiler:

> mcerl\_compiler -sources example.erl



### **Example under McErlang**

First have to recompile the module using the McErlang compiler:

```
> mcerl_compiler -sources example.erl
Then we run it:
```

```
> erl
Erlang R13B02 (erts-5.7.3) ...

1> example:start().
** exception error: undefined function mcerlang:spawn/1
    in function example:start/0
```

Hmm... we better include the McErlang libraries and start McErlang



#### **Example under McErlang**

Lets run it with McErlang libraries and from within McErlang:

```
> mcerl
Erlang R13B02 (erts-5.7.3) ...
1> mce:apply(example,start,[]).
Starting McErlang model checker environment version 1.0
*** User code generated error
exception error due to reason badarg
Stack trace:
 mcerlang:resolvePid/2
 mcerlang:mce_send/2
  -example:start/0-anonymous-1-/0
```



#### **Investigating the Error**

An error! Let's find out more using the McErlang debugger: 2> mce\_erl\_debugger:start(mce:result()). Starting debugger with a stack trace; execution terminate user program raised an uncaught exception. stack(@2)> showExecution(). 0: process <node,1>: run function example:start([]) spawn({#Fun<example.1.118053186>,[]},[]) --> <node,2> spawn({#Fun<example.2.76847815>,[]},[]) --> <node,3> process <node,1> was terminated process <node,1> died due to reason normal 1: process <node,3>: run #Fun<example.2.76847815>([]) process <node, 3> died due to reason badarg



#### **Error Cause**

■ Apparently in one program run the second process spawned (the one calling the echo server) was run before the echo server itself:

```
run #Fun<example.2.76847815>([])
```

■ Then upon trying to send a message

```
echo! {msg,self(),'hello world'}
```

the echo name was obviously not registered, so the program crashed



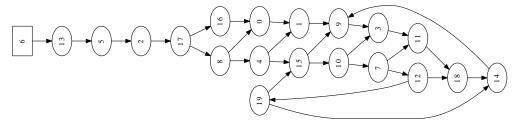
#### **Presentation Outline**

- What is model checking & a brief comparison with testing
- McErlang basics
- McErlang in practise: installing and usage
- Working with a larger example: a lift control system



# What is Model Checking

■ Run the program in a controlled manner so that all program states are visited (visualised as a finite state transition graph):



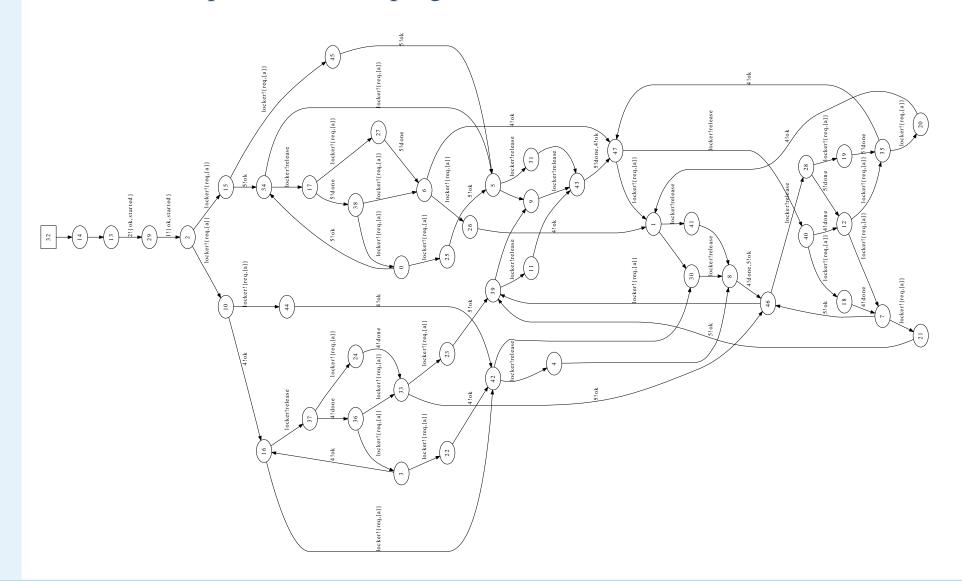
- A node represents a **program state** which records the state of all Erlang processes, all nodes, messages in transit...
- **Graph edges** represent computation steps from one program state to another
- Correctness Properties are automata that run in lock-step with the program; they inspect each program state to determine whether the state is ok or not



release /req

# **Comparison with Random Testing**

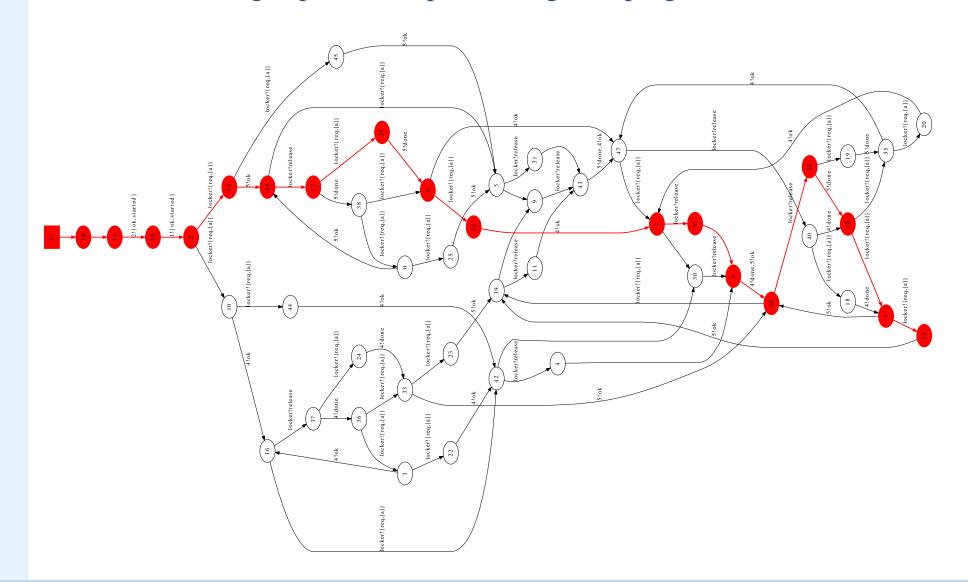
The State Space of a small program:





# Testing, run 1:

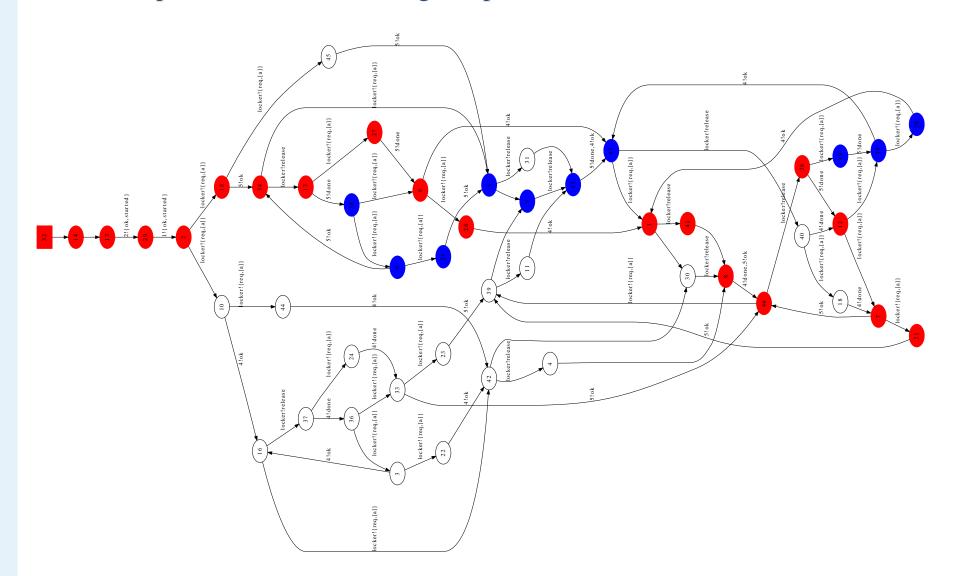
# Random testing explores one path through the program:





# Testing, run 2:

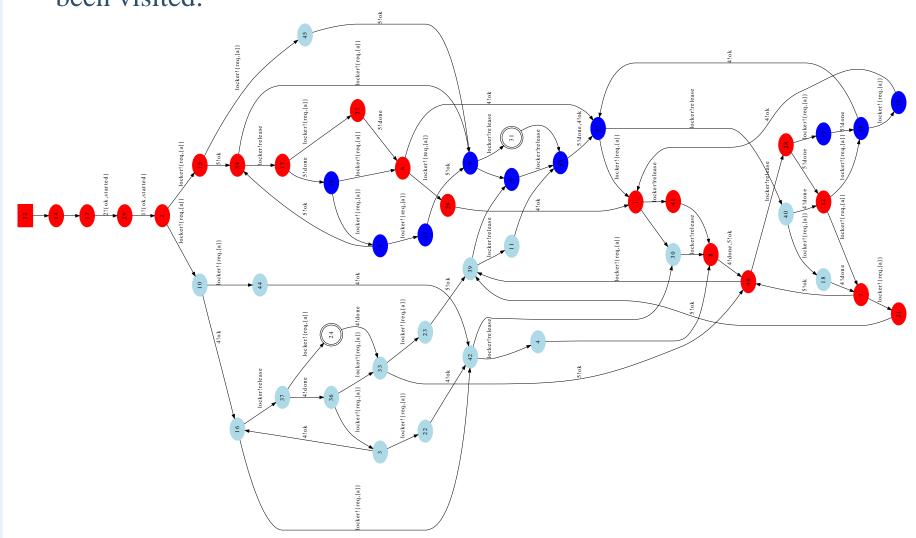
# With repeated tests the coverage improves:





# Testing, run n:

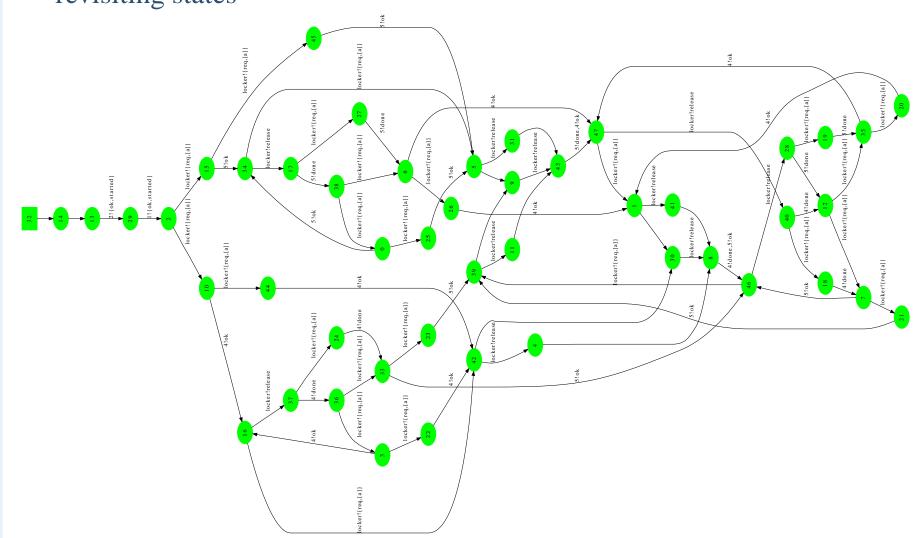
But even after a lot of testing some program states may not have been visited:





# Model checking: 100% coverage

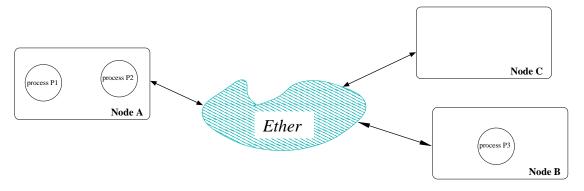
Model checking can guarantee that all states are visited, without revisiting states





## What is the trick? How can we achieve 100% coverage

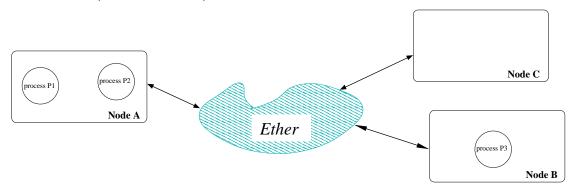
- Needed: the capability to take a **snapshot** of the Erlang system
  - ◆ A **program state** is: the contents of all process mailboxes, the state of all running processes, messages in transit (the ether), all nodes, monitors, ...





### What is the trick? How can we achieve 100% coverage

- Needed: the capability to take a **snapshot** of the Erlang system
  - ◆ A **program state** is: the contents of all process mailboxes, the state of all running processes, messages in transit (the ether), all nodes, monitors, ...



- Save the snapshot to memory and forget about it for a while
- Later continue the execution from the snapshot



# **Fundamental Difficulties of Model Checking**

- Too many states (not enough memory to save all snapshots)
- Checking all states takes too much time
- We have to a snapshot of things outside of Erlang (hard drives due to disk writes and reads,...)



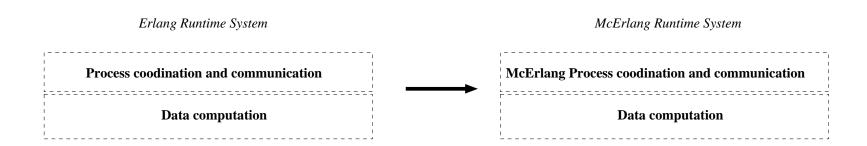
## The McErlang approach to model checking

- The lazy solution: just execute the Erlang program to verify in the normal Erlang interpreter
- And extract the system state (processes, queues, function contexts) from the Erlang runtime system



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- The lazy solution: just execute the Erlang program to verify in the normal Erlang interpreter
- And extract the system state (processes, queues, function contexts) from the Erlang runtime system
- Too messy! We have developed a **new runtime system** for the process part, and still use the old runtime system to execute code with no side effects





# Adapting code for the new runtime environment

Erlang code must be "compiled" by the McErlang "compiler" to run under the new runtime system:

■ API changes: call mcerlang:spawn instead of erlang:spawn



# Adapting code for the new runtime environment

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- API changes: call mcerlang:spawn instead of erlang:spawn
- Instead of executing (which would block)

```
receive
  {request, ClientId} -> ...
end
```

an adapted function returns a special Erlang value describing the receive request:

```
{'_recv_', {Fun, VarList}}
```

McErlang translator works on HiPE Core Erlang code



# **Full Erlang Supported?**

- Virtually the full core language supported:
  - Processes, nodes, links, all data types
  - ◆ Higher-order functions

Many libraries at least partly supported:

- supervisor, gen\_server, gen\_fsm, ets
- ◆ Not supported: gen\_tcp, ...



# **Full Erlang supported?**

No real-time model checking implementation yet

```
receive
  after 20 -> ...
end

behaves the same as

receive
  after 20000 -> ...
end
```



## **Extensions to Erlang in McErlang**

■ Non-determinacy:

```
mce_erl:choice
  ([fun () -> Pid!hi end,
     fun () -> Pid!hola end]).
```

sends either hi or hola to Pid but not both



### **Extensions to Erlang in McErlang**

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```

sends either hi or hola to Pid but not both

#### ■ Convenience:

```
mcerlang:spawn
  (new_node,
  fun () -> Pid!hello_world end)
```

The node new\_node is created if it does not exist



# Compiling/preparing code for running under McErlang

- *All* source code modules of a project must be provided to the McErlang compiler
- *Some* OTP behaviours/libraries are automatically included at compile time
- Example: mcerl\_compile -sources \*.erl
- The translation is controlled by the funinfo.txt file (can be customised)
- The result of the translation is a set of beam files (and Core Erlang code for the translated modules)



#### **Controlling Translation**

■ The file funinfo.txt controls the remapping of functions and describes side effects:

■ A verification project can use its own funinfo.txt



#### **Choice of Libraries**

- McErlang has tailored versions of some libraries: supervisor, gen\_server, gen\_fsm, gen\_event, lists, ets,...which are automatically included
- It may be possible to use the standard OTP libraries instead



#### Running programs under McErlang

■ Starting McErlang:

■ Example: starting the Echo program

■ The result of a model checking run can be retrieved using mce:result()

(a program trace leading to the bug)



### **McErlang runtime options**

More #mce\_opts{} record options:

- sim\_external\_world = true() | false()
  McErlang does I/O with external world? (false)
- shortest = true() | false()
  Compute the shortest path to failure? (false)
- fail\_on\_exit = true() | false()
  Stop a model checking run if a process terminates abnormally
  due to an uncaught exception (true)
- time\_limit = seconds
  Halts verification after reaching a time limit
- And many more ...



### **Algorithms**

An algorithm determines the particular state space exploration strategy used by McErlang:

- mce\_alg\_simulation
  Implements a basic simulation algorithm –
  following a single execution path
- mce\_alg\_safetyChecks the specified monitor on *all* program states
- mce\_alg\_combine
  Combines simulation and model checking to reduce state
  space



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Ok, we can run programs under the McErlang runtime system. Next we need a language for expressing correctness properties:



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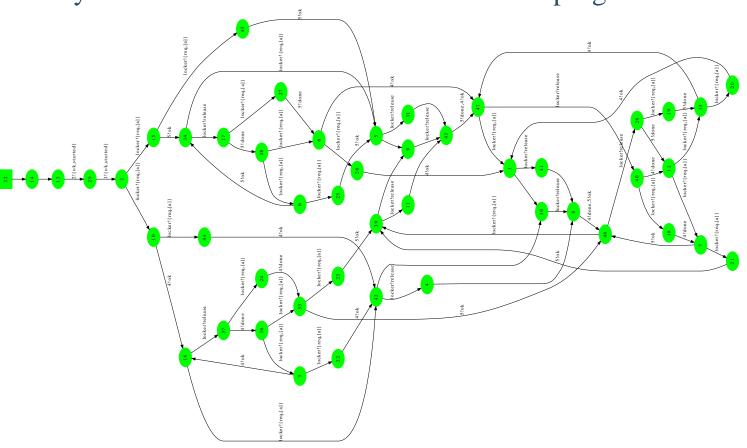
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A safety monitor is an user function with three arguments: stateChange(State, MonitorState, Action) -> ... {ok, NewMonitorState}.
```

- A program is checked by running it in lock-step with a monitor
- The monitor can inspect the current state, and the side effects (actions) in the last computation step
- The monitor either returns a new monitor state {ok, NewMonitorState}, or signals an error



# **Safety Monitors**

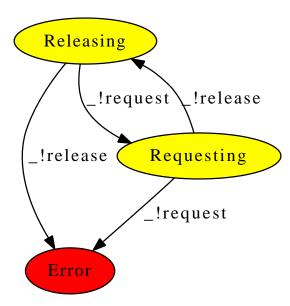
- Safety Monitors check that *nothing bad ever happens*
- They must be checked in *all* the states of the program:





# A monitor example

- We want to implement a monitor to check that a program alternates between sending request and release
- As an automaton:





# A monitor example implemented in Erlang

```
-module(req_rel_alternate).
-export([init/1,stateChange/3,monitorType/0]).
-behaviour(mce_behav_monitor).
monitorType() -> safety.
init(_) -> {ok,request}.
stateChange(ProgramState, request, Action) ->
  case get_action(Action) of
    {ok,request} -> {ok,release};
    {ok,release} -> not_alternating
    _ -> {ok,request}
  end; ...
get action(Action) ->
  case mce_erl_actions:is_send(Action) of
    true -> {ok,mce_erl_actions:get_send_msg(Action)};
    false -> no_action
  end.
```



### What can monitors observe?

- Program actions such as sending or receiving a message
- Program **state** such as the contents of process mailboxes, names of registered processes
- The values of some program variables (can be tricky)
- Programs can be instrumented with special *probe actions* that are easy to detect in monitors

  (e.g. calling mce\_erl:probe(requesting))
- Programs can be instrumented with special probe states,
   which are persistent (actions are transient)
   (e.g. calling mce\_erl:probe\_state(have\_requested))



# **Some Predefined Monitors**

- mce\_mon\_deadlockChecks that there is at least one non-deadlocked process
- mce\_mon\_queue
  Checks that all queues contain at most MaxQueueSize elements.



# **Checking Liveness Properties**

- For expressing that *something good eventually happens*
- Linear Temporal Logic (always, eventually, until, next, ...) is used to express liveness properties
- State predicates are Erlang functions
- Example:

```
always(fun liftprop:go_to_floor/3 =>
    eventually fun liftprop:stopped_at_floor/3)
```

■ State predicate:

```
go_to_floor(_ProgramState,Action,_PrivateData) ->
  case interpret_action(Action) of
    {f_button,Floor} -> {true,Floor};
    {e_button,_,Floor} -> {true,Floor};
    _ -> false
  end.
```



# The McErlang Debugger

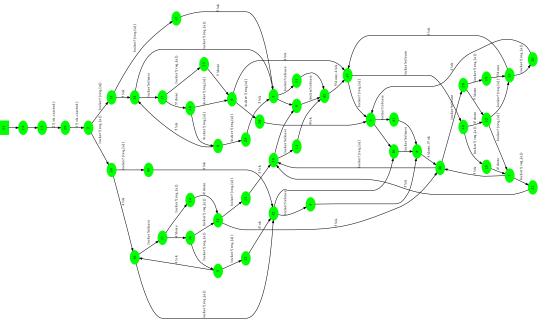
- There is a rudimentary debugger for examining counter examples
- After a failed model checking run, start the debugger on the counterexample using:

```
mce_erl_debugger:start(mce:result()).
```



# Things that can go wrong

■ McErlang runs out of memory – too many states



- McErlang takes too long
- Why? Program uses timers, counters, random values, ... or is simply too complex



# What can be done

Partial verification – explore part of the state space



### What can be done

Partial verification – explore part of the state space

■ Use a (lossy) bounded size state table:

```
#mce_opts
{...,table={mce_table_bitHash,Size}, ...}
```

■ Use a bounded stack

```
#mce_opts
{...,stack={mce_stack_bounded,Size}, ...}
```

- Put a bound on the verification time
- Check smaller examples (a set of test cases)



- Write state machine specifications in QuickCheck
- Check them using eqc\_statem:commands or eqc\_statem:parallel\_commands



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- Use normal Erlang scheduler to check programs under the *normal* Erlang scheduler
- Use Pulse to check program under a more random scheduler
- Use McErlang to check program under all schedulings
- McErlang interface will likely be distributed with the next QuickCheck release



# McErlang in Practise: downloading

- https://babel.ls.fi.upm.es/trac/McErlang/
- Use subversion to check out the McErlang sources:

```
svn checkout \
https://babel.ls.fi.upm.es/svn/McErlang/trunk \
McErlang
```

■ Get bug fixes and improvements using subversion:

```
svn update
```



# **Installing**

- We use Ubuntu McErlang doesn't work well under Windows
- Compile McErlang:

```
cd McErlang; make
```

■ Put scripts directory on the command path (in Bash):

```
export PATH=~/McErlang/scripts:$PATH
```

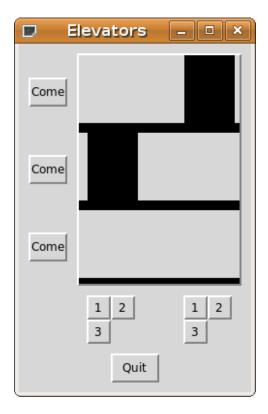
■ Read the manuals:

```
acroread doc/tutorial/tutorial.pdf acroread doc/userManual/userManual.pdf
```



# McErlang in practise: The Elevator Example

■ We study the control software for a set of elevators



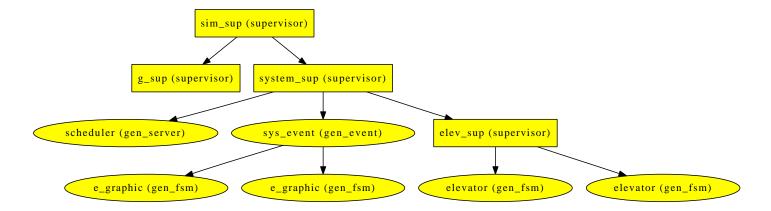
■ Used to be part of an Erlang/OTP training course from Ericsson



# The Elevator Example

### Example complexity:

- Static complexity: around 1670 lines of code
- Dynamic complexity: around 10 processes (for two elevators)
- Uses quite a few libraries: lists, gen\_event, gen\_fsm, supervisor, timer, gs, application





# Running the elevator under McErlang

- First we just try to run it under the McErlang runtime system (forgetting about model checking for a while)
- This will test the system under a less deterministic scheduler than the normal Erlang scheduler



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### ■ Executing:

```
mce:start
  (#mce_opts
    {program={sim_sup,start_link,[1,3,2]},
        sim_external_world=true,
        algorithm={mce_alg_simulation,void}}).
```



# Running the elevator under McErlang

- First we just try to run it under the McErlang runtime system (forgetting about model checking for a while)
- This will test the system under a less deterministic scheduler than the normal Erlang scheduler
- Executing:

```
mce:start
  (#mce_opts
    {program={sim_sup,start_link,[1,3,2]},
        sim_external_world=true,
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```

■ Seems to work...





Model checking is a bit more complicated:

■ The gs graphics will not make sense when model checking ⇒
We shut it off in model checking mode



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- The example is very geared to smooth graphical display ⇒ We modify the program to only have three (3) intermediate points between elevator floors (normally 20)
- The program contain timers (for moving the elevator) ⇒

  We assume that the program is *infinitely fast* compared to the timers: timer only release when no program action is possible



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- The program contain timers (for moving the elevator) ⇒
   We assume that the program is *infinitely fast* compared to the timers: timer only release when no program action is possible
- In total, about 15 lines of code had to be changed to enable model checking **not too bad!**



### **Scenarios**

- Instead of specifying one big scenario with a really big state space, we specify a number of smaller scenarios
- Paremeters:

```
Number of elevators,
Number of floors,
Commands:
```

```
[{scheduler,f_button_pressed,[1]},
  {scheduler,e_button_pressed,[2,1]},
  {scheduler,f_button_pressed,[1]}]
```

QuickCheck can be used to generate a set of scenarios





■ *No runtime exceptions* 



- *No runtime exceptions*
- Checking:



- *No runtime exceptions*
- Checking:

### ■ Result:

```
*** User code generated error:
exception error due to reason {badmatch,[]}
Stack trace:
scheduler:add_to_a_stoplist near line 344/3
scheduler:handle_cast/2
...
```



- *No runtime exceptions*
- Checking:

■ Result:

```
*** User code generated error:
exception error due to reason {badmatch,[]}
Stack trace:
scheduler:add_to_a_stoplist near line 344/3
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...
```

■ **Bug** - the system received the "press button"-command before it had been initialised



# "Hiding the bug"

■ Instead of fixing the bug we hide it by only sending commands when the system has started by enabling the option is\_infinitely\_fast=true

### ■ Checking:





■ An elevator only stops at a floor after receiving an order to go to that floor

(implemented as a monitor that keeps a set of floor requests, and checks that visited floors are in the set)



# **A Monitor Implementing the Floor Request Property**

```
-module(stop_after_order).
-behaviour(mce_behav_monitor).
%% The monitor state is a set of floor requests
init(_) -> ordsets:new().
%% Called when the program changes state
stateChange(_,FloorReqs,Action) ->
  case interpret_action(Action) of
    {f_button,Floor} ->
      ordsets:add_element(Floor,FloorRegs);
    {e_button, Elevator, Floor} ->
      ordsets:add_element(Floor,FloorReqs);
    {stopped_at, Elevator, Floor} ->
      case ordsets:is_element(Floor,FloorReqs) of
        true -> FloorRegs;
        false -> throw({bad_stop,Elevator,Floor})
      end;
    -> FloorRegs
```

ProTest property based testing

# Checking the first correctness property

# ■ Checking:

- Fails...
- We display the counterexample (a program trace) using a custom pretty printer:

```
Floor button 3 pressed
Elevator 1 is moving up
Elevator 1 is approaching floor 2
Elevator 1 is stopping
Elevator 1 stopped at floor 2
```



# **More Correctness Properties**

■ Refining the floor correctness property:

An elevator only stops at a floor after receiving an order to go to that floor, if no other elevator has met the request

(implemented as a monitor that keeps a set of floor requests; visited floors are removed from the set)



# **More Correctness Properties**

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An elevator only stops at a floor after receiving an order to go to that floor, if no other elevator has met the request (implemented as a monitor that keeps a set of floor requests; visited floors are removed from the set)

■ A Liveness property:

If there is a request to go to some floor, eventually some elevator will stop there



# **McErlang Status and Conclusions**

- Supports a large language subset (full support for distribution and fault-tolerance and many higher-level components)
- Everything written in Erlang(programs, correctness properties, ...)
- An alternative implementation of Erlang for testing (using a much less deterministic scheduler)
- Using McErlang and testing tools like QuickCheck can be complementary activities:
  - ◆ Use QuickCheck to generate a set of test scenarios
  - ◆ Run scenarios in McErlang
- "IDE integration" coming soon (for Emacs and Eclipse)

